

# L20, SBC Controller Metal Welding System

# Product Manual

Branson Ultrasonics Corp. 120 Park Ridge Road Brookfield, CT 06804 (203) 796-0400 http://www.bransonultrasonics.com



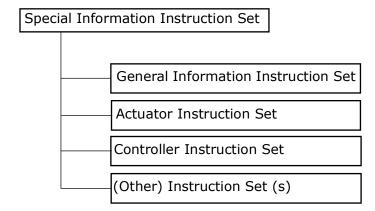


#### **Introduction**

This is the product manual for your BRANSON Metal Welding ultrasonic welding system.

Several combined Instruction Sets form the contents of this manual. This section contains information which relates most uniquely to you as the customer, your particular system and application. It also documents other Instruction Sets used in the manual. The figure below illustrates how the manual is organized.

Branson Metal Welding Product Manual



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### **Using this manual**

It is highly recommended that you read and understand the contents of this manual prior to operating your Branson Metal Welding system. Each Instruction Set has a table of contents and is intended to logically group information in a manner which the user will find convenient.

#### **Classification of Hazards**

The safety indications in this manual are divided into different classes. The figure below shows the assignment of symbols (pictograms) and signal words to the specific hazards and its potential consequence.

DANGER	
<u>^</u>	A potentially dangerous situation that could cause injury to persons and serious damage to equipment.

CAUTION	
<u> </u>	A situation that may cause damage to the equipment.

NOTICE	
6	Useful information, an application hint or other important or useful information.

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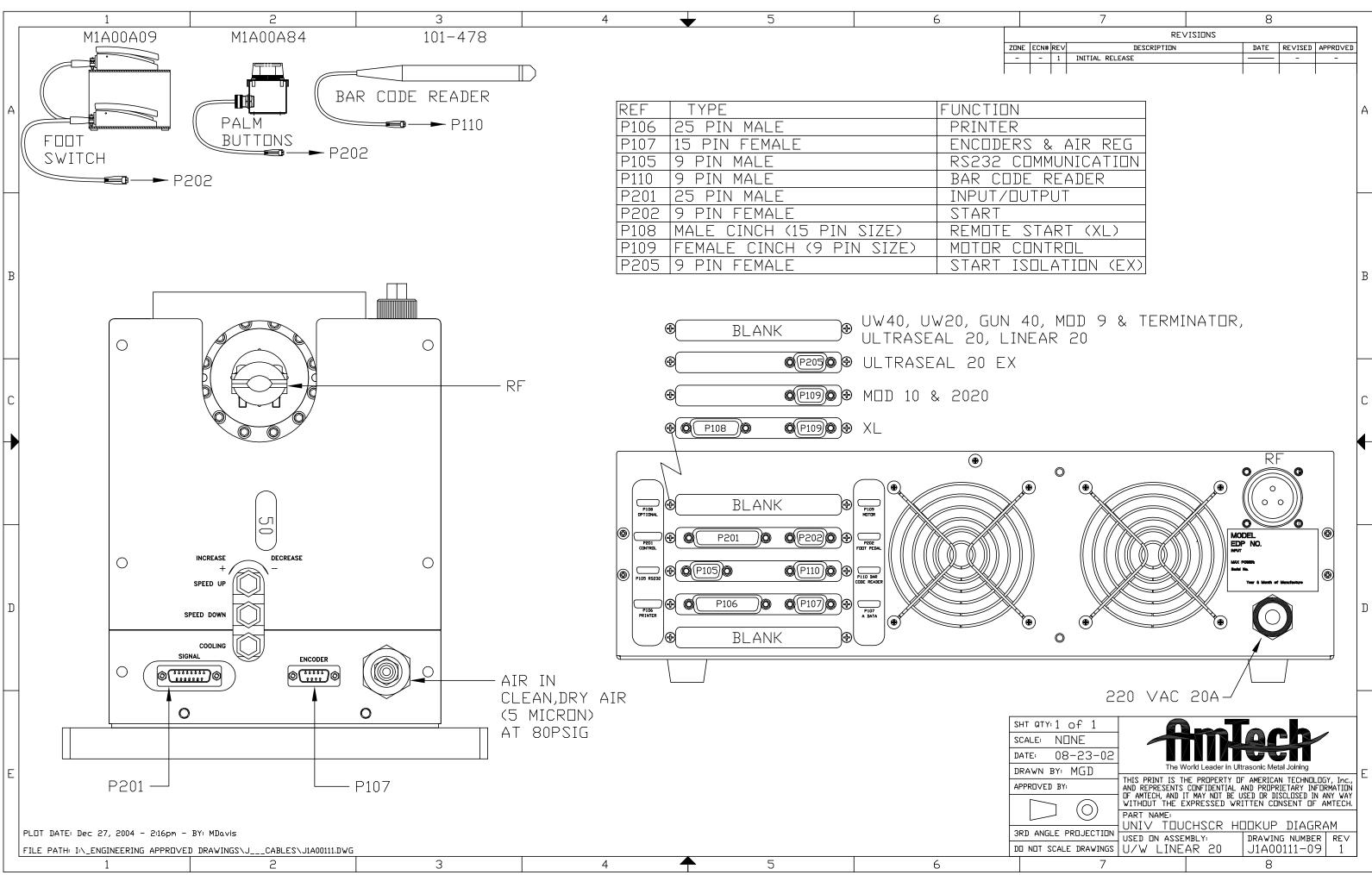


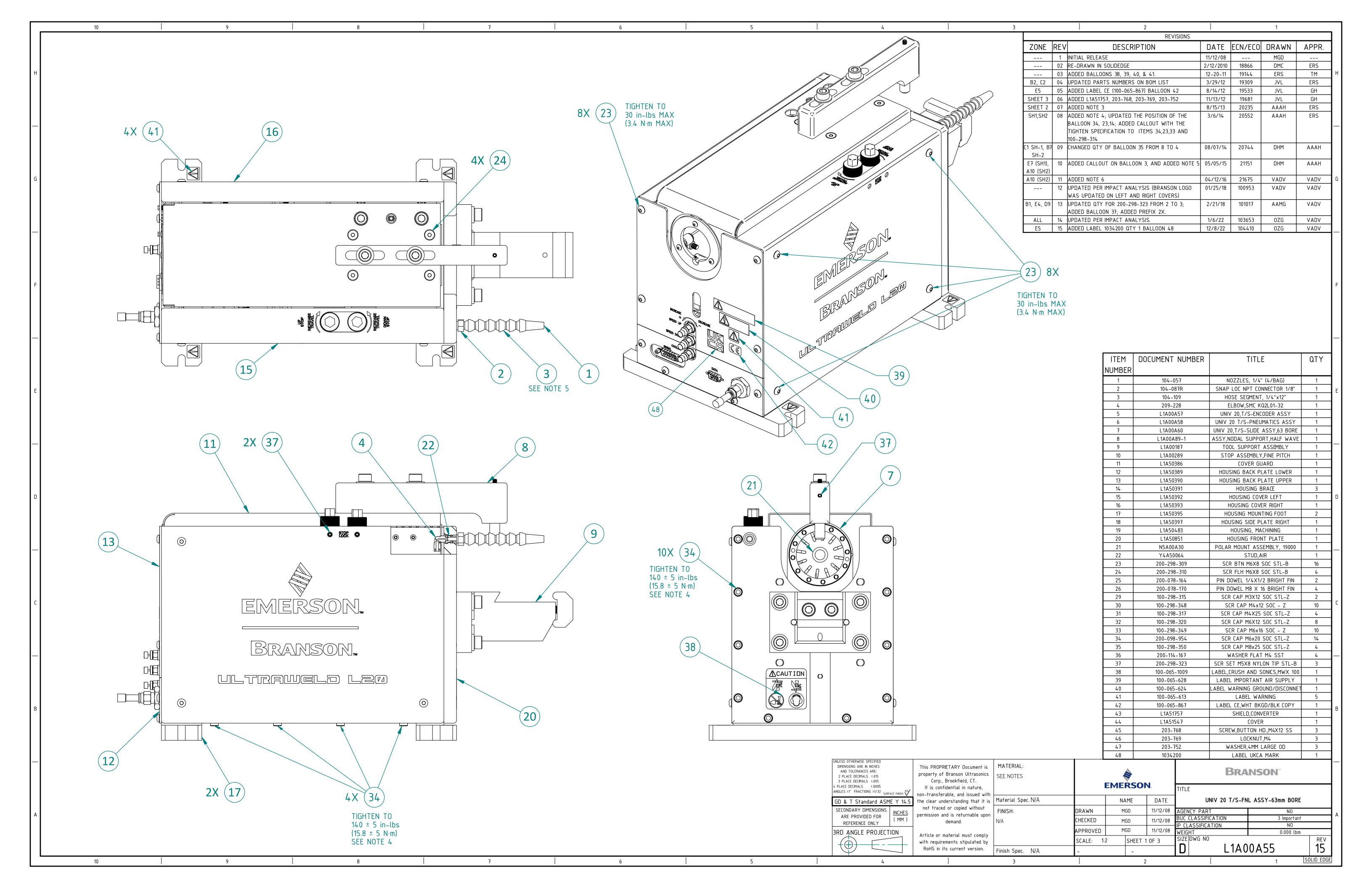
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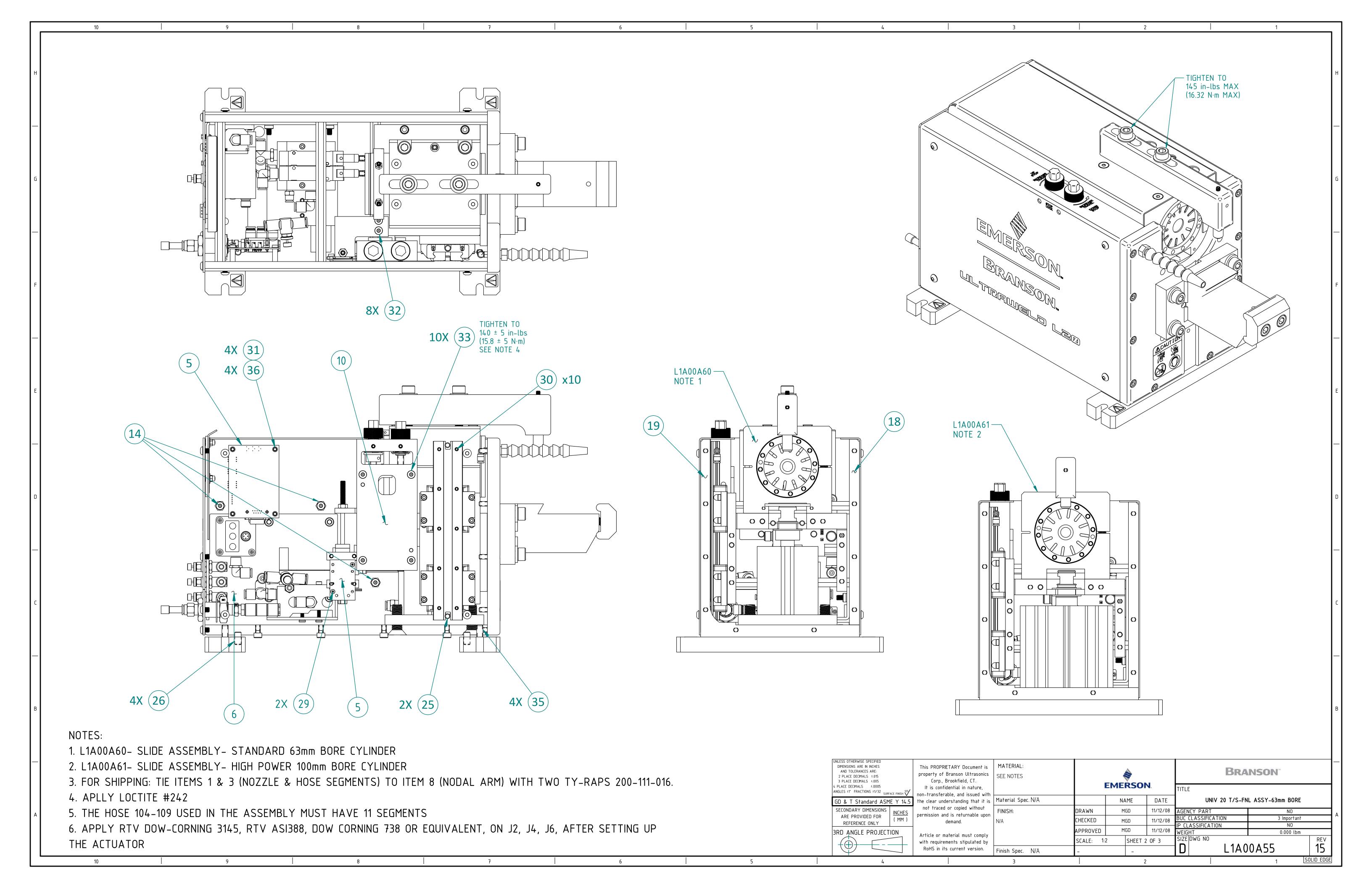
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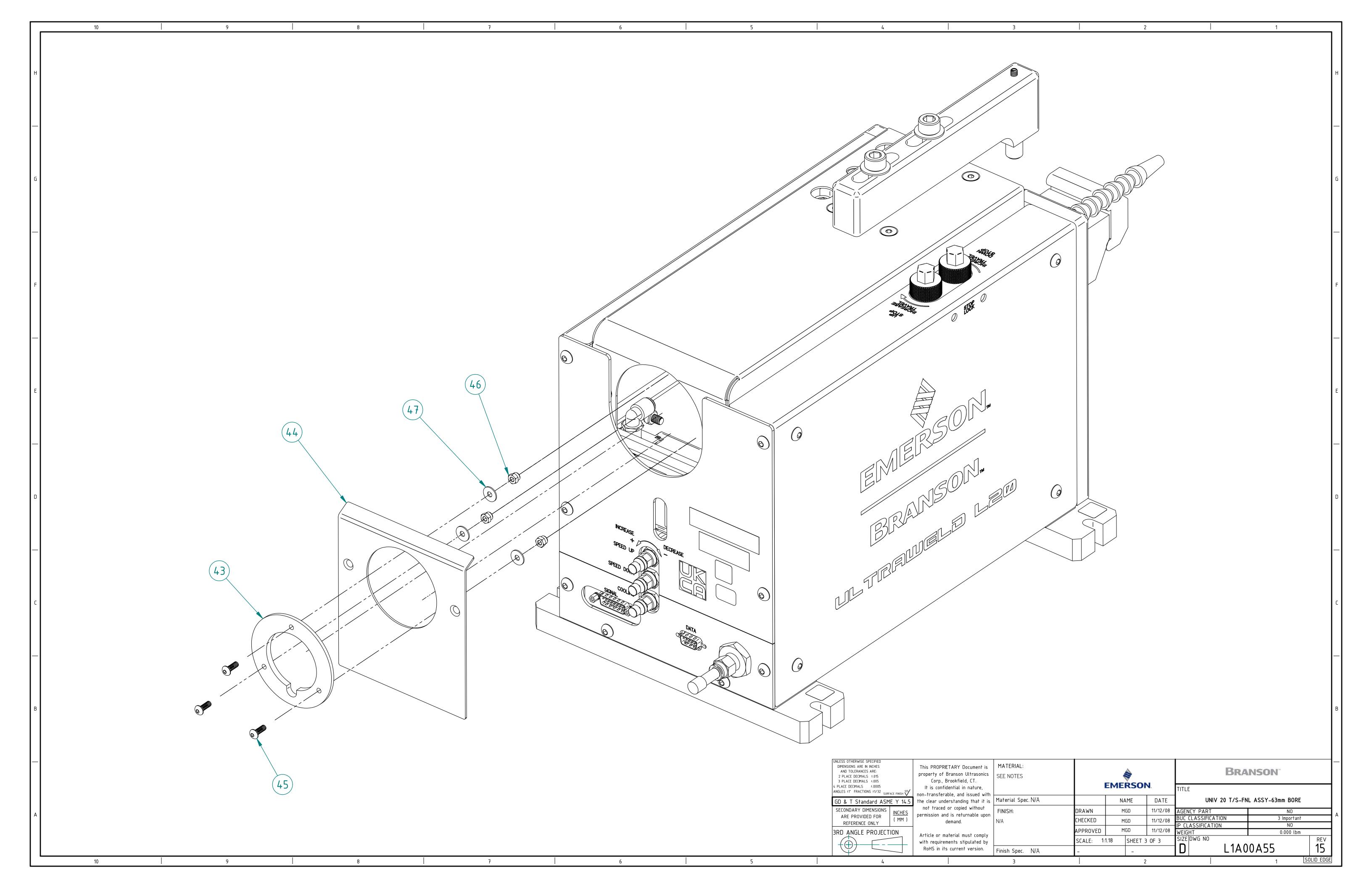
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Assembly Drawing	L1A00A56 (Heavy Duty)

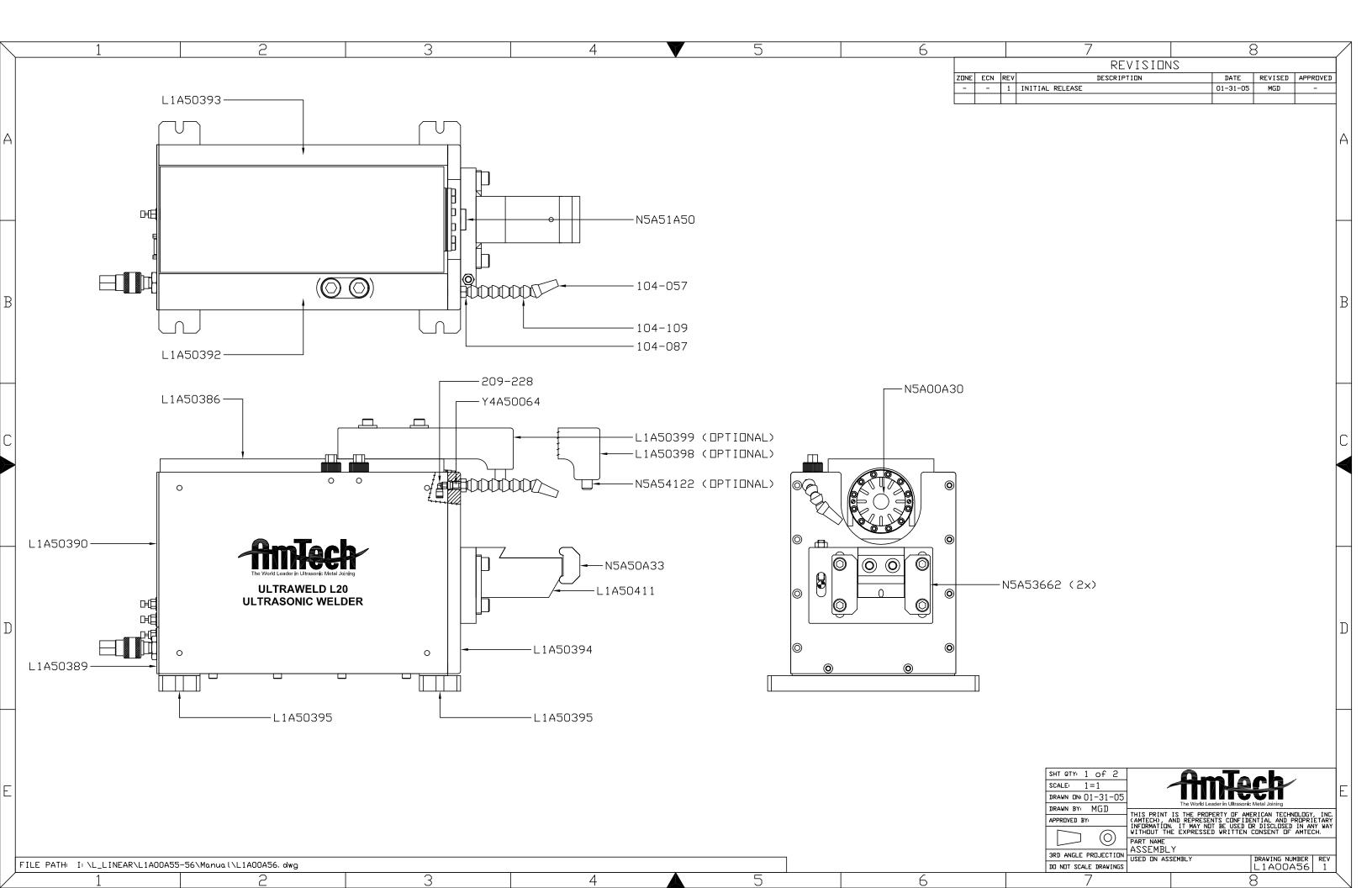
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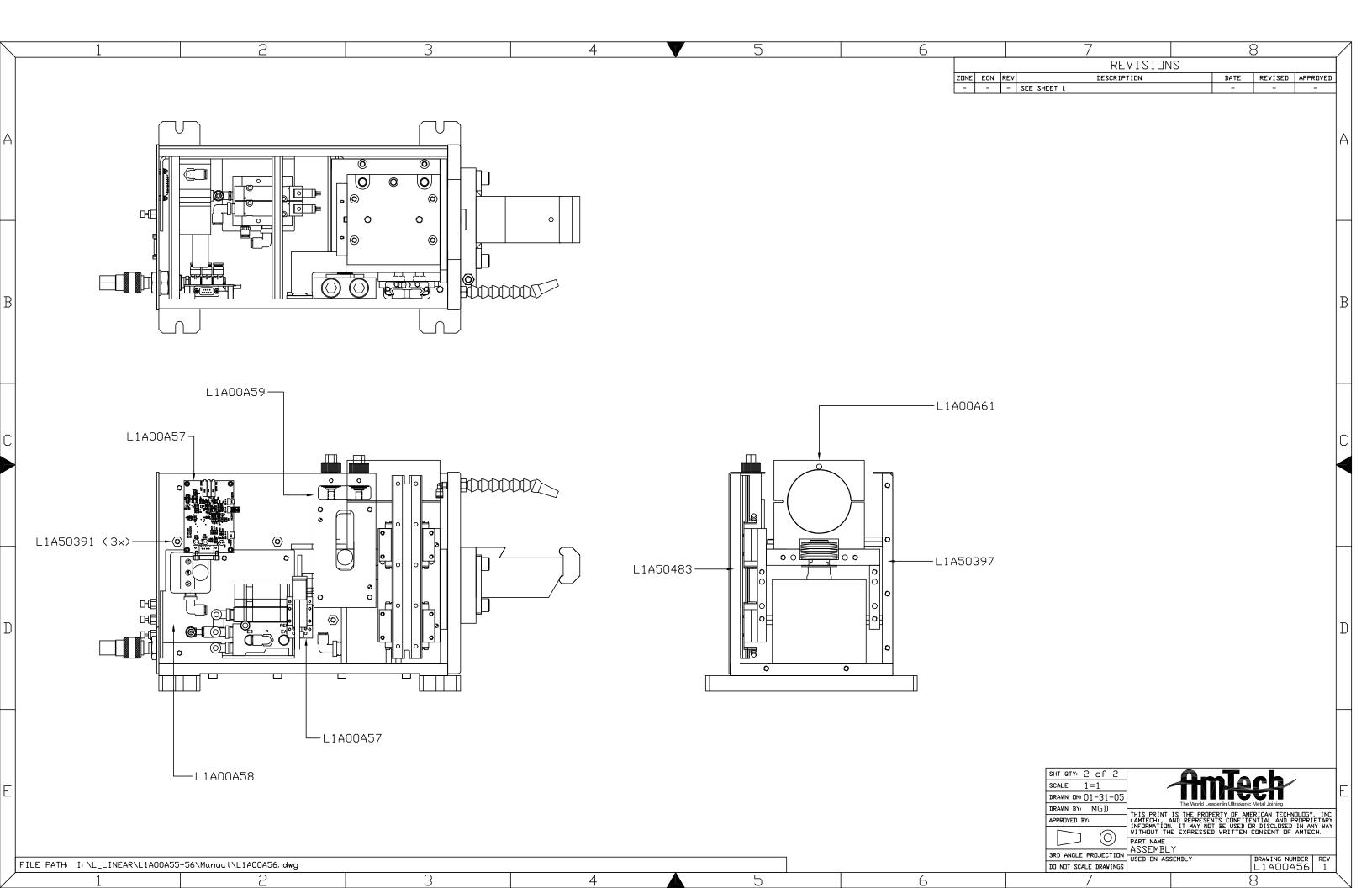














# MWX100 / Ultrasplice Systems

# Instruction Manual

Branson Ultrasonics Corp. 120 Park Ridge Road Brookfield, CT 06804 (203) 796-0400 http://www.bransonultrasonics.com



#### Introduction

This Instruction Set includes common information which relates to Branson products. It will help you in setting up your system and to understand the fundamentals of the ultrasonic metal welding process.

#### **Thank You**

Thank you, and congratulations on selecting Branson MWX100/ ULTRASPLICE Systems for your welding production. This system has been developed to produce the highest quality welds at the lowest cost per weld.

If you should experience difficulty or have any recommendations for improvement, please do not hesitate to contact us.

Please be advised that the MWX100/ ULTRASPLICE machine is protected under the United States and International patents listed below. This operator's manual is also protected by copyright and may not be copied without prior written permission by Branson.

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#### **Trademarks**

MWX100 and ULTRASPLICE are registered trademarks of Branson Ultrasonics Corp.

## Copyright

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# **Chapter 1: Safety and Support**

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#### 1.1 Intended Use

This equipment is for the joining of metal parts using ultrasonic energy. A complete system includes an actuator, controller and tooling (which delivers mechanical energy to the work pieces). Some systems also include special fixturing and machine automation. Branson systems may only be utilized to weld soft, ductile, metal parts together with Branson-supplied weld tooling (such as horns, tips, anvils, and converters) unless an explicit, written, contrary agreement between the ordering party and Branson has been consummated.

## 1.2 Safety, Personal

#### 1.2.1 Safety Devices

The removal, bridging or disabling of safety devices is not condoned for production operation. Individual safety devices mentioned below may only be disabled if super-ordinate safety devices are employed in their place.

#### 1.2.2 Emergency Stops

In case of danger, hit the red, emergency stop which is found on the red, top portion of the foot pedal. The actuator, power supply and related fixturing are returned to the "Home" position. If dual anti-tie start buttons are used, there must be a red emergency stop associated in line. Free access to the emergency stop button must be maintained.

#### 1.2.3 Controller Cover

The power supply is equipped with a top cover which should only be removed for maintenance and installation purposes.

#### 1.2.4 Safety Guidelines

For operating safety, please observe the following precautions:

- Plug the power supply into a grounded electrical supply to avoid electrical shock
- Ensure that no one is in contact with system moving parts when operating
- Keep hands away from the horn tip as high force and ultrasonic vibration can cause injury to hands and fingers
- Do not test ultrasonics when the converter is removed from the actuator. Without the converter there is the danger of damage or shock
- Before adjusting or repairing the ultrasonic stack or power supply, disconnect the line power
- Any unauthorized modification of the units control circuitry or wiring may cause a malfunction, which could result in injury to operating personnel
- Do not operate the equipment until repairs and adjustments have been made and the equipment is in good working order

## 1.3 Maintenance Safety

Safety devices, especially covers, guards and ground cables should only be removed when it is absolutely essential for the completion of maintenance work. If safety devices were removed prior to starting maintenance work, be sure to re-install those devices after finishing the maintenance work. The following installation and maintenance operations must be performed prior to any disassembly of equipment:

- All system components must be disconnected from the main electrical supply
- Remove the plug from the main electrical supply and secure it from being re-inserted accidentally
- All system components must be disconnected from the main air supply
- Disconnect the air hose from the main air supply and release system air pressure via the pressure regulator



## 1.4 Safety, System

#### 1.4.1 System Protection Monitoring (SPM)

The SPM (System Protection Monitoring) stops ultrasonics when the power supply has been overloaded or when inappropriate or defective horns are used.

#### 1.4.2 Thermal Switch

A thermal switch is contained within the power supply to automatically disconnect power to the machine if the unit gets too hot. This will occur if the exhaust fans from the generator are inadvertently blocked or clogged.

#### 1.4.3 Daily Functional Safety Checks

- Check the machine tip and anvil for any signs of grinding, cracking, or galling that could be the result of misalignment or tooling contact. Replace tooling that has excessive wear
- Check for any loose material or debris in the welding cavity, cleaning it out
- Check all parameter settings on the controller to ensure they are properly set for the weld to be made
- Drain water and contaminants from the airline filters as necessary

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## 1.5 Contacting Branson

#### 1.5.1 Spare Parts & Replacement Tooling

Spare parts or replacement tooling for the ultrasonic welding system may be ordered directly from Branson. A spare tooling specification sheet is included in the Special Information Instruction Set. Additional part listings are contained in the Actuator and Touchscreen Controller Instruction Set sections of this manual.

Branson will work with you and recommend components you need and should carry in inventory based upon your manufacturing philosophy and or production needs. We will quote price, delivery and can coordinate special arrangements such as expedited service or blanket orders.

When Ordering Spare or Replacement Parts, have the purchasing agent Fax the order to us with the following information provided:

- · Purchase Order Number,
- · Branson Part Number, Quantity, and Date Required,
- Ship To Information, (including "Ship to the Attention of")
- · Bill To Information
- Shipping Instructions, (such as air freight, truck, etc.)
- Special Instructions, (such as "Hold at Pick-Up Counter and Call" -- Be sure to provide a name and a phone number)

#### 1.5.2 Questions or Problems

If you have any questions or are experiencing a problem, call the local Branson field sales and/or service representative. He or she will be familiar with your equipment and application and, in most cases, will be able to help you. He or she may have the replacement part you need, in stock, that will return your system to operation in the shortest possible time.

If necessary, the representative will contact Branson for additional service and, in some cases, will put you into contact with the appropriate personnel. If the local representative is unavailable, please call us directly.

#### Before you call, take the following steps:

- · Have this manual with you
- Know how your system has been set up and equipped, including your MBOS version
- · Be able to describe the situation or problem
- Have a list of steps that you have already taken
- · Have a list of spare parts in your inventory
- Have the name and phone number of the Local Branson Representative

#### 1.5.3 Returning Equipment

In order to properly and efficiently handle an equipment return to Branson, the following procedure must be followed. Contact your Local Sales Manager or Branson Customer Service for assistance. Proper handling and identification of your equipment will expedite servicing and/or return.

Call Branson and Receive a Return Authorization Number (RA#) from Branson Customer Service.

- · Properly package the equipment to prevent damage
- Clearly mark the RA# on the outside of the package
- Include a copy of the completed Return Authorization Form inside the package
- · Return general repairs by any convenient method. Send priority repairs via Air Freight
- Prepay the transportation charges, (FOB Brookfield, CT)

Complete the following in the Return Authorization Form:

- Customer Information Section
- · Description of Problem
- · Equipment Information

#### 1.5.4 New Applications

Branson is always eager to work with you on a new ultrasonic application. Whether it be a manual workstation, a semi or fully automated system, Branson has the personnel and technical competence to support your requirements. Branson's application laboratory, product and automation engineering, customer service and manufacturing capabilities are second to none. Branson is the world leader in ultrasonic metal welding and our business philosophy is practiced to assure customer success.

Application assistance is always available. For initial application review, contact your Local Sales Manager who can indicate initial feasibility and assist you in completing an Ultrasonic Weld Evaluation Request For. Please complete one (1) request form for each application.

Please fill out the Ultrasonic Evaluation Request Form, complete the customer and application information section and forward it to Branson along with enough component material to produce 24 assemblies, (if this is not practical please advise). A feasibility evaluation will be performed and samples returned, for review, along with a system quotation/ proposal. Be sure to include drawings of the completed assembly and include the electrical, mechanical, and production requirements. Complete the form as completely as possible. The Branson Sales Representative can assist you.

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## 1.6 Warranty

For warranty information please reference the warranty section of Terms and Conditions found at: <a href="https://www.emerson.com/branson-terms-conditions">www.emerson.com/branson-terms-conditions</a>.

# **Chapter 2: Introduction**

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## 2.1 Ultrasonic Theory

#### What Is An Ultrasonic Weld?

Ultrasonic welding joins metal parts by applying the energy of high frequency vibrations onto the interface area between the parts to be welded.

#### **How Does It Work?**

Electrical Energy is transformed into high frequency mechanical vibration. This mechanical vibration is transferred to a welding tip through an acoustically tuned horn (Figure 2.1). The parts are "scrubbed" together under pressure at 20,000 or 40,000 cycles per second. This high frequency vibration, applied under force, disperses surface films and oxides, creating a clean, controlled, diffusion weld (Figure 2.2). As the atoms are combined between the parts to be welded, a true, metallurgical bond is produced.

Figure 2.1 Transforming Electrical Energy into high frequency mechanical vibration

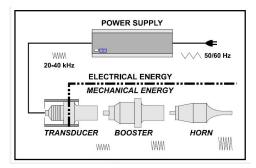
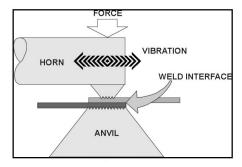


Figure 2.2 High frequency vibration Welding



#### **Benefits of Ultrasonic Welding**

Ultrasonic metal welding exhibits unique welding properties that include:

- Excellent electrical, mechanical, and thermal connections between similar and dissimilar metals
- Low heat build up during the ultrasonic process (no annealing of materials)
- Compensation for normal surface variations of the material
- Ability to clean surface oxides and contaminants prior to welding
- Ability to weld large areas using minimal energy
- Ability to weld thin materials to thick materials
- · Low cost per weld

#### **How Is An Ultrasonic Weld Made?**

Although the theoretical process of producing an ultrasonic weld is uncomplicated, the interactions of the various weld parameters are important and should be understood.



When producing an ultrasonic weld, there are three primary variables that interact; they are:

**Time:** The duration of applied ultrasonic vibration

Amplitude: The longitudinal displacement of the vibration

**Force:** The compressive force applied perpendicular (normal) to the direction of vibration.

Power required to initiate and maintain vibration (motion) during the weld cycle can be defined as:

 $P = F \times A$ 

#### Where:

- P = Power (watts)
- F = Force \* (psi)
- A = Amplitude (microns)

NOTICE	
<b>f</b>	Force is determined by multiplying:  Force = (Surface Area of the Cylinder) X (Air Pressure) X (Mechanical Advantage)

Energy is calculated as:

 $E = P \times T$ 

#### Where:

- E = Energy (joules)
- P = Power (watts)
- T = Time (seconds)

Thus the complete 'Weld To Energy' process would be defined as:

$$E = (F \times A) \times T$$

A well designed ultrasonic metal welding system will compensate for normal variations in the surface conditions of the metals by delivering the specified energy value. This is achieved by allowing Time (T) to adjust to suit the condition of the materials and deliver the desired energy.

#### Welding To Energy - Why?

Most metal welding applications are produced by 'Welding To Energy' in order to compensate for the various surface oxides and contaminants associated with the metals being joined. In a few applications 'Welding To Time' or 'Welding To Height' will yield better results. Since the majority of all metal welds are produced using energy as the controlling factor we will confine our discussion to that condition.

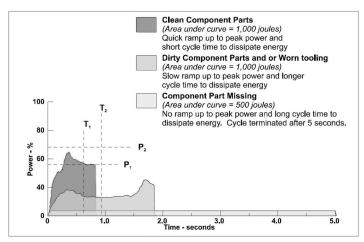
Welding to energy is necessary because of the non-metallic oxides that form on the metal's surface as well as other contaminates such as grease and dirt. To producing quality welds reliably it is necessary that the surfaces to be joined are clean. The high frequency scrubbing action, combined with pressure, cleans the weld interface at the beginning of the weld process.

The following graph (Figure 2.3) illustrates a weld produced. The weld 'power graph' is sometimes referred to a weld 'footprint'. It can be used to visualize the weld cycle and assists in parameter optimization. Graphs from consecutive welds will vary slightly as the system dynamically adjusts time to accommodate varying surface conditions. The weld power data is gathered by sampling the power used in 5 millisecond intervals.

#### **Power**

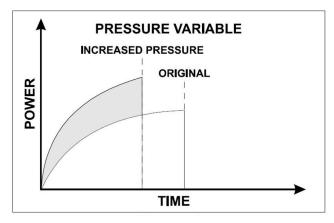
The converter/ booster/ horn, (stack assembly), requires minimal electrical power to initiate and maintain motion (vibration) at a 'no-load' condition. As the mechanical load increases, the power required to maintain the mechanical vibration also increases. The maximum power required during a weld cycle is 'Peak Power'.





By increasing Pressure and maintaining all other parameters, the mechanical load or force on the weld joint increases, therefore, the amount of Power required to maintain the vibration of the stack increases. Subsequently, because of the increased Power Level, less time is required to deliver the same amount of Energy. This relationship is illustrated in the following diagram (Figure 2.4):

Figure 2.4 Pressure, Power, and Time relationship

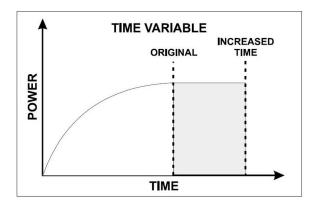


The difference in the appearance of each of the above weld graphs is the result of increased Power loading. Based upon an increase in Pressure, additional Power is required to maintain the motion of vibration. Thus, the same amount of energy is delivered in less time. This approach is typically used to raise the loading of the power supply during a weld cycle to the desired level as determined by the application.

#### **Time**

The time required to deliver the necessary energy is defined as the Weld Time. For most welds, the time required will be less than one second. If more energy is required and all other weld parameters are maintained, the weld time will increase (Figure 2.5).

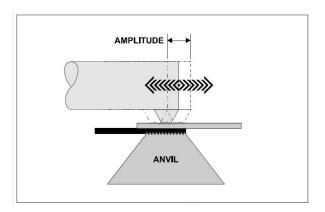
Figure 2.5 Weld Time



#### **Amplitude**

An ultrasonic tool is a resonant acoustical device. The term Amplitude is used to describe the amount of longitudinal expansion and contraction that the tooling endures as it vibrates (Figure 2.6). The amplitude correlates to the scrubbing action at the weld interface. This scrubbing action combined with pressure is what advances the weld by a diffusing or mixing of the base materials.

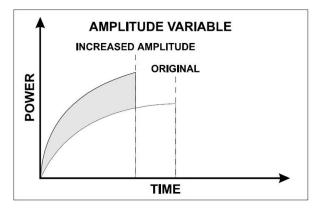
Figure 2.6 Amplitude



As previously mentioned, the converter/ booster/ horn, (stack assembly), requires minimal electrical power to initiate and maintain vibration in a 'no-load' condition. As the amplitude increases, the power required to maintain the increased velocity of vibration also increases.

Subsequently, because of the increased Power less time is required deliver the same amount of Energy. This relationship is illustrated in the power diagram (Figure 2.7):

Figure 2.7 Power, Time, and Energy relationship

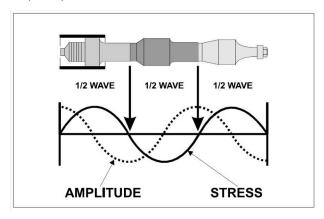


#### **Resonant Frequency**

The ultrasonic tooling acts as a spring having node points and anti-node points. The mechanical energy used to vibrate the tool is created by the converter. As the vibrations are propagated through the acoustical tool, a harmonic resonance is established consisting of nodes and anti-nodes. This action results in a resonant wave being transferred through the tooling (Figure 2.8). The efficiency of the resonant wave transfer depends on the natural resonant frequency of the horn and is determined by two factors:

- The speed of sound through the material
- The geometric shape of the object

Figure 2.8 Resonant Frequency



Avoiding An Overload Condition: It is possible to increase the Amplitude and or the Pressure to a point where the power available is not adequate to initiate or maintain vibration under the given mechanical load. At this point, the power supply will stall resulting in an Overload condition. Electronic circuits in the system will protect the power supply if this condition exists.

Welding To Time: In specific applications, 'Welding To Time' may be desired. As previously mentioned, there are three primary variables that interact; they are:

- TIME: The duration of applied ultrasonic vibration
- AMPLITUDE: The longitudinal displacement of the vibration
- FORCE: The compressive force applied perpendicular (normal) to the direction of vibration



Generally, welding for a specific time will produce acceptable results when:

- The equipment is installed on an automated production line and each station must complete its process within a certain time limit
- Very small low energy welds on clean components are being made

**Welding Temperature:** Ultrasonic welding produces a localized temperature rise from the combined effects of elastic hysteresis, interfacial slip and plastic deformation. The weld interfaces reach approximately 1/3 the temperatures needed to melt the metals. Since the temperature does not reach the melting point of the material, the physical properties of the welded material are preserved. As the ultrasonic welding process is an exothermic reaction, as welding time increases so does weld temperature.

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## 2.2 Terminology

**Actuator:** A mechanical device which houses the converter/booster/horn (stack) assembly in a rigid mounting and is utilized to move the stack up or down. This allows for precise control of welding pressure for efficient while delivering mechanical vibrations from the ultrasonic stack to the work piece(s).

**After Burst:** A short duration (burst) of ultrasonic energy that begins after completion of the AFTER BURST DELAY. (Also See: AFTER BURST DELAY & AFTER BURST DURATION).

**After Burst Delay:** The amount of time, in seconds, between the completion of the ultrasonic welding cycle and the start of the AFTER BURST. (Also See: AFTER BURST & AFTER BURST DURATION).

**After Burst Duration:** The amount of time, in seconds, that AFTER BURST energy is delivered. (Also See: AFTER BURST & AFTER BURST DELAY).

**Amplitude:** Amplitude is the peak-to-peak displacement of mechanical motion as measured at the face of the horn tip. Amplitude is measured in thousandths of an inch or in microns. (i.e. A standard 40 kHz converter produces approximately .0004" or 10 microns of amplitude), Inches x 25,400 = microns. -- With 'Advanced Power Supply' this is adjustable depending on system frequency and application tooling.

**Anti-Node:** The anti-node is the area of the horn and booster that exhibits maximum longitudinal displacement and where the internal dynamic forces are equal to zero. This area is at the face and back surface on half-wave technology.

**Anvil:** A device specially designed to grip the lower component and hold it stationary against the energy of vibration(s) which allows a weld to be created.

**Baud Rate:** A communications measure describing the speed at which signals are transmitted serially (the number of signal events per second).

**BBRAM:** Nonvolatile random access memory (battery back-up random access memory). Equipped with long life built in batteries, this memory area preserves weld parameters and menu settings when the system is powered off. (also known as BBR).

**Booster:** The central component of an ultrasonic stack assembly. A device which transfers mechanical energy from the converter to the ultrasonic horn. The booster will, depending on design, increase, decrease, or maintain the specific energy (amplitude) as received from the converter.

**Calibration:** The process of adjusting a device to a known position for purposes of inspection and/or monitoring position, direction, speed, and/or velocity.

**Clock:** An electronic circuit that generates timing pulses to synchronize the operations of various other circuits in a device(s).

**Communications:** Transmission of information between points of origin and reception without alteration of the sequence and or structure of that information content.

**Consumable Spare Tooling:** The tooling portion of the ultrasonic system that wears and requires replacement due to production use. This includes but is not limited to ultrasonic horns, replaceable tips, anvil, and positioning mask. A Spare Tooling Specification Sheet is included within the Operation Manual to document the spare tooling for a specific metal welding application.

**Continuous Sonics Mode:** A system setting in which the power supply will deliver ultrasonic electrical energy until the start signal is terminated.

**Controller:** The portion of the welding system that provides specific settings & instruction(s) to the overall welding system.

**Converter:** A device which utilizes a lead-zirconate-titanate electrorestrictive element to change high frequency electrical energy into high frequency mechanical energy.

**Counter:** A programmable device used to monitor system cycles and alert personnel when specific conditions are met.

**Data:** Any representation(s) of instructions, characters, information, or analog quantities to which meaning may be assigned.

**Default:** A chosen system setting or parameter in which the system does not require external data input. In some cases the default value will be changed based upon equipment use.

**Dynamic Spring:** An, adjustable, energy storage mechanism (shock absorber) which allows for stack follow through upon engagement of application tooling with the work pieces to be welded.

**Energy:** Energy is the area beneath the ultrasonic power curve and is calculated in joules, (Watts X Seconds = Joules). When the ultrasonic welding system is setup in the "Weld In Energy" mode the system will deliver the amount of energy as programmed. **NOTE:** The maximum (default) time allowed for delivering ultrasonic energy is five (5) seconds.

**Energy Mode:** A welding method in which the ultrasonic power supply is active until the required amount of energy is delivered (See ENERGY).

**Fixture:** A device for positioning and or holding a component for assembly.

**Force:** The amount of mechanical pressure that is used to deliver, (bring down) the mechanical actuator. This programmed force is also called TRIGGER FORCE and is used to engage the knurl pattern into the component part(s) prior to the initiation of ultrasonic energy.

**Frequency:** The number of complete oscillations per second expressed in Hertz (Hz) or kilohertz (1 kilohertz = 1000 Hz). Typically 20 kHz or 40 kHz.

**Gain:** The ratio of the amplitude of motion produced by the converter and delivered by the horn is called the gain. It is determined by the difference in mass on either side of the nodal point.

**Hand Shaking:** The procedure (signal exchange) when a connection is established between two electronic devices. A common example is the signal exchange between a terminal and a MODEM. These signals (hardware and software) are used to control the flow of data (start/stop) between devices.

**Height:** A display value, in millimeters (mm), as registered by a linear encoder upon completion of an ultrasonic welding cycle. -- Programmable, in millimeters, with Upper Control Limit & Lower Control Limit.

**Height Encoder:** A device utilized to monitor position, direction, speed, and/or velocity.

**Horn:** An acoustically designed metal tool that delivers mechanical energy from the converter/ booster into the work piece. Most applications utilize half wave technology, (40 kHz =  $2.2'' \pm 1.20$  kHz =  $5.5'' \pm 1.20$  kHz =  $5.5''' \pm 1.20$  kHz =  $5.5'''' \pm 1.20$  kHz =  $5.5'''' \pm 1.20$  kHz =  $5.5''''' \pm 1$ 

**Hold Time:** The amount of time after delivery of ultrasonic energy until the stack tooling begins to retract from the component material(s).

Joint: The welded surfaces.

**Linear Height Encoder:** (See: Height Encoder).

**Loading Meter:** A meter which indicates the power drawn from the ultrasonic power supply.

**Maintenance Counter:** A programmable device used to alert production personnel of the need to review / inspect application tooling and/or the ultrasonic system for preventive maintenance purposes. The device increments one (1) count for each system cycle. (See: Counters).

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**Mode:** The method of operating the system (also see WELDING MODE).

**Node:** The node is the area of the horn, (and booster), that exhibits no longitudinal displacement and where the internal dynamic forces are at the maximum. This area is in the center location on half-wave technology.

**Parameter(s):** Programmable units used to control and or monitor the ultrasonic process. -- Include but not limited to ENERGY, FORCE, PRESSURE, AMPLITUDE.

**Parts Counter:** A programmable device used to monitor system cycles and alert personnel when specific conditions are met. (See: Counters).

**Peak Power:** Peak power is the maximum amount of power in watts that was required to keep the ultrasonic stack in motion during the weld cycle.

**Power:** Power, measured in watts, is a function of pressure and amplitude. The amount of power, (watts) required to keep the ultrasonic stack in motion is monitored and used to develop a power curve. This power curve is used to calculate the amount of energy delivered/ dissipated, (Watts = Joules / Time). The power as displayed on the control box is peak power.

**Power Supply (Ultrasonic):** An electronic device that converts 50/60 cycle electrical current into 40 kHz, (40,000) or 20 kHz, (20,000) cycles per second high frequency electrical energy.

**Power Supply Overload (Ultrasonic):** The point or limit at which the amount of power in watts, required to keep the ultrasonic stack in motion, exceeds the available power from the power supply. The system will go into an overload condition in order to prevent system damage.

**Preheight:** A pre-sonic inspection display, in millimeters (mm), as registered by a linear encoder prior to initiation of the ultrasonic welding cycle. -- Programmable, in millimeters, with Upper Control Limit & Lower Control Limit.

**Presets:** System memory available for storage and retrieval of welding parameters.

**Pressure:** The amount of mechanical pressure supplied to the ultrasonic stack assembly while delivering ultrasonic energy to the components.

**Quality Widows & Limits:** Programmable values used by the system to compare actual process data. Actual process data must be within limits or an alarm condition will exist.

**Setup Mode:** The condition the control box must be in prior to adjusting parameters, quality windows, and/or any others settings except those contained within the Command Mode.

**Squeeze Time:** The amount of time after the ultrasonic tooling engages the component(s) and before delivery of ultrasonic energy. -- Adjustable from 0 - 0.5 seconds

**Stress:** Stress is the amount of dynamic force per cross sectional area.

**Time:** Time is the duration of the ultrasonic, mechanical, activity. Time is a component used to calculate the amount of ultrasonic energy delivered during a weld cycle, (Time = Joules / Watts).

**Tip:** Device specially designed to grip the upper component, to be welded, and to direct the ultrasonic energy into the work piece, (Also: Horn Tip & Replaceable Horn Tip).

**Tip Nut:** Device specially designed to securely clamp a replaceable tip onto the horn.

Trigger Force: (See: Force).

**Tuning:** Adjusting to optimize power supply performance according to resonance frequency, especially with regard to the horn and converter.

**Velocity:** The rate of motion at a specific time [velocity = distance / time] (also referred to as speed).



#### Weld Mode:

- **Weld In Energy:** System delivers ultrasonic energy until a predetermined amount of energy, in joules is dissipated. The system determines energy by calculating the area beneath the power curve -- Watts x Time = Joules (1 watt per second = 1 joule).
- **Weld In Height:** System delivers ultrasonic energy until the ultrasonic tooling reaches a predetermined position.
- Weld In Time: System delivers ultrasonic energy for a predetermined amount of time.
- Welding Parameters: (See: Parameters).

# **Chapter 3: Shipping and Handling**

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## 3.1 Unpacking, Handling & Installation

Unpack the Actuator and Touchscreen Controller. Remove the top cover of the power supply and check if any components became loose during shipment.

### 3.1.1 If damage has occurred

Notify the shipping company immediately. Retain packaging materials for inspection and possible re-use.

### 3.1.2 System Location

Locate the Touchscreen Controller in an area away from radiators or heating vents. Allow sufficient clearance in back of the controller to access the connectors. Observe the following:

- Do not block the exhaust or air intake areas. Proper air circulation is necessary to maintain a safe operating temperature
- Only operate the controller within an ambient temperature range of 41°F to 122°F (5°C to 50°C)
- Verify that neither dust nor dirt are allowed to restrict the flow of air exhaust or air intake. Clean the air ports as necessary

If the temperature of the power supply exceeds the recommended operating range, a thermal switch will stop ultrasonics and the power supply will display an Overload alarm. Ultrasonics will remain off until the power supply cools to a safe operating temperature and the RESET button is pressed.

If the environment is excessively dirty or oily, contact Branson for assistance. Special Touchscreen Controller enclosures, filters (i.e. filter/separator/regulator), and other equipment are available.

### 3.1.3 System Assembly

Connect the actuator system per the Hookup diagram contained in the Special Information Instruction Set. Verify that connections are complete and correct before proceeding. Plug the Controller into a proper power source. See the Touchscreen Controller Instruction Set for power specifications, plugs and receptacles used.

To prevent the possibility of an electrical shock, always plug the power supply into a grounded power source. Be sure the power switch is in the Off position before making any electrical connections.

Connect the system to a clean (5 micron air filter with 0.5 micron mist separator), dry, 80 psig (5.5 bar) minimum air supply. See the Actuator Instruction Set for information on the set up of application tooling and the use of this equipment for ultrasonic welding.

## 3.1.4 Crash Gap Adjustment

In most applications, adjustment of the gap between the ultrasonic Horn Tip and the Anvil is factory set to prevent these surfaces from contacting each other when no parts to be welded are present and the foot pedal is depressed. A poorly adjusted crash gap can cause serious damage to the tooling. See the Actuator Instruction Set for proper setup instructions.

## 3.1.5 Operating the System

With all proper connections made and with tooling properly set up, welding may be performed. In most instances it is likely that Branson has developed weld settings for your application and stored them as presets in the controller prior to shipping. See the Touchscreen Controller Instruction Set for information on retrieving presets. For other



weld parameter information pertaining to your system, see the parameter preset page included in the Special Information Instruction Set.

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# **Chapter 4: Troubleshooting**

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## 4.1 Troubleshooting

This section shows how to fix some of the possible errors and problems which may occur in normal use of the MWX100/ Ultrasplice system.



### 4.2 Weld Overload

Weld overloads are premature shut downs of the power supply. Overloads signify excessive loads and must be corrected if continued reliability of the equipment is to be maintained. Hardware internal to the supply are controlling this function and it can not be defeated.

The control system analyzes the end of weld characteristics to check for overloads. If the system determines an overload an alarm occurs. The control halts action until the system is reset.

Some of the possible causes for overloads are:

- The tool clearances are too small, horn and anvil touch during welding
- Excessive air pressure with low amplitude
- Defective Stack assembly
- Defective Power Transistors in power supply

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### 4.3 Low Air Pressure

The control system and its components were designed to run with a clean air supply of from 90 to 120 psi. The control system monitors the air pressure from the low air pressure switch (optional). The low pressure threshold is set from the controller. An alarm occurs when incoming line pressure the drops below the set pressure.



## 4.4 Ready Check

The system undergoes a Ready Check operation at every startup, the end of every weld, and at the exit of Setup mode. This procedure checks the height encoder position. If an incorrect height value is returned, an alarm occurs.

Some of the possible causes of a Ready Check alarm are:

- The horn is stuck in the closed position
- Maintenance has moved the height encoder to an out of limit condition
- Defective encoder or electronics
- Encoder not plugged in to its connector



# 4.5 Troubleshooting Guide

**Table 4.1** Troubleshooting Guide

Problem	Solution
	Power cable plugged in.
System will not turn on.	Power turned on at the outlet.
	Check internal fuses on the Controller Line Board.
Plant fuse fails or circuit breaker trips	Inspect power cord, replace if shorted.
when plugging the unit into an electrical outlet.	Check line filter, replace if failed.
Plant fuse fails or circuit breaker trips during weld cycle.	Check current rating of the plant fuse or the circuit breaker, replace if failed.
Line fuse fails.	Check fuse current rating, replace if incompatible.
	Check fan motor, replace if failed.
Horn will not move down or up.	System not connected to air supply.
Horri will not move down or up.	Air not turned on.
	Check Emergency Stop Switch.
Get Emergency Stop when system is	All cables properly connected.
turned on.	Press red switch on foot pedal. (if system is equipped with one)
	RF Cable connected.
No Sonics when test button is pressed.	Check RF cable for broken wire.
, , , , , , , , , , , , , , , , , , ,	Ribbon cable in power supply between SPM and programmer unplugged.
	Check all cable connections.
	Check start cable for broken wires.
No sonics during weld cycle.	Check inside power supply for loose start cable from rear of unit to programmer board.
	Check thermo switch in power supply.

Table 4.1Troubleshooting Guide

Problem	Solution
	Stack not tuned properly.
	Tooling not set up properly.
	Crash gap not set properly.
Overloads when welding.	Tip nut cracked, replace if needed.
o concess mish meranig.	Check weld parameters.
	Check stack interfaces for fretting.
	Check for loose or failed horn or booster, tighten or replace as necessary.
When touching the system you get a slight	Inspect power cord, replace if needed.
electrical shock.	Inspect system ground, repair if needed.
Tooling heats up after machine runs a	Cooling air is not turned on or is not on long enough.
while.	Cooling air is not directed at tooling.
	Check weld parameters.
	Check tooling gaps.
	Check knurl on tooling. If worn replace tooling.
Low weld strength.	Increase Energy.
	Check the Down stop adjustment.
	Check for part contamination.
	Ensure all hardware is tight.
	Reset parameters.
	Reset amplitude.
Excessive welding.	Reset pressure.
	Measure and re-calibrate amplitude display.
	Reset limits.
	Check tip, rotate or replace if worn.
	Check anvil for wear, rotate or replace if worn.
Time limit error or peak power error	Check air pressure setting.
lisplayed after weld cycle.	Cl   t f
displayed after weld cycle.	Check up stop for proper adjustment.
displayed after weld cycle.	Process settings have to be opened up due to part variance or limits should be adjusted according to the part/wire being run.

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**Table 4.1** Troubleshooting Guide

Problem	Solution
	Check plate screws and tighten or replace.
	Check cover plate screws and tighten.
Squealing sound during welding or when test key is depressed.	Reset gaps.
,	Re-square horn/tip and reset gaps.
	Reset horn tip and gap.
	Re-calibrate encoders with 1mm gauge.
Weld heights are inconsistent.	Ensure the connector for the encoder is tightly plugged into the actuator card.
	Check air pressure.
Horn is stuck in down position.	Ensure air lines are installed properly.
	Check for kinks in air lines.
Air leaking from machine.	Ensure all air line connections are tight.
All leaking from machine.	Check for cracked or broken air lines.
	Check tooling gap.
Unusual sound during weld cycle.	Check converter.
	Check stack assembly.
Squealing sound from power supply when unit is turned on.	Check cooling fans in rear of unit.
Maintenance counter alarm.	Reset maintenance counter.
	Check air lines for contamination.
Actuator arm moves sluggish.	<b>NOTE:</b> Air must be filtered to 5 microns and be oil and water free.
	Check solenoid valve, replace if needed.
	Check air regulator.
	The horn is stuck in the closed position.
Custom has READY CHECK massage	Maintenance has moved the height encoder to an out of limit condition.
System has READY CHECK message.	Defective encoder or electronics.
	Encoder not plugged into the actuator card.
Time, height and energy inconsistent.	Switch to energy mode & open height window. Make some sample welds. Check the time and the height of the welds for consistency. If the time or weld thickness varies greatly, check the air regulator.

# **Chapter 5: Maintenance**

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### 5.1 Periodic Maintenance

In order to maintain optimum operating conditions, it is important to perform various maintenance and equipment inspections at periodic intervals. Please observe the following recommendations.

#### **Daily**

• Drain water and contaminants from the airline filters, if required

#### **Every Tool Rotation**

- Inspect the clamping surfaces of the Tip, the Tip Nut and the Horn for fretting
- Vacuum and clean out any copper residue or dirt in the actuator

#### After 40k-50k Cycles Maximum (subject to change based on weld application):

- Vacuum and clean inside of power supply
- Calibrate pressure regulator
- Clean and torque the stack interface
- Calibrate amplitude

### 5.1.1 FSR Assembly

Air Filter/Separator/Regulator (Optional Branson Part #207-020) should be serviced after 1 year or when a pressure drop of 15 psi is reached.

- Disconnect the air supply
- · Remove and clean out filter bowl with a clean rag
- Replace the white filter element and re-assemble
- · Remove and clean out separator bowl with a clean rag
- Replace brass-colored filter element and reassemble
- · Reconnect air supply

#### Do not use solvent to clean filter bowls.

CAUTION	
	Clean the air filter bowl with a mild household soap only. The bowl is made from a polycarbonate material, which can rupture if exposed to synthetic lubricating oils solvents or harsh chemicals. The bowl is rated for a maximum line pressure of 140 psig (1043 kPa) and a maximum temperature of 120°F (49°C).





Ultraweld L20
Actuator

Operating Manual

Branson Ultrasonics Corp. 120 Park Ridge Road Brookfield, CT 06804 (203) 796-0400 http://www.bransonultrasonics.com





## **Manual Change Information**

At Branson, we strive to maintain our position as the leader in ultrasonics metal welding, plastics joining, cleaning, and related technologies by continually improving our circuits and components in our equipment. These improvements are incorporated as soon as they are developed and thoroughly tested.

Information concerning any improvements will be added to the appropriate technical documentation at its next revision and printing. Therefore, when requesting service assistance for specific units, note the Revision information found on this document, and refer to the printing date which appears on this page.

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#### **Foreword**

Congratulations on your choice of a Branson system!

The Branson Ultraweld L20 Series system is process equipment for the joining of metal parts using ultrasonic energy. It is the newest generation of product using this sophisticated technology for a variety of customer applications. This Operating Manual is part of the documentation set for this system, and should be kept with the equipment.

Thank you for choosing Branson!

#### Introduction

This manual is arranged into several structured chapters which will help you find the information you may need to know to safely handle, install, set up, program, operate, and/or maintain this product. Please refer to the <u>Table of Contents</u> of this manual to find the information you may be looking for. In the event you require additional assistance or information, please contact our Product Support department (see <u>1.5 How to Contact Branson</u> for information on how to contact them) or your local Branson representative.

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## 1.1 Safety Requirements and Warnings

This chapter contains an explanation of the different Safety Notice symbols and icons found in this manual and provides additional safety information for ultrasonic welding. This chapter also describes how to contact Branson for assistance.

### 1.1.1 Symbols Found in This Manual

These symbols used throughout the manual warrant special attention:

WARNING	General Warning
<u>^</u>	<b>WARNING</b> indicates a hazardous situation or practice which, if not avoided, can result in serious injury or death.

CAUTION	High Voltage Hazard				
4	High voltage. Turn power off before servicing.				

CAUTION	Loud Noise Hazard					
	Loud noise hazard. Ear protection must be worn.					

CAUTION	General Warning					
	<b>CAUTION</b> indicates a hazardous situation which, if not avoided, could result in minor or moderate injury. It can also alert the user to unsafe practices or conditions that can damage equipment if not corrected.					

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NOTICE	
1	<b>NOTICE</b> is used to address practices not related to personal injury. It contains important information. It might also alert the user about unsafe practices or conditions that can damage equipment if not corrected.

### 1.1.2 Symbols Found on the back of the product

The Ultraweld L20 Actuator has several warning labels on it to alert the user of items of concern or hazard. The following warning symbols appear on the L20 Actuator:

Figure 1.1 Safety Label Found on the Front of the Actuator



Figure 1.2 Safety Labels Found in the Back of the Unit





Figure 1.3 Safety Labels Found Near Bolt-Down Locations



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### 1.2 General Precautions

Take the following precautions before servicing the Power Supply:

CAUTION	Loud Noise Hazard					
	Sound level emissions of up to 84.9 dB have been measured using a standard test load. To prevent the possibility of hearing loss, use appropriate hearing protection.					

WARNING	High Voltage Hazard				
4	Be sure the power switch is in the Off position before making any electrical connections.				

NOTICE	
1	Sound level and frequency of the noise emitted during the ultrasonic assembly process may depend upon <b>a.</b> type of application, <b>b.</b> size, shape and composition of the material being assembled, <b>c.</b> shape and material of the holding fixture, <b>d.</b> welder setup parameters and <b>e.</b> tool design. Some parts vibrate at an audible frequency during the process. Some or all of these factors may result in sound levels of up to 84.9 dB. In such cases operators may need to be provided with personal protective equipment. See 29 CFR (Code of Federal Regulations) 1910.95 Occupational Noise Exposure. For all other countries, follow your local regulations.

- To prevent the possibility of an electrical shock, always plug the Power Supply into a grounded power source
- Power supplies produce high voltage. Before working on the Power Supply module, do the following:

Turn off the Power Supply;

Unplug main power; and

Allow at least 2 minutes for capacitors to discharge

- High voltage is present in the Power Supply Controller. Do not operate with the cover removed
- High line voltages exist in the ultrasonic Power Supply module. Common points are tied to circuit reference, not chassis ground. Therefore, use only non-grounded, battery-powered multimeters when testing these modules. Using other types of test equipment can present a shock hazard
- Be sure power is disconnected from the Power Supply before setting a DIP switch
- Keep hands from under the horn. Down force (pressure) and ultrasonic vibrations can cause injury
- Do not cycle the welding system if either the RF cable or converter is disconnected
- · Avoid situations where fingers could be pinched between the horn and the fixture

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### 1.2.1 Intended Use of the System

The Branson Metal Welding Controller and Ultraweld L20 Actuator are components of an ultrasonic welding system. These are designed for a wide variety of welding or processing applications:

- Welding of non-ferrous metals
- Welding of copper to copper
- Welding of copper to aluminum
- Welding of aluminum to aluminum
- Termination of non-tinned wire to terminals

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## 1.3 Regulatory Compliance

This product meets electrical safety requirements and EMC (Electromagnetic Compliance) requirements for North America, Great Britain and the European Union.

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## 1.4 Warranty

For warranty information please reference the warranty section of Terms and Conditions found at: <a href="https://www.emerson.com/branson-terms-conditions">www.emerson.com/branson-terms-conditions</a>.

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#### 1.5 How to Contact Branson

Branson is here to help you. We appreciate your business and are interested in helping you successfully use our products. To contact Branson for help, use the following telephone numbers, or contact the field office nearest you (business hours from 8 a.m. to 4 p.m. Central and Eastern Times Zones).

- North American Headquarters (all departments): (203) 796-0400
- Parts Store: Direct Number for Parts Store in Brookfield (203) 796-9807

Tell the operator which product you have and which person or department you need. If after hours, please leave a voice message with your name and return telephone number.

### 1.5.1 Before Calling Branson for Assistance

This manual provides information for troubleshooting and resolving problems that could occur with the equipment (see <a href="Chapter 7: Maintenance">Chapter 7: Maintenance</a>). If you still require assistance, Branson Product Support is here to help you. To help identify the problem, use the following questionnaire which lists the common questions you will be asked when you contact the Product Support department.

#### Before calling, determine the following information:

- 1. Your company name and location
- 2. Your return telephone number
- 3. Have your manual with you
- 4. Know your equipment model and serial numbers (found on a gray data label on the units). Information about the Horn (part number, gain, etc.) or other tooling may be etched into the tooling. Software- or firmware-based systems may provide a BIOS or software version number, which may be required
- 5. What tooling (horn) and booster are being used?
- 6. What are the setup parameters and mode?
- 7. Is your equipment in an automated system? If so, what is supplying the "start" signal?
- 8. Describe the problem; provide as much detail as possible. For example, is the problem intermittent? How often does it occur? How long before it occurs if you are just powering up? If an error is occurring, which error (give error number or name)?
- 9. List the steps you have already taken
- 10. What is your application, including the materials being processed?
- 11. Have a list of service or spare parts you have on hand (tips, horns, etc.)

12. I	Notes:					
-						

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### 1.6 Returning Equipment for Repair

Before sending equipment for repair, provide as much information with the equipment to help determine the problem with the system. Use the following page to record necessary information.

#### 1.6.1 Returning Equipment for Repair

To return equipment to Branson, you must first obtain an RGA number from a Branson representative, or the shipment may be delayed or refused.

If you are returning equipment to Branson for repair, you must first call the Repair department to obtain a Returned Goods Authorization (RGA) number. (If you request it, the repair department will fax a Returned Goods Authorization form to fill out and return with your equipment).

Branson Repair Department

120 Park Ridge Road

Brookfield, Connecticut 06804 U.S.A.

Direct telephone number: (203) 796-0575

Fax number: (203) 796-0574

- · Provide as much information as possible that will help identify the need for repair
- · Carefully pack the equipment in original packing cartons
- Clearly label all shipping cartons with the RGA number on the outside of cartons as well as on your packing slip, along with the reason for return

If you are returning equipment to Branson, please call the Repair Department to obtain a Returned Goods Authorization (RGA) number. (At your request, the Repair Department

- Return general repairs by any convenient method. Send priority repairs by air freight
- You must prepay the transportation charges FOB Brookfield, Connecticut, U.S.A.

1.6.2	Get	an	RGA	N	lum	ber
-------	-----	----	-----	---	-----	-----

RGA # \_\_\_

	wi	Il fax an RGA form to fill out and return with the equipment.)
1.6.3	R	ecord Information About the Problem
		fore sending equipment for repair, record the following information and send a copy of it the equipment. This will greatly increase Branson's ability to address the problem.
	1.	Describe the problem; provide as much detail as possible. For example, is the problem intermittent? How often does it occur? How long before it occurs after powering up?
	2.	Is your equipment in an automated system?
	3.	If the problem is with an external signal, which signal?
	4.	If known, include plug/pin # (e.g., P29, pin #3) for that signal:



5.	What are the Weld Parameters?
6.	What is your application? (Type of weld, metal material, etc.)
7.	Name and phone number of the person most familiar with the problem:
8.	Contact the Branson office prior to shipping the equipment.

- 8. Contact the Branson office prior to shipping the equipment.
- 9. For equipment not covered by warranty, to avoid delay, include a Purchase Order.

Send a copy of this page with the equipment being returned for repair.

#### 1.6.4 **Contact Information**

Call your local Branson Representative, or contact Branson by calling (203) 796-0400.	
My Local Branson Representative's name is:	
can reach this representative at:	
	_

#### 1.6.5 Pack and Ship the Equipment

- 1. Carefully pack the system in original packing material to avoid shipping damage. Plainly show the RGA number on the outside of cartons as well as inside the carton along with the reason for return. Make a list of all components packed in the box. KEEP YOUR MANUAL.
- 2. Return general repairs by any convenient method. Send priority repairs by air freight. Prepay the transportation charges FOB the repair site (either the Branson field office or Brookfield, Connecticut USA location).

NOTICE	
6	Items that are sent Freight Collect will be refused.



## 1.7 Obtaining Replacement Parts

You can reach Branson Parts Store at the following telephone numbers:

- Direct Telephone Number: (203) 796-9807
- Fax number: (203) 926-2678

Many parts can be shipped the same day if ordered before 2:30 p.m., Eastern time.

A parts list is found in <u>Chapter 7: Maintenance</u> of this manual, listing descriptions and EDP part numbers. If you need replacement parts, coordinate the following with your purchasing agent:

- · Purchase order number
- Ship to information
- · Bill to information
- Shipping instructions (air freight, truck, etc.)
- Any special instructions (for example, "Hold at the airport and call"). Be sure to give a name and phone number
- Contact name information

# **Chapter 2: The Ultraweld L20 Actuator**

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### 2.1 Models Covered

This manual contains instructions for installing, setting up and operating the Ultraweld L20 Actuator.

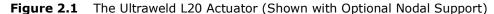
An Ultraweld L20 Actuator requires a compatible Branson Metal Welding Power Supply to function. The power supply operation is covered in separate manuals and user documents.

### 2.1.1 Power Supply Manual Set

The Following documentation is available for Branson Metal Welding Power Supplies compatible with Ultraweld L20 actuators:

- Ultraweld L20 VersaGraphix Controller Instruction Manual (DCM00060)
- Ultraweld L20 Touch Screen Controller Instruction Manual (DCM00002)

### 2.2 Overview of These Models





The Branson Ultraweld L20 system is comprised of a power supply, ultrasonic stack assembly, application tooling, and mechanical actuator.

The Ultraweld L20 Actuator is the part of the system that rigidly holds and moves the converter, booster and horn assembly known as the ultrasonic stack.

A pneumatic cylinder drives the actuator to apply a precise pressure to the parts to be welded during the weld cycle.

The Ultraweld L20 Actuator requires a compatible Branson Metal Welding Power Supply for power and control of the actuator's operation and to provide ultrasonic power to the converter in the actuator.

The Ultraweld L20 Actuator is designed with full, built-in pneumatic controls, and mechanical controls.

#### 2.2.1 Polar Shell & Ultrasonic Stack

The converter-booster-horn assembly, or ultrasonic stack, is supported in a steel polar shell by means of two diaphragm springs. The diaphragm springs are mounted at either end of the booster and are securely bolted to the polar shell. The diaphragm shaped springs are made from titanium and are acoustically tuned at the 20 kHz operating frequency. This system permits efficient transmission of ultrasonic vibration along the axis of the ultrasonic stack while providing rigid mounting.

#### 2.2.2 The Pneumatic System

The pneumatic system included on the Ultraweld L20 Actuator consists of solenoid valves, an air cylinder, an electronic pressure regulator, and 4 flow control valves. The ultrasonic stack's rate of descent and rate of return are controlled by the Down Speed and Up Speed control valves, respectively, located at the back of the unit. The front nozzle air flow is controlled by the Cooling Control valve, also located at the back of the unit. The converter cooling flow is controlled by a flow control valve located inside the unit.

#### 2.2.3 The Linear Encoder

The linear encoder is a sensing device that tracks polar block movement. The accuracy of the encoder is  $\pm 0.002$  in ( $\pm 0.05$ mm).

#### 2.2.4 Converter

The 20 kHz electrical energy from the power supply is applied to the transducer element or converter, which transforms the high frequency electric current into high frequency mechanical vibrations at the same frequency. The heart of the converter is a lead-zirconate-titanate electrostrictive element that, when subjected to an alternating voltage expands and contracts. The converter's efficiency of changing electrical energy to mechanical vibrations exceeds ninety-five percent.

#### 2.2.5 Booster

A booster couples the converter to the horn and helps determine the amplitude of vibration produced at the face of the horn. The booster is a resonant half-wave metal device made of titanium or aluminum and is designed to resonate at the same frequency as the converter with which it is to be used.

A booster has two functions:

- A rigid mounting for the converter/booster/horn stack
- An amplitude-of-vibration increaser or decreaser as ultrasonic energy is transmitted from the converter through the booster to the horn. The ratio of input to output amplitude is called the gain

#### 2.2.6 Horn

The horn is a half-wave length resonant metal device that transfers the ultrasonic vibrations from the booster to the weld tip. The horn is made of steel (titanium for replaceable tip tooling) and is designed to resonate at 20 kHz. The acoustical efficiency of steel and titanium helps to maintain constant amplitude throughout the operating temperature of the welder.

Since the horn is a vital part of the ultrasonic assembly system, it should not be altered without proper training and advice from Branson.

Depending upon the particular application at hand, the horn may be either a solid horn as shown in <u>Figure 2.1</u>, or a Horn with a replaceable tip that can be rotated or replaced.

### 2.2.7 Welding Tip (Replaceable Tip Tooling)

The welding tip is designed to grip the upper component of the part to be welded, and to couple the ultrasonic vibrations through that element into the bonding area. Welding tips are fabricated from high-speed tool steel and heat-treated to precise specifications to provide maximum life. The tip is coated to further enhance tool life and to provide corrosion resistance. The tip design offers multiple weld surfaces by indexing the tip on the horn to a new weld area.

#### 2.2.8 Tip Nut (Replaceable Tip Tooling)

The tip nut is made of titanium and is designed to securely clamp the tip onto the horn. The horn welding-tip/ tip-nut assembly is an efficient system for transmitting ultrasonic vibration to the parts to be welded and offers an interchangeable tool at a low cost.

#### 2.2.9 Anvil

The anvil is made of high grade tool steel and coated for maximum wear and corrosion resistance. The tool design allows it to be rotated to present multiple weld surfaces.

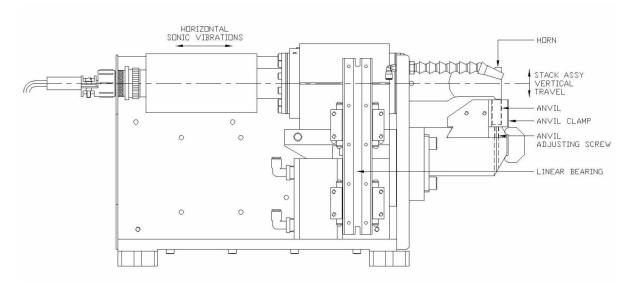
#### 2.2.10 Actuator

The ultrasonic stack is mounted into a steel polar block and securely clamped in place. The polar block is mounted to a linear bearing which provides precise vertical travel of the stack assembly, while providing excellent rigidity to resist any loss of ultrasonic energy in the horizontal direction of sonic vibrations. See <u>Figure 2.2</u>.

#### 2.2.11 Application Tooling

Application tooling is designed and manufactured to position and weld component materials to meet customer specifications. Application tooling typically consists of a horn/tip nut, anvil clamp, anvil holder, and tool support (see Figure 2.2).

Figure 2.2 Actuator Slide Mechanism



### 2.3 Features

The Ultraweld L20 Actuator is designed for automated, semi-automated and/or manual production operations. The following list describes the Ultraweld L20 Actuator features:

- A precision roller bearing slide to assure smooth operation and extreme accuracy
- Precise adjustments for accurate setting of both upper and lower positive stops
- Conveniently located flow controls offering easy adjustment of head speed in both directions
- A polar mounted ultrasonic stack to facilitate linear and axial setup and efficient transmission of ultrasonic energy to the horn
- Titanium horns with low cost replaceable tips or solid tool steel horns for fast setup and minimum tooling cost
- Fixturing which is changed quickly and easily for various applications by means of a dovetail mounting
- Optional vortex cooling to allow high-speed operation without heat buildup



#### 2.4 Controls

- **Up Speed:** Controls the upward speed of the ultrasonic stack. This control is used to raise the stack quickly for other mechanism actions and for quick part removal
- **Down Speed:** Controls the downward speed of the ultrasonic stack. This control is used to prevent damaging the parts to be welded, and increasing/decreasing cycle times to get better weld results
- **Cooling Air:** Controls the cooling air flow rate coming out of the cooling hose on the front of the actuator. Cooling air is used to keep the weld area and the converter within a reasonable temperature during welding
- **Down Stop:** The down stop is used to prevent contact between the Horn and Anvil if the welder is cycled without the part(s) to be welded. A minimum gap of 0.0004 in (0.10mm) is recommended
- **Up Stop:** The up stop is used to limit the upward travel of the horn. It is used to limit the upward travel to reduce cycle times and to ease the loading and unloading of parts

## 2.5 Ultrasonic Theory

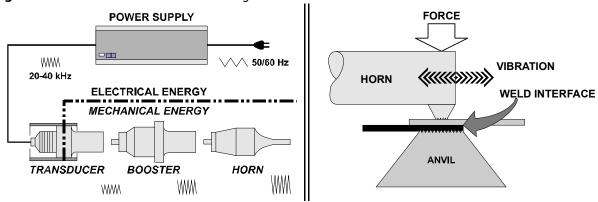
#### 2.5.1 What Is an Ultrasonic Weld?

Ultrasonic welding joins metal parts by applying the energy of high frequency vibrations onto the interface area between the parts to be welded.

#### 2.5.1.1 How Does It Work?

Electrical Energy is transformed into high frequency mechanical vibration. This mechanical vibration is transferred to a welding tip through an acoustically tuned horn. The parts are "scrubbed" together under pressure at 20,000, 40,000, or 60,000 cycles per second. This high frequency vibration, applied under force, disperses surface films and oxides, creating a clean, controlled, diffusion weld. As the atoms are combined between the parts to be welded, a true, metallurgical bond is produced.

Figure 2.3 How does Ultrasonic Welding Work?



### 2.5.2 Benefits of Ultrasonic Welding

Ultrasonic metal welding exhibits unique welding properties that include:

- · Excellent electrical, mechanical, and thermal connections between similar and dissimilar metals
- Low heat build up during the ultrasonic process (no annealing of materials)
- · Compensation for normal surface variations of the material
- Ability to clean surface oxides and contaminants prior to welding
- · Ability to weld large areas using minimal energy
- Ability to weld thin materials to thick materials
- Low cost per weld

#### 2.5.3 How Is an Ultrasonic Weld Made?

Although the theoretical process of producing an ultrasonic weld is uncomplicated, the interactions of the various weld parameters are important and should be understood. When producing an ultrasonic weld, there are three primary variables that interact; they are:

- Time: The duration of applied ultrasonic vibration
- Amplitude: The longitudinal displacement of the vibration
- Force: The compressive force applied perpendicular (normal) to the direction of vibration



The power required to initiate and maintain vibration (motion) during the weld cycle can be defined as:

Table 2.1 Calculating Power

	Where:
	P = Power (watts)
$P = F \times A \times f$	• F = Force* (N)
	A = Amplitude (microns)
	f = Frequency (Hertz)

<sup>\*</sup>Force = (Surface Area of the Cylinder) X (Air Pressure) X (Mechanical Advantage)

Energy is calculated as;

**Table 2.2** Calculating Energy

	Where:
E = P x T	E = Energy (joules)
	P = Power (watts)
	T = Time (seconds)

Thus the complete 'Weld To Energy' process would be defined as:

$$E = (F \times A \times f) \times T$$

A well designed ultrasonic metal welding system will compensate for normal variations in the surface conditions of the metals by delivering the specified energy value. This is achieved by allowing Time (T) to adjust to suit the condition of the materials and deliver the desired energy.

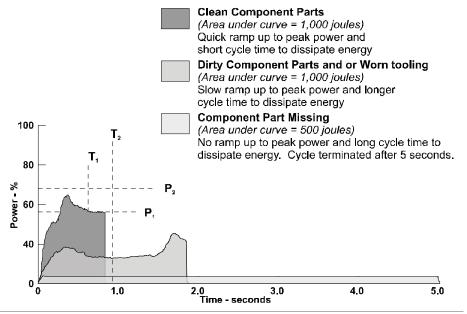
### 2.5.4 Welding to Energy - Why?

Most metal welding applications are produced by 'Welding To Energy' in order to compensate for the various surface oxides and contaminants associated with the metals being joined. In a few applications 'Welding To Time' or 'Welding To Height' will yield better results. Since the majority of all metal welds are produced using energy as the controlling factor we will confine our discussion to that condition.

Welding to energy is necessary because of the non-metallic oxides that form on the metal's surface as well as other contaminates such as grease and dirt. To producing quality welds reliably it is necessary that the surfaces to be joined are clean. The high frequency scrubbing action, combined with pressure, cleans the weld interface at the beginning of the weld process.

The following graph (<u>Figure 2.4</u>) illustrates a weld produced. The weld 'power graph' is sometimes to referred to a weld 'footprint'. It can be used to visualize the weld cycle and assists in parameter optimization. Graphs from consecutive welds will vary slightly as the system dynamically adjusts time to accommodate varying surface conditions. The weld power data is gathered by sampling the power used in 5 millisecond intervals.

Figure 2.4 Weld Power Graph for Clean and Dirty Components and when Part is Missing

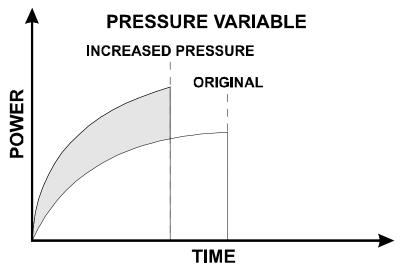


#### 2.5.5 Power

The converter/ booster/ horn, (stack assembly), requires minimal electrical power to initiate and maintain motion (vibration) at a 'no-load' condition. As the mechanical load increases, the power required to maintain the mechanical vibration also increases. The maximum power required during a weld cycle is 'Peak Power'.

By increasing Pressure and maintaining all other parameters, the mechanical load or force on the weld joint increases, therefore, the amount of Power required to maintain the vibration of the stack increases. Subsequently, because of the increased Power Level, less time is required deliver the same amount of Energy. This relationship is illustrated on Figure 2.5.

Figure 2.5 Pressure Variable with Increased Power

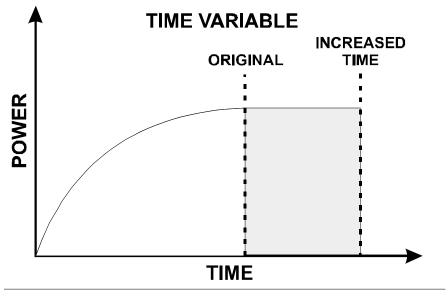


The difference in the appearance of each of the above weld graphs is the result of increased Power loading. Based upon an increase in Pressure, additional Power is required to maintain the motion of vibration. Thus, the same amount of energy is delivered in less time. This approach is typically used to raise the loading of the power supply during a weld cycle to the desired level as determined by the application.

#### 2.5.6 Time

The time required to deliver the necessary energy is defined as the Weld Time. For most welds, the time required will be less than one second. If more energy is required and all other weld parameters are maintained, the weld time will increase (Figure 2.6).

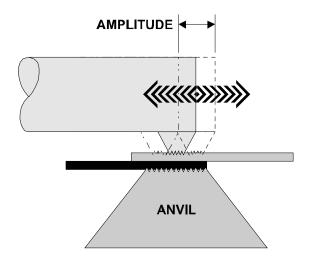
Figure 2.6 Pressure Variable with Increased Time



### 2.5.7 Amplitude

An ultrasonic tool is a resonant acoustical device. The term Amplitude is used to describe the amount of longitudinal expansion and contraction that the tooling endures as it vibrates (Figure 2.7). The amplitude correlates to the scrubbing action at the weld interface. This scrubbing action combined with pressure is what advances the weld by a diffusing or mixing of the base materials.

Figure 2.7 Scrubbing Action on Weld Interface



As previously mentioned, the converter/ booster/ horn, (stack assembly), requires minimal electrical power to initiate and maintain vibration in a 'no-load' condition. As the amplitude increases, the power required to maintain the increased velocity of vibration also increases. Subsequently, because of the increased Power less time is required deliver

the same amount of Energy. This relationship is illustrated in the following power diagram (<u>Figure 2.8</u>):

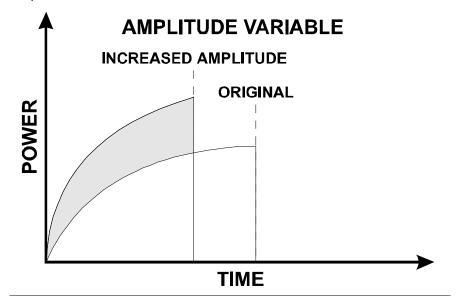


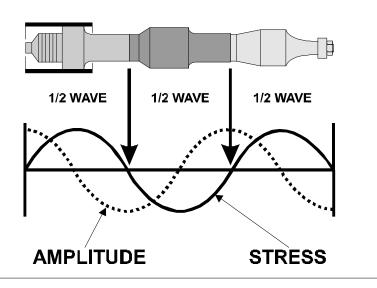
Figure 2.8 Amplitude's Influence on Weld Power and Time

### 2.5.8 Resonant Frequency

The ultrasonic tooling acts as a spring having node points and anti-node points. The mechanical energy used to vibrate the tool is created by the converter. As the vibrations are propagated through the acoustical tool, a harmonic resonance is established consisting of nodes and antinodes. This action results in a resonant wave being transferred through the tooling (<u>Figure 2.9</u>). The efficiency of the resonant wave transfer depends on the natural resonant frequency of the horn and is determined by two factors:

- The speed of sound through the material
- The geometric shape of the object

Figure 2.9 Harmonic Resonance on Ultrasonic Tooling.



#### 2.5.9 Avoiding an Overload Condition

It is possible to increase the Amplitude and or the Pressure to a point where the power available is not adequate to initiate or maintain vibration under the given mechanical load. At this point, the power supply will stall resulting in an Overload condition.

NOTICE	
1	Electronic circuits in the system will protect the power supply if an overload condition exists.

#### 2.5.10 Welding to Time

In specific applications, 'Welding To Time' may be desired. As previously mentioned, there are three primary variables that interact; they are:

- **TIME:** The duration of applied ultrasonic vibration
- AMPLITUDE: The longitudinal displacement of the vibration
- FORCE: The compressive force applied perpendicular (normal) to the direction of vibration

Generally, welding for a specific time will produce acceptable results when:

- The equipment is installed on an automated production line and each station must complete its process within a certain time limit
- Very small low energy welds on clean components are being made

#### 2.5.11 Welding Temperature

Ultrasonic welding produces a localized temperature rise from the combined effects of elastic hysteresis, interfacial slip and plastic deformation. The weld interfaces reach approximately 1/3 the temperatures needed to melt the metals. Since the temperature does not reach the melting point of the material, the physical properties of the welded material are preserved. As the ultrasonic welding process is an exothermic reaction, as welding time increases so does weld temperature.

### 2.6 Terminology

**Actuator:** A mechanical device which houses the converter/booster/horn (stack) assembly in a rigid mounting and is utilized to move the stack up or down. This allows for precise control of welding pressure while delivering mechanical vibrations from the ultrasonic stack to the work piece(s).

**After Burst:** A short duration (burst) of ultrasonic energy that begins after completion of the AFTER BURST DELAY. (Also see AFTER BURST DELAY & AFTER BURST DURATION).

**After Burst Delay:** The amount of time, in seconds, between the completion of the ultrasonic welding cycle and the start of the AFTER BURST. (See Also AFTER BURST & AFTER BURST DURATION).

**Amplitude:** Amplitude is the peak-to-peak displacement of mechanical motion as measured at the face of the horn tip. Amplitude is measured either in thousandths of an inch or in microns (e.g. a standard 40 kHz Converter produces approximately 0.0004'' or 10 microns of amplitude), Inches x 25.4 = microns. -- This is adjustable depending on system frequency and application tooling.

**Anti-Node:** The anti-node is the area of the horn and booster that exhibits maximum longitudinal displacement and where the internal dynamic forces are equal to zero. This area is at the face and back surface on half-wave technology.

**Anvil:** A device specially designed to grip the lower component and hold it stationary against the energy of vibration(s) which allows a weld to be created.

**BBR:** Nonvolatile random access memory (battery back-up random access memory). Equipped with long life built in batteries, this memory area preserves weld parameters and menu settings when the system is powered off. (Also known as BRAM.)

**Booster:** The central component of an ultrasonic stack assembly. A device which transfers mechanical energy from the Converter to the ultrasonic horn. The booster will, depending on design, increase, decrease, or maintain the specific amplitude as received from the converter.

**Calibration:** The process of adjusting a device to a known position for purposes of inspection and/or monitoring position, direction, speed, and/or velocity.

**Consumable Spare Tooling:** The tooling portion of the ultrasonic system that wears and requires replacement due to production use. This includes but is not limited to ultrasonic horns, replaceable tips, anvil, and positioning mask. A Spare Tooling Specification Sheet is included within the Actuator Operation Manual to document the spare tooling for a specific metal welding application.

**Controller:** The portion of the welding system that provides specific settings & instruction(s) to the overall welding system.

**Converter:** A device which utilizes a PZT (lead-zirconate-titanate) electrostrictive element to change high frequency electrical energy into high frequency mechanical energy.

**Counter:** A programmable device used to monitor system cycles and alert personnel when specific conditions are met.

**Data:** Any representation(s) of instructions, characters, information, or analog quantities to which meaning may be assigned.

**Default:** A chosen system setting or parameter in which the system does not require external data input. In some cases the default value will be changed based upon equipment use.

**Dynamic Spring:** An, adjustable, energy storage mechanism (shock absorber) which allows for stack follow through upon engagement of application tooling with the work pieces to be welded.

**Energy:** Energy is the area beneath the ultrasonic power curve and is calculated in joules, (Watts X Seconds = Joules). When the ultrasonic welding system is setup in the "Weld In Energy" mode the system will deliver the amount of energy as programmed. **NOTE:** The maximum (default) time allowed for delivering ultrasonic energy is five (5) seconds.

**Energy Mode:** A welding method in which the ultrasonic power supply is active until the required amount of energy is delivered (see ENERGY).

**Fixture:** A device for positioning and or holding a component for assembly.

**Force:** The amount of mechanical pressure that is used to deliver (bring down) the mechanical actuator. This programmed force is also called TRIGGER FORCE and is used to engage the knurl pattern into the component part(s) prior to the initiation of ultrasonic energy.

**Frequency:** The number of complete oscillations per second expressed in Hertz (Hz) or kilohertz (1 kilohertz = 1000 Hz). Typically 20 kHz or 40 kHz.

**Gain:** The ratio of the amplitude of motion produced by the Converter and delivered by the horn is called the gain. It is determined by the difference in mass on either side of the nodal point.

**Height:** A value, in millimeters (mm), as registered by a linear encoder upon completion of an ultrasonic welding cycle. -- Programmable, in millimeters, with Upper Control Limit & Lower Control Limit.

**Height Encoder:** A device utilized to monitor position, direction, speed, and/or velocity.

**Horn:** An acoustically designed metal tool that delivers mechanical energy from the converter/ booster into the work piece. Most applications utilize half wave technology.

**Hold Time:** The amount of time after delivery of ultrasonic energy until the stack tooling begins to retract from the component material(s).

**Joint:** The area where the surfaces are welded together.

**Linear Height Encoder:** See Height Encoder.

**Loading Meter:** A meter which indicates the power drawn from the ultrasonic power supply.

**Maintenance Counter:** Used to alert production personnel of the need to review/ inspect application tooling and/or the ultrasonic system for preventive maintenance purposes. (See Counters.)

**Mode:** The method of operating the system (See also WELDING MODE).

**Node:** The node is the area of the horn, (and booster), that exhibits no longitudinal displacement and where the internal dynamic forces are at the maximum. This area is in the center location on half-wave technology.

**Parameter(s):** Programmable units used to control and or monitor the ultrasonic process. --Include but not limited to ENERGY, FORCE, PRESSURE, AMPLITUDE.

**Parts Counter:** Used to monitor system cycles and alert personnel when specific conditions are met. (See Counters.)

**Peak Power:** Peak power is the maximum amount of power in watts that was required to keep the ultrasonic stack in motion during the weld cycle.

**Power:** Power, measured in watts, is a function of pressure and amplitude. The amount of power, (watts) required to keep the ultrasonic stack in motion is monitored and used to develop a power curve. This power curve is used to calculate the amount of energy delivered/ dissipated, (Watts = Joules / Time). The power as displayed on the control box is peak power.

**Power Supply (Ultrasonic):** An electronic device that converts 50/60 cycle electrical current into 20 kHz, (20,000), 40 kHz (40,000), or 60 kHz, (60,000) cycles per second high frequency electrical energy.

**Power Supply Overload (Ultrasonic):** The point or limit at which the amount of power in watts, required to keep the ultrasonic stack in motion, exceeds the available power from the power supply. The system will go into an overload condition in order to prevent system damage.

**Pre-Height:** A pre-sonic inspection display, in millimeters (mm), as registered by a linear encoder prior to initiation of the ultrasonic welding cycle. -- Programmable, in millimeters, with Upper Control Limit & Lower Control Limit.

**Presets:** Welding parameters stored in the controller memory.

**Pressure:** The amount of mechanical pressure supplied to the ultrasonic stack assembly while delivering ultrasonic energy to the components.

**Quality Widows & Limits:** Programmable values used by the system to compare actual process data. Actual process data must be within limits or an alarm be issued.

**Squeeze Time:** The amount of time after the ultrasonic tooling engages the component (s) and before delivery of ultrasonic energy. -- Adjustable from 0 - 2 seconds.

**Stress:** Stress is the amount of dynamic force per cross sectional area.

**Time:** Time is the duration of the ultrasonic, mechanical, activity. Time is a component used to calculate the amount of ultrasonic energy delivered during a weld cycle, (Time = Joules / Watts).

**Tip:** Device specially designed to grip the upper component, to be welded, and to direct the ultrasonic energy into the work piece, (Also Horn Tip & Replaceable Horn Tip).

**Tip Nut:** Device specially designed to securely clamp a replaceable tip onto the horn.

**Trigger Force:** See Force.

**Tuning:** Adjusting to optimize power supply performance according to resonance frequency, especially with regard to the horn and converter.

**Velocity:** The rate of motion at a specific time [velocity = distance time] Also referred to as speed.

# **Chapter 3: Shipping and Handling**

3.1	Shipping and Handling	. 30
3.2	Receiving and Unpacking	. 31
3.3	Returning Equipment	. 32

## 3.1 Shipping and Handling

The Ultraweld L20 Actuator is a system of metal and electro-pneumatic components that move the ultrasonic tooling in the ultrasonic welding system and control aspects of the weld process. Many of its components can be harmed if the unit is dropped, shipped under improper conditions, or otherwise mishandled.

### 3.1.1 Environmental Specifications

The following environmental guidelines should be respected in the shipping of the Ultraweld L20 Actuator unit.

**Table 3.1** Environmental Requirements

Environment	Range
Storage / Shipping Temperature	-13° F to +131° F (-25° C to +55° C)
Humidity	30% to 90% non condensing

## 3.2 Receiving and Unpacking

Branson Metal Welding actuator units are carefully checked and packed before dispatch. It is recommended, however, that you follow the inspection procedure below after delivery.

To inspect the Ultraweld L20 Actuator when it is delivered:

Table 3.2 Receiving and Unpacking

Step	Action		
1	Verify that all parts are complete according to the packing slip.		
2	Check the equipment immediately after delivery to ensure that it has not been damaged during transport.		
3	Report any damage claims to your carrier immediately.		
4	Determine if any component has become loose during shipping and, if necessary, tighten screws.		

NOTICE	
<b>1</b>	If the goods delivered have been damaged during shipping, please contact the forwarding agent immediately. Retain packing material (for possible inspection or for sending back the unit).

CAUTION	Heavy Object
	The Actuator and the Controller are heavy. Handling, unpacking, and installation might require assistance of a colleague or the use of a lifting device.

## 3.3 Returning Equipment

If you are returning equipment to Branson, please call your Branson Representative or Customer Service to receive approval to return goods to Branson.

If you are returning equipment for repair refer to 1.6 Returning Equipment for Repair of this manual, for the appropriate procedure.

# **Chapter 4: Installation and Setup**

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### 4.1 About Installation

This chapter is intended to help the installer with the basic installation and setup of your new Ultraweld L20 system. This chapter will bring the reader to the point at which the system is functionally "ready to weld".

CAUTION	Heavy Object
	The Ultraweld L20 Actuator and related components are heavy. Handling, unpacking, and installation can require help or the use of lifting platforms or hoists.

International safety labels are found on the power supply and actuator. Those that are of importance during installation of the system are identified in the figures in this and other chapters of the welding system manuals.

### 4.2 Handling and Unpacking

If there are any visible signs of damage to the shipping containers or the product, or you later discover hidden damage, take pictures, and NOTIFY YOUR CARRIER IMMEDIATELY. Save the packing material.

- 1. Unpack the Ultraweld L20 components as soon as they arrive. Refer to the following procedures.
- 2. Verify you have all of the equipment ordered. Some components are packed inside other boxes.
- 3. Inspect the controls, indicators, and surfaces for signs of damage.
- 4. Save all packing material. Evaluation systems will be returned using this material.

#### 4.2.1 Unpack the Power Supply

Power supplies are shipped in a cardboard carton. Power supplies weight approximately 36 lbs (16 kg).

- 1. Open the box, remove foam top packing half and lift the power supply out.
- 2. Remove the toolkit(s) and other components shipped with the power supply. These items may be shipped in small, separate boxes, or underneath the power supply in the box.
- 3. Save the packing material; evaluation systems will be returned using this packing material.

### 4.2.2 Unpack the Ultraweld L20 Actuator

CAUTION	Heavy Object
	Equipment exceeds 40 lb. Sling required to lift.

The actuator is assembled and ready to install. L20 Actuators weight approximately 97 lbs (44 kg).

Move the shipping container close to the intended installation location, leave it on the floor.

- 1. Open the top of the cardboard box, remove the insert from the top of the box and set it aside.
- 2. The toolkit, mounting bolts, and converter and/or booster are shipped with the actuator but in separate shipping box(es). Unpack the converter, booster, toolkit and bolts from their packages.
- 3. Save the packing material.

## 4.3 Take Inventory of Small Parts

**Table 4.1** Standard small parts included with Power Supply and/or Actuator

Part or Kit	Description		Comments
11008-09-001	HANDLE, EXTENSION	1	
11008-09-002	SOCKET, 5/8" MODIFIED	1	
X3A50325	SPACER, 6MM	1	
101-118-039	WRENCH SPANNER #0472	1	
211-099	PASTE, MOLYKOTE GN METAL 2.8 OZ	1	
211-205	EMORY, 600 GRIT(SHEET) 00346007	1	
211-206	PAD, METAL FINISH 41028416 MSC	1	Toolkit M1A50A19
211-636	CANVAS BAG W/BRANSON LOGO	1	TOOIRIC MIASOAIS
211-658	SET, ALLEN, 1.5-5MM, HEX:05051628		
211-659	WRENCH HEX ALLEN, 6MM, 88350137	1	
211-660	WRENCH HEX, 8MM,05051925 MSC	1	
48000-03-011	WRENCH, SPANNER	1	
M1A50A42 SHIM, .001		1	
M1A50A45	SPACER, 1MM MSC 81757700	1	
M1A00117	SINGLE PALM BUTTON W/E-STOP	N/A	
M1A00137	.37 FOOTSWITCH ASSEMBLY		
M1A00A10	M1A00A10 DUAL PALM BUTTON ULTRAWELD 20		Optional
M1A00A11	M1A00A11 OPTO-TOUCH START SWITCH ASSY		
211-968	Wrench, 1-3/8 Open End, 1/2 Dr	N/A	

#### 4.3.1 Cables

Three cables connect the power supply and actuator: the analog data cable, the control cable, and the RF cable. If the system is to be automated, you may also need a remote start cable. Check your invoice for cable types and cable lengths.

Table 4.2 List of Cables

EDP number	Description	Comments
101-266-8R	CABLE, ANALOG DATA	EN Compliant Part
101-640-8	CABLE, CONTROL	EN Compliant Part
101-240-177	CBL EXT 15' RF SHLD J931CS CE	EN Compliant when used with Converter 101-135-065
J1A00230	CABLE, AUTOMATION INTERFACE, 10'	



### 4.4 Installation Requirements

#### 4.4.1 Location

The actuator may be installed in a variety of positions. The Ultraweld L20 is often manually operated using a foot switch, and so it can be installed at a safe and comfortable workbench height (approximately 30-36 inches) with the operator sitting or standing in front of the system. The power supply may be located up to 20 feet away from the Ultraweld L20 Actuator.

The power supply must be accessible for user parameter changes and settings, and must be placed in a horizontal orientation. The power supply should be positioned so it does not draw in dust, dirt or material via its rear fans. Refer to the illustrations on the pages that follow for a dimensional drawing of each component.

### 4.4.2 Environmental Specifications

Table 4.3 Environmental Specifications

Environmental concern	Acceptable Range
Humidity	30% to 90%, non-condensing
Ambient Operating Temperature	+5° C to +50° C (41° F to 122° F)
IP Rating	2X
Operating Altitude	1000 m (3280 ft)

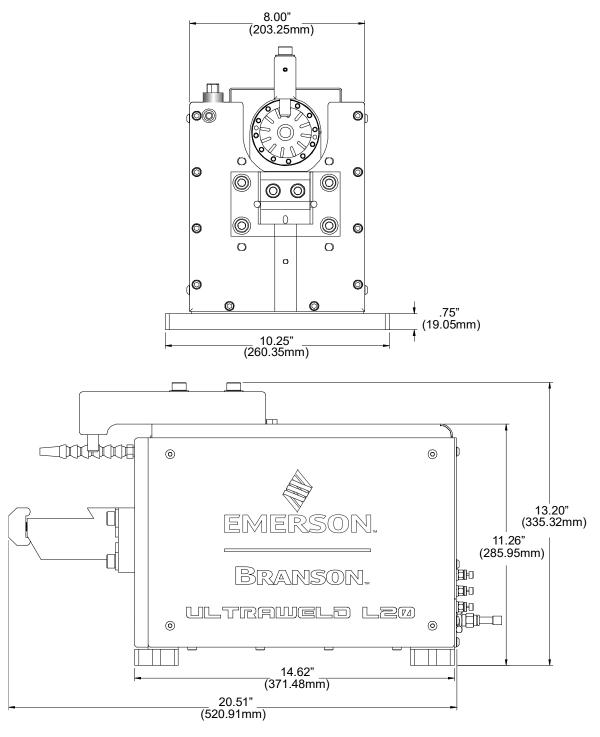
5.0" (127mm) Desired Clearance Air Intake 20.6" 522.9mm Air Outlet is under BRANSON 52.8mm front panel **6** Various Grayelolik 0.58" 13.4" 14.7mm 340.1mm 17.55" 445.8mm BRANSON 5.2" 132.4mm 146mm VersaGraphiX

**Figure 4.1** Power Supply Dimensional Drawing (VersaGraphiX)

5.0" (127mm) Desired Clearance Air Intake 20.6" 522.9mm Air Outlet is under 2." Branson 52.8mm front panel • 0.58" 13.4" 14.7mm 340.1mm 17.55" 445.8mm BRANSON 5.2" 5.75" 132.4mm 146mm 0 О

Figure 4.2 Power Supply Dimensional Drawing (Touch Screen)

Figure 4.3 Ultraweld L20 Actuator Dimensional Drawing



### 4.4.3 Electrical Input Power Ratings

Plug the Power Supply into a single-phase, grounded, 3-wire, 50 or 60 Hz power source. <u>Table 4.4</u> lists the current and fuse ratings for the various models.

**Table 4.4** Input Power requirements

Model	Power	Current Rating	NEMA Connector
	2200 W 200V - 230V	14 Amp Max. @ 200V / 20 Amp fuse	NEMA L6- 20P Plug
20 kHz models	3300 W 200V - 230V	21 Amp Max. @ 200V / 20 Amp fuse	NEMA L6- 20P Plug
	4000 W 200V - 230V	25 Amp Max. @ 200V / 25 Amp fuse	NEMA L6- 30P Plug
	5500 W 3 phase 480V		

#### 4.4.4 Air Cylinder Consumption

The Ultraweld L20 air consumption rate can be estimated using the table below:

Table 4.5 Cubic Feet of air per minute per inch of stroke length (each direction)

Air Pressure (PSI)	10	20	30	40	50	60	70	80
100mm Bore	0.0118	0.0166	0.0214	0.0262	0.0310	0.0358	0.0406	0.0454
63mm Bore	0.0047	0.0066	0.0085	0.0104	0.0123	0.0142	0.0161	0.0180

Add 0.034 cubic foot per minute (CFM) for each second of actual weld time to account for converter cooling air per weld cycle.

#### Example:

The Ultraweld L20 Actuator (100mm Bore) running at full pressure (80PSI) and full stroke length (48mm=1.9") at a cycle of 20 parts per minute. The air consumption (in CFM) will be:

Consumption per stroke = 0.0454 CFM per inch of stroke x 3.8'' (total stroke) = 0.1771 CFM per stroke.

If the weld time is 1 second, we add  $0.034\ \text{CFM}$  of actual weld time to account for converter cooling air per weld cycle.

Consumption per cycle = 0.1771 + 0.034 = 0.2111 CFM per cycle.

Consumption = 0.2111 CFM per cycle x 20 cycles per minute = 4.222CFM.

The example above is to be considered a worse case condition for an Ultraweld L20 Actuator to run at.

#### 4.4.5 Factory Air

The factory compressed air supply must be "clean, dry and unlubricated" air with a regulated maximum pressure of 100 psig (690 kPa). Depending on your application, the actuator requires between 70 to 80 psi. Use a lockout device on the air line if required.

WARNING	General Warning
<u>^</u>	Synthetic air compressor lubricants containing WD-40 or Silicone will cause internal actuator damage and failure due to the solvents contained within these types of lubricants.

#### **4.4.5.1** Pneumatic Connections to Actuator

Air connection to the Ultraweld L20 Actuator is made to the air inlet connector on the rear of the actuator with a quick-connect safety pneumatic coupling. Refer to <a href="#">Chapter 5:</a> <a href="#">Technical Specifications</a> for a pneumatic schematic.

## 4.5 Installation Steps

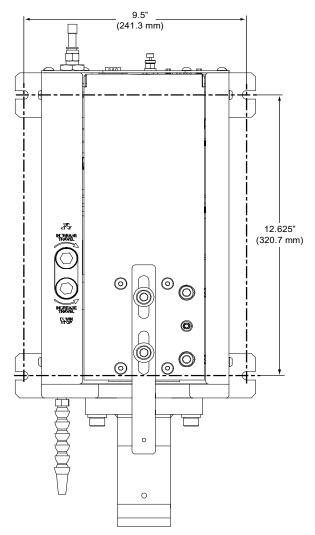
### 4.5.1 Mounting the Ultraweld L20 Actuator (Bench Mounting)

The Ultraweld L20 Actuator must be bolted to your workbench to prevent undesired movement. Open-end slots are provided at the Ultraweld L20 mounting feet, and will accept your 5/16 inch or M8 cap screws.

CAUTION	General Warning
<u> </u>	You must secure the actuator to your work surface using four bolts to prevent undesired movement.

- 1. Mount the Ultraweld L20 Actuator to your workbench using four socket-head cap screws (customer provided, 5/16 inch or M8).
- 2. Connect factory air to the air inlet connector on the rear of the actuator with a quick-connect safety pneumatic coupling

Figure 4.4 Ultraweld L20 Mounting Centers



### 4.5.2 Mounting the Power Supply

The power supply is designed to be placed on a workbench (rubber feet on bottom) within cable length limits of the actuator. It has two rear-mounted fans which draw cooling air from rear to front, which must be free from obstruction. Do not place the power supply on the floor or in other locations that will allow dust, dirt or contaminants to be drawn into the power supply.

The controls on the front of the power supply must be accessible and readable for setup changes (touchscreen models).

All electrical connections are made to the rear of the power supply, which should be positioned in your workspace with adequate clearance (approximately 4 inches or more on either side, and 5 inches to the rear) for cable access and ventilation. Do not place anything on top of the power supply case.

In the event the system is to be installed in a high dust environment, the use of a fan filter kit (101-063-614) is required.

See <u>Figure 4.1</u> and <u>Figure 4.2</u> for dimensional drawing of compatible Power Supplies.

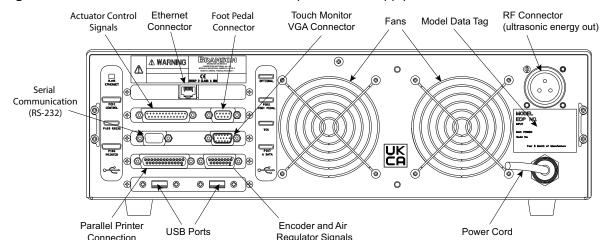
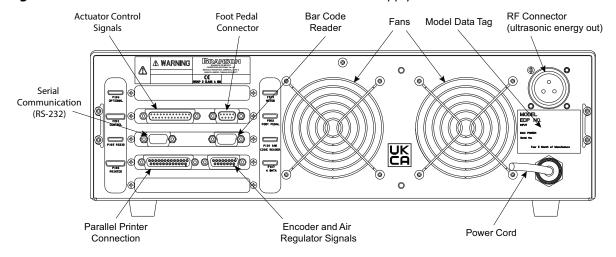


Figure 4.5 Connections on Rear of a VersaGraphiX Power Supply

Figure 4.6 Connections on Rear of a Touch Screen Power Supply



The cable lengths are limited based on the operating frequency of the welding system. Performance and results can suffer if the RF cable is crushed, pinched, damaged or modified. Contact your Branson Representative if you have special cable requirements. In



some cases, remote operation from a User I/O or a Remote Terminal can be used to solve a distance limitation.

#### 4.5.3 Input Power (Main)

The system requires single-phase input power, which you connect to the Power Supply using the integral power cord. See <u>Table 4.4</u> for plug and receptacle requirements for your specific power level.

Refer to the unit's Model Data Tag to be sure of the power rating of the Model in your system.

### 4.5.4 Output Power (RF Cable)

Ultrasonic Energy is delivered to a screw-on MS receptacle connection on the rear of the Power Supply, which is connected to the Ultraweld L20 Actuator.

WARNING	General Warning
<u></u>	Never operate the System with the RF Cable disconnected or if the RF Cable is damaged.

#### 4.5.5 Interconnect Between Power Supply and Actuator

The Ultraweld L20 Actuator has three electrical connections between the Power Supply and the Actuator: the RF Cable, the Analog Data Cable, and the Control Cable.

There can be other connections to the Actuator, and other connections to the Power Supply, but these are the three standard connections, depicted in Figure 4.7.

Ultraweld L20 Actuator Rear View J931CS RF Cable Connect cooling air hose 0 **O** • Power Cord Power Supply Rear View Analog Data Cable Control Cable

Figure 4.7 Electrical Connections from Power Supply to an Ultraweld L20 Actuator



## 4.6 Safety Devices

The removal, bridging or disabling of safety devices is not condoned for production operation. Individual safety devices mentioned below may only be disabled if super-ordinate safety devices are employed in their place.

### 4.6.1 Emergency Stops

In case of danger, hit the red, emergency stop Which is found on the red, top portion of the foot pedal. Twist the emergency stop to reset the system. The actuator, power supply, and related fixtures are returned to the "Home" position. If dual anti-tie start buttons are used, there must be a red emergency stop associated in line. Free access to the emergency stop button must be maintained.

#### 4.6.2 Actuator Covers

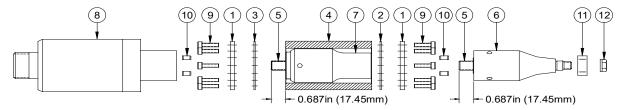
The Ultraweld L20 Actuator is equipped with covers which should only be removed for maintenance and installation purposes.

## 4.7 Ultrasonic Stack Assembly

Refer to Figure 4.8 for item listings when assembling the ultrasonic stack.

- 1. Apply an even, light coat of Molykote G-n paste (about equal in size to half a paper match head) to the mating surfaces of the Converter, Booster and Horn. Do NOT apply paste to threaded opening or to stud threads or to diaphragm. Do NOT use silicone grease.
- 2. Place the Rear Diaphragm Spring (Item 3 0.500" diameter center hole) and Clamp Ring (Item 1) onto the studded end of the Booster (Item 7). Then thread the Booster into the Converter. Be careful to center the Diaphragm Spring on the Booster and then torque Booster and Converter to 55 ft/lbs (74.6 N-m) using two spanner wrenches. Do not clamp on the Converter.
- 3. Slide the Booster/Converter subassembly in through the rear of the polar shell. Assemble the twelve M5 SHCS's to fasten in an alternating pattern the Clamp Ring to the rear of the polar shell.
- 4. Place a Clamp Ring and the Front Diaphragm Spring (Item 2 0.750" diameter center hole) onto the studded end of the Horn (Item 6). Then thread the Horn into the Booster. Assemble the twelve M5 SHCS's to fasten in an alternating pattern the Clamp Ring to the front of the polar shell. Be careful to center the Diaphragm Spring on the Horn and then torque Booster and Horn to 80 ft/lbs (108.5 N-m).
- 5. Install the replaceable tip and loosely thread on the tip nut (applicable to replaceable Tip Horns only). The Tip (or Horn blade) will have to be made square and parallel to the Anvil prior to welding.

Figure 4.8 Exploded Ultrasonic Stack Assembly



ITEM	DESCRIPTION
1	CLAMP RING
2	DIAPHRAGM SPRING, FRONT
3	DIAPHRAGM SPRING, REAR
4	POLAR SHELL
5	1/2-20 STUD
6	HORN

ITEM	DESCRIPTION
7	BOOSTER
8	CONVERTER (105 STYLE)
9	SOCKET HEAD CAP SCREW
10	DOWEL PIN
11	TIP
12	TIP NUT

WARNING	General Warning
<u>\( \)</u>	Do not operate ultrasonics while the tip is loose.

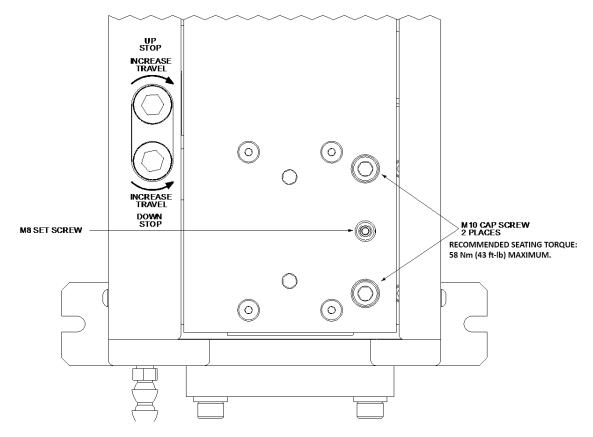
WARNING	General Warning
<u> </u>	Do not operate ultrasonics without connecting the converter lead wire and ground.

#### 4.7.1 Installing the Stack in the Actuator

The ultrasonic stack must first be assembled. To install the stack:

- 1. Make sure that the system power is turned off by disconnecting the power plug.
- 2. Loosen the two M10 screws on top of the polar block.
- 3. Insert the stack into the polar block. Note: If the stack does not fit into the polar block, tighten the spreading M8 set screw located in between the clamping screws.
- 4. Adjust the stack to the desired position.
- 5. If the spreading set screw has been tightened to loosen the stack, unscrew it to achieve clamping of the stack.
- 6. Tighten the two M10 screws on top the polar block in an alternating pattern to achieve equal clamping force.
- 7. Re-check position of the stack relative to the tooling surface.
- 8. Adjust stack accordingly to achieve proper alignment.

Figure 4.9 Mounting the Stack on the Ultraweld L20 Actuator

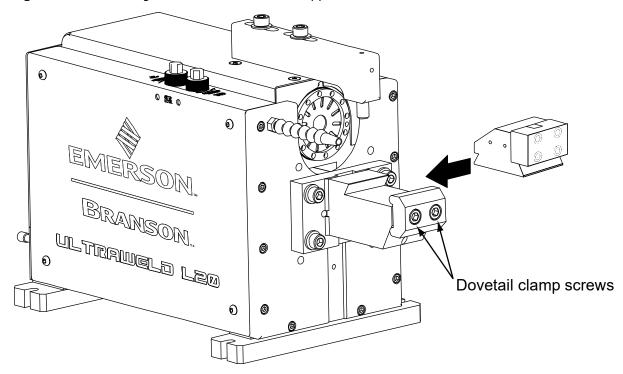


## 4.8 Mounting the Fixture on the Tool Support

The Ultraweld L20 Actuator allows for quick tooling installation by means of a dovetail mounting design. To install your fixture onto the tool support:

- 1. Loosen the two dovetail clamp screws.
- 2. Slide the anvil onto the tool support.
- 3. Tighten the two dovetail clamp screws.

Figure 4.10 Mounting the Fixture on the Tool Support



## 4.9 Testing the Installation

- 1. Turn on the air supply connections.
- 2. Ensure there are no leaks in the air supply connections.
- 3. Turn on the power supply. The power supply will begins its normal self-check.
- 4. Make sure the horn is in the up position and is not in contact with any object.
- 5. Go to the Maintenance screen for VersaGraphix or the Maintain button for Touch Screen Controller.
- 6. Go to Sonic screen and push test button, the horn should vibrate while the button is pushed.
- 7. In the screen that follows, select the key that corresponds to Cal Actuator.
- 8. If the power supply goes into overload please contact Branson Customer service. If the horn does vibrate make sure R.F. cable is connected and try again.
- 9. Fit a test part onto the fixture.
- 10. Press the foot-pedal or the start switches to make a weld.

In summary, if the power supply does not display an alarm message and the actuator descends and retracts correctly, your ultrasonic welder is ready for operation.

## 4.10 Still Need Help?

Branson is pleased that you chose our product and we are here for you! If you need parts or technical assistance with your Ultraweld L20 system, call your local Branson representative or contact Branson Customer Service. See <u>1.6.4 Contact Information</u>.

## **Chapter 5: Technical Specifications**

5.1	Technical Specifications	. 54
5.2	Physical Description	. 55

## **5.1** Technical Specifications

#### **5.1.1** Requirement Specifications

The Ultraweld L20 Actuator requires compressed air. The factory air source must be "clean and dry air", that is, without moisture or lubricants. The Actuator requires 70 psi minimum pressure for operation and cooling, and can require up to 80 psi maximum, depending on the application. The following table lists environmental specifications for the ultrasonic welder. The following table lists environmental specifications for the ultrasonic welder.

Table 5.1 Environmental Specifications

Environment	Range
Humidity	30% to 90% non condensing
Ambient Temperature	+5° C to +40° C (+41° F to +104° F)
Storage / Shipping Temperature	-13° F to +131° F (-25° C to +55° C)
Operating Altitude	1000 m (3280 ft)
IP Rating	2X

All electrical input power connections are to the Power Supply.

#### **5.1.2** Performance Specifications

The following table details some of the performance specifications associated with the Ultraweld L20 Actuator.

**Table 5.2** Ultraweld L20 Actuator Performance Specifications

Height Encoder Accuracy	±0.05mm (0.002 in)
Maximum Stroke	48mm / 1.9 in

## **5.2** Physical Description

Refer to Chapter 4: Installation and Setup for dimensional information.

#### 5.2.1 Standard Items

#### Slide Mechanism

The slide system is based on a precision roller bearing slide which provides precise alignment of the anvil, smooth linear motion and long term reliability.

### **Mechanical Stops**

The Ultraweld L20 Actuator has two mechanical stops to limit the horn travel: the down stop and the up stop.

The down stop is used as a safety to prevent contact between the Horn and Anvil if the welder is cycled without the part(s) to be welded.

The up stop is used to limit the upward travel of the horn. Two examples for the use of the up stop are limiting the upward travel to quicken cycle times and for easier loading and unloading of components.

#### **Polar Shell & Ultrasonic Stack**

The converter-booster-horn assembly, or ultrasonic stack, is supported in a steel polar shell by means of two diaphragm springs. The diaphragm springs are mounted at either end of the booster and are securely bolted to the polar shell. The diaphragm shaped springs are made from titanium and are acoustically tuned at the 20 kHz operating frequency. This system permits efficient transmission of ultrasonic vibration along the axis of the ultrasonic stack while providing rigid mounting.

#### **Linear Encoder**

The linear encoder measures the distance traveled by the horn. Depending on the weld mode settings, it can:

- Weld in height mode
- Weld in energy with height compensation
- Inspect the height of the parts to be joined (pre-height)
- Inspect the height of the parts after being welded (height)

### **Tool Support**

The Ultraweld L20 tool support allows for quick tooling installation by means of a dovetail mounting design.

## **Pneumatic System**

The pneumatic system is contained within the actuator's enclosure. Refer to Figure 5.1.

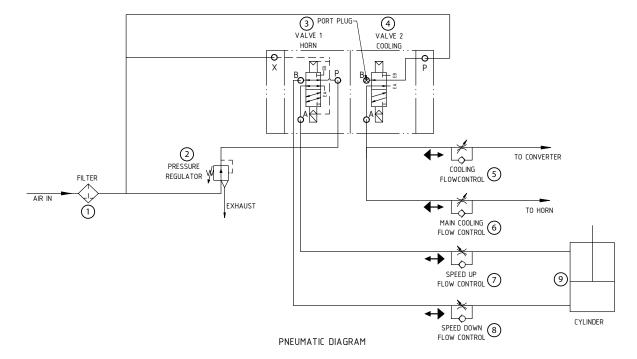
The system consists of:

- 1. A cooling solenoid valve.
- 2. A horn solenoid valve.
- 3. A pressure regulator.
- 4. A quick exhaust valve.

- 5. An air cylinder.
- 6. A down speed flow control valve.
- 7. An up speed flow control valve.
- 8. A main cooling flow control valve.
- 9. A converter cooling flow control valve.

The horn's rate of descent (Down Speed); the horn's rate of ascent (Up Speed); and the main cooling flow (Cooling) are adjusted at the back. The converter's cooling flow is adjusted on the control valve located inside the actuator.

Figure 5.1 Ultraweld L20 Actuator Pneumatic Schematics



# **Chapter 6: Operation**

6.1	Actuator Controls	58
6.2	Initial Actuator Settings	59
6.3	Operating the Actuator	64
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### **6.1** Actuator Controls

This section describes how to operate a weld cycle using the Ultraweld L20 Actuator. For more detailed information on making and altering settings, refer to your Power Supply Manual.

CAUTION	General Warning
	Keep hands away from under the horn when setting up and operating the Actuator. Down force (pressure) and ultrasonic vibrations can cause injury.

The Ultraweld L20 Actuator is controlled by the Power Supply. The Actuator sends operating cycle data, and status information to the power supply. The Power Supply sends operating parameters to the Actuator, determining how and when cycles are initiated and terminated. Refer to your Power Supply manual for tuning testing, setup and operating instructions.

## 6.2 Initial Actuator Settings

The Ultraweld L20 Actuator is controlled by the Power Supply, however there are several functions that are part of the Actuator. These include:

- · Factory air source
- Down speed control
- Up speed control
- · Cooling air
- Down stop
- Up stop

Each of these will affect the operation of the actuator.

#### 6.2.1 Factory Air Source

Factory air must be turned on, supplying the actuator's air pressure regulator with air pressure. If factory air is too low (below 70 psi maintained) the actuator will not weld or operate reliably. Factory air is also used to provide cooling air to the converter.

Factory air input may affect weld results for applications requiring more weld pressure buildup.

NOTICE	
<b>f</b>	Factory air pressure must be higher than the maximum system requirements. The compressed air system must have sufficient capacity to serve all of the systems connected to it. The use of an accumulator may be required to provide continuous air flow.

### **6.2.2 Down Speed Control**

The Speed Down knob, located on the rear of the actuator, controls the downward speed of the ultrasonic stack. This is useful to prevent damaging the parts to be welded, increasing/decreasing cycle times to get better weld results.

To DECREASE the downward speed, turn the indicated knob clockwise.

To INCREASE the downward speed, turn the indicated knob counter-clockwise.

#### 6.2.3 Up Speed Control

The Speed Up knob, located on the rear of the actuator, controls the upward speed of the ultrasonic stack. This is useful for raising the stack quickly for other mechanism actions and for quick part removal.

To DECREASE the upward speed, turn the indicated knob clockwise.

To INCREASE the upward speed, turn the indicated knob counter-clockwise.

#### 6.2.4 Cooling Air

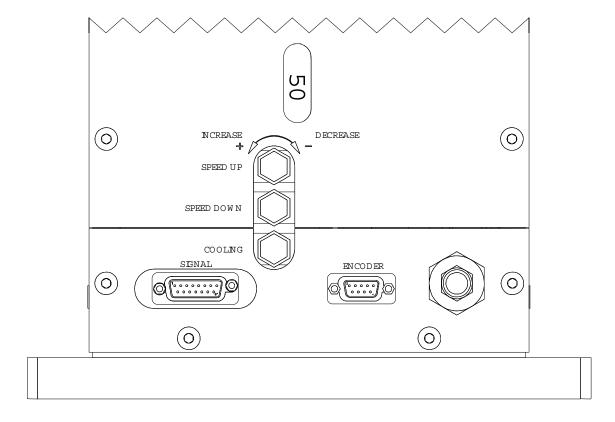
The Cooling knob, located on the rear of the actuator, controls the flow of air delivered to the front nozzle. Cooling air is designed to keep the weld cooled to a reasonable temperature during welding.

To INCREASE cooling air flow rate, turn the cooling air control knob counter-clockwise.

To DECREASE cooling air flow rate, turn the cooling air control knob clockwise.

CAUTION	General Warning
	Compressed airflow should be directed away from the operator at all times.

Figure 6.1 Speed Controls and Cooling Knob Location



## 6.2.5 Down Stop Adjustment

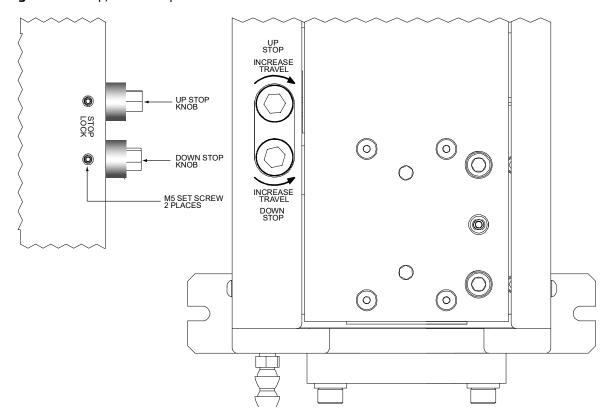
The down stop is used as a safety mechanism to prevent contact between the Horn and Anvil if the welder is cycled without the part(s) to be welded. Unless otherwise specified, a 0.004'' (0.10 mm) gap between the Horn and Anvil is recommended. See <u>Figure 6.2</u> for the Down Stop location.

NOTICE	
1	Some applications require no down stop due to thickness of the material.

To adjust the down stop:

- 1. Loosen the forward set crew (located on the left side facing the front of the actuator) so that the down stop knob moves smoothly.
- 2. Turn the Down Stop Knob clockwise to increase the maximum downward travel end position.
- 3. Turn the Down Stop Knob counter-clockwise to decrease the maximum downward travel end position.
- 4. Tighten the forward set screw when the desired down travel location is achieved.

Figure 6.2 Up/Down Stop Knob Locations



## 6.2.6 Up Stop Adjustment

The up stop is used to limit the upward travel of the Horn. Two examples for the use of the up stop are limiting the upward travel to quicken cycle times and for easier loading and unloading of components. See <u>Figure 6.2</u> for the up stop location.

To adjust the up stop:

- 1. Loosen the rearward set screw (located on the left side facing the front of the actuator) so that the up stop knob moves smoothly.
- 2. Turn the Up Stop Knob clockwise to increase the maximum upward travel end position.
- 3. Turn the Up Stop Knob counter-clockwise to decrease the maximum upward travel end position.
- 4. Tighten the rearward set screw when the desired upward travel location is achieved.

CAUTION	General Warning
	Increasing the Up Stop gap too much can result in an unsafe weld condition (pinch point). The Up Stop travel distance should be kept to an absolute minimum for safety reasons.

#### **6.2.7** Torque Check

Proper tightness of tooling is critical to assure efficient transmission of ultrasonic energy into the weld nugget. Please check the tightness of the following areas during a tool change or whenever looseness is suspected.

Table 6.1 Tooling Torque

Area	Suggested Torque
Horn to Booster	
Solid Blade Horn to Booster	80 ft/lbs (108 N.m)
Replaceable Tip Horn to Booster	100 ft/lbs (135 N.m)
Converter to Booster	55 ft/lbs (75 N.m)
Tip Nut (if used)	70 ft/lbs (95 N.m) (Unless Otherwise Specified)

#### 6.2.8 Emergency Stop

The emergency stop is found on the red, top portion of the foot pedal. When engaged it will prevent the actuator from running, and will also immediately terminate a weld cycle and cause the actuator to return to its "Home" position. It does not remove power from the system. The power supply will indicate that the system is in emergency stop mode and emit a beep sound when the emergency stop is engaged. Push the emergency stop foot pedal to reset the system.

#### **6.2.9 Tool Gap Requirements**

Tooling includes the Horn (or Horn Tip), Anvil and all surfaces that contact the weld nugget during processing. The tooling should be inspected to confirm a gap as per the application tooling set up sheet. If the tooling is in contact during the application of ultrasonic energy, severe damage may result to the tooling and power supply.

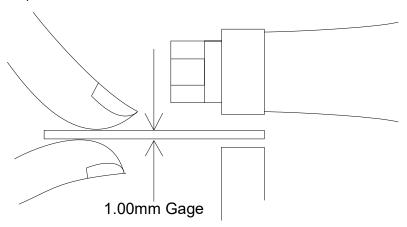
NOTICE	
6	This test should be checked whenever the tooling is changed. Also perform this test whenever you suspect tool contact.

NOTICE	
1	Most tooling that contacts the weld nugget is designed with several weld surfaces. When one surface is worn and no longer useful, an alternate surface may be used resulting in extended tool life.

#### To set the Tool Gap:

- 1. Set the air regulator at the same pressure as the weld pressure.
- 2. Ensure that there are no work pieces between the Horn and Anvil.
- 3. Navigate to the Maintenance menu on the power supply, then press the HORN button. This will cause the Horn to descend to its stop.
- 4. Measure this crash gap as per the application tooling setup sheet.
- 5. Press the HORN button again to raise the Horn and adjust the down stop screw located on the top of the actuator.

Figure 6.3 Tool Gap



The Branson Ultraweld L20 is capable of accurate height measurements and can adjust for weld pressure and crash gap settings. All tool setups especially crash gap must be complete before this procedure.

## **6.3** Operating the Actuator

For detailed information about Ultraweld L20 Actuator controls, refer to 2.4 Controls

#### 6.3.1 Check Welder Performance

Ensure that nothing is touching the tip on all four sides. With the tooling disengaged and unloaded, press the "TEST" button on the power supply for no longer than one second. If there is a loud squealing noise, the problem may be in the following areas:

- 1. The Tip may not be secured properly.
- 2. The Horn may not be secured properly.
- 3. Tooling may be in contact with each other.

NOTICE	
6	For information on locating the "TEST" button on your particular Power Supply model please refer to your Power Supply manual.

#### **6.3.2 Establishing Weld Parameters**

With the tooling properly set up and with the ultrasonic stack tuned, welding may be performed. Optimize the weld settings in the following manner:

NOTICE	
<b>f</b>	Weld parameters may already be established. Refer to Parameter Preset Information located in the Special Information Section.

- 1. Set weld energy and pressure for initial weld trials to minimum values: 50 joules and 15 PSIG for air pressure as a starting point.
- 2. Place the parts to be welded securely into the fixture.
- 3. Cycle the welder by actuating the foot switch or the start switches.
- 4. Inspect the welded joint.
- 5. Increase/decrease the values for energy, and air pressure as necessary to reach an acceptable level of welding.

### **6.3.3 Knurl Pattern Imprint Evaluation**

The imprint that the tooling creates on the interface is a result in the aligning the welding tip to the anvil. If the weld appears heavy to a certain side, readjustment of the tooling will be required to get even weld results across the weld surface. Typically, using carbon paper will give the best results. Figure 6.4 shows what typical imprints will look like and the corrective action to be taken

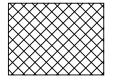


Figure 6.4 Knurl Pattern Imprint Evaluations

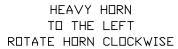
#### CARBON PAPER IMPRINT

ANVIL SURFACE

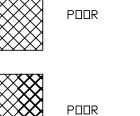
EVEN PARALLEL PATTERN SQUARE AND PARALLEL



GOOD

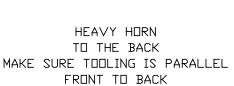


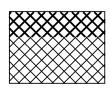




HORN ORIENTATION

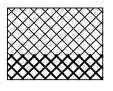
HEAVY HORN TO THE RIGHT ROTATE HORN COUNTER-CLOCKWISE





POOR

HEAVY HORN
TO THE FRONT
MAKE SURE TOOLING IS PARALLEL
FRONT TO BACK



POOR

BE SURE TO SET AND TIGHTEN TOOLING AND POLAR SHELL CLAMP

## **6.4 Safety Circuit Alarms**

The Safety Control System within the Controller constantly monitors the system's safety related components for correct operation. When this system detects a fault condition, operation is interrupted and the system immediately goes to a safe state. A beeper is used to signal a safety system alarm.

Use the following procedure to troubleshoot safety circuit alarms:

- 1. Verify that the 9-pin footswitch cable is properly connected to the back of the Controller.
- 2. Power down and then power up the Controller to reset the system.
- 3. If the alarm persists, call Branson Support. See <u>1.6.4 Contact Information</u>.

# **Chapter 7: Maintenance**

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#### 7.1 Periodic and Preventive Maintenance

#### 7.1.1 Maintenance Safety

Safety devices, especially covers, guards and ground cables should only be removed when it is absolutely essential for the completion of maintenance work. If safety devices were removed prior to starting maintenance work, be sure to re-install those devices after finishing the maintenance work. The following installation and maintenance operations must be performed prior to any disassembly of equipment:

WARNING	General Warning
<b>A</b>	Use LOTO (Lock Out Tag Out) lockable plug cover over line cord plug during any maintenance
	All system components must be disconnected from the main electrical supply
	Remove the plug from the main electrical supply and secure it from being re-inserted accidentally
	All system components must be disconnected from the main air supply
	Disconnect the air hose from the main air supply and release system air pressure via the pressure regulator

#### 7.1.2 Periodic Maintenance

In order to maintain optimum operating conditions, it is important to perform various maintenance and equipment inspections at periodic intervals. Please observe the following recommendations.

#### 7.1.2.1 Daily Maintenance:

• Drain water and contaminants from the airline filters, if required

#### 7.1.2.2 On Every Tool Rotation

- Inspect the clamping surfaces of the Tip, the Tip Nut and the Horn for fretting
- Vacuum and clean out any copper residue or dirt in the actuator

#### 7.1.2.3 After 40k-50k Cycles Maximum (subject to change based on weld application):

- Vacuum and clean inside of power supply
- Calibrate pressure regulator
- Clean and torque the stack interface
- Calibrate amplitude

### 7.1.3 Recondition the Stack (Converter, Booster, and Horn)

The transmission of ultrasonic energy along the stack requires a tight and clean interface between the Converter, Booster, Diaphragm Springs and Horn.

NOTICE	
1	Remove the stack and check the interfaces after 40k-50k cycles or whenever a problem is suspected.

#### 7.1.3.1 Ultrasonic Stack Disassembly

WARNING	High Voltage Hazard
4	Be sure that the power supply is off to prevent any possible electrical shock from the high voltage contact on the converter.

- 1. Disconnect the cable at the rear of the Converter (Item 8).
- 2. Remove the Tip Nut and Tip (applicable to replaceable tip horns only). Check the Tip and Nut to be sure that the clamp surfaces are clean and smooth. Follow the instructions in 7.1.3.3 Reconditioning Tip and Nut Clamping Surfaces (Replaceable Tip Horns Only).

NOTICE	
1	Clean only the clamp surface, not the knurl area.

- 3. Using the torque wrench and the Torque Wrench Adapter, remove the Horn (Item 6) from the Stack Assembly.
- 4. Remove the twelve M5 SHCS's (Item 9), the Clamp Ring (Item 1) and the Front Diaphragm Spring (Item 2).
- 5. Remove the twelve M5 SHCS's (Item 9) from the back end of the Polar Shell (Item 4).
- 6. The Converter (Item 8), Clamp Ring (Item 1), Rear Diaphragm Spring (Item 3) and Booster (Item 7) can now be slipped out of the Polar Shell (Item 4) towards the rear of the actuator.

Figure 7.1 Ultrasonic Stack Assembly.

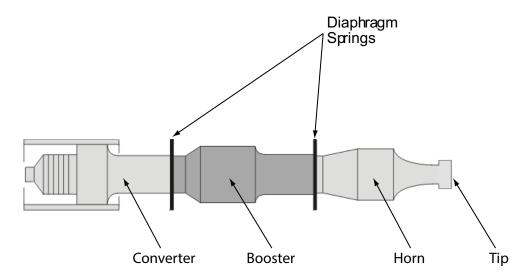
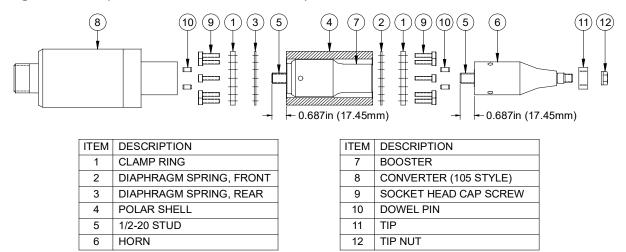


Figure 7.2 Exploded Ultrasonic Stack Assembly

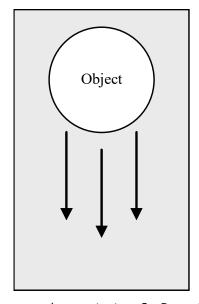


7. With two spanner wrenches carefully separate the Booster from the Converter. Check and clean the mating surfaces of these components with an oilstone or 600-grit paper as shown below.

Place 600 grit emery on a hard, flat surface. Place component on emery with the mating side you wish to clean face down.

Do not press down. Using only the weight of the converter, booster, or horn as downward pressure, drag the component across the emery in a single, straight, long stroke (Figure 7.3).

Figure 7.3 Cleaning object mating surface direction



Turn the component 90 degrees and repeat step 2. Repeat this procedure until all mating surfaces are clean.

- 8. Clean and then polish away any roughness on the Diaphragm Spring.
- 9. Assemble the stack per the steps in the next section.

#### 7.1.3.2 Ultrasonic Stack Assembly

NOTICE	
1	See <u>Figure 7.2</u> for item listings.

- 1. Clean Horn, Converter, Booster and diaphragm surfaces with solvent to remove all contaminants and previously used paste.
- 2. Apply an even, light coat of Molykote G-n paste (about equal in size to half a paper match head) to the mating surfaces of the Converter, Booster and Horn. Do NOT apply paste to threaded opening or to stud threads or to diaphragm. Do NOT use silicone grease.
- 3. Place the Rear Diaphragm Spring (Item 3 0.500" diameter center hole) and Clamp Ring (Item 1) onto the studded end of the Booster (Item 7). Then thread the Booster into the Converter. Be careful to center the Diaphragm Spring on the Booster and then torque Booster and Converter to 55 ft/lbs (74.6 N-m) using two spanner wrenches. Do not clamp on the Converter.
- 4. Slide the Booster/Converter subassembly in through the rear of the Polar Shell. Assemble the twelve M5 SHCS's to fasten in an alternating pattern the Clamp Ring to the rear of the Polar Shell.
- 5. Place a Clamp Ring and the Front Diaphragm Spring (Item 2 0.750" diameter center hole) onto the studded end of the Horn (Item 6). Then thread the Horn into the Booster. Assemble the twelve M5 SHCS's to fasten in an alternating pattern the Clamp Ring to the front of the Polar Shell. Be careful to center the Diaphragm Spring on the Horn and then torque Booster and Horn to 80 ft/lbs (108.5 N-m).
- 6. Replace the Tip and loosely thread on the Tip Nut. (applicable to replaceable Tip Horns only) The Tip (or Horn blade) will have to be made square and parallel to the Anvil prior to welding.

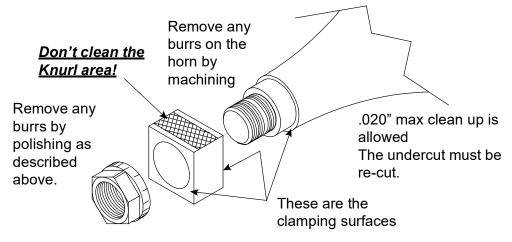
CAUTION	General Warning
	Do not operate ultrasonics while the tip is loose.

#### 7.1.3.3 Reconditioning Tip and Nut Clamping Surfaces (Replaceable Tip Horns Only)

After prolonged use, burrs may form on the clamping surfaces of the tooling. These burrs may be removed from the Tip and Tip Nut by polishing with 600 grit emery paper placed on a flat surface. With light pressure, polish the clamp faces in a Figure 7.3 pattern.

The burrs on the horn clamping surface must be removed by machining back the Horn clamp surface. The least amount of material should be removed, but in no case should more than .020" be removed. The undercut at this clamping surface must also be re-cut

Figure 7.4 Reconditioning Tip and Nut Clamping Surfaces



CAUTION	General Warning
<u>^</u>	In no case should more than .020" of material be removed from the Horn clamp surface.

#### 7.1.3.4 Lubrication Schedule

Actual lubrication interval is under the influence of each application and environment.

NOTICE	
1	When re-mounting the slide block to the rail for any reason, care must be taken to avoid dislodging rollers from the tracks within the slide block.

Branson recommends the following schedule as an initial plan to follow:

## After 1 month of normal operation:

- 1. Inspect interior of actuator for possible grease discharge.
- 2. Re-lubricate slide with specified grease until slide reservoir is full (minimum of 0.6 CC).
- 3. Allow full travel of the slide unit inside the actuator.
- 4. Cycle the slide 10-20 to re-circulate the grease.

## After 3 months of normal operation:

- 1. Inspect interior of actuator for possible grease discharge.
- 2. Re-lubricate slide with specified grease until slide reservoir is full (minimum of 0.6 CC).
- 3. Allow full travel of the slide unit inside the actuator.
- 4. Cycle the slide 10-20 to re-circulate the grease.



### After 6 months of normal operation:

- 1. Remove slide assembly from actuator.
- 2. Inspect the slide block and rail for damage or unusual wear.
- 3. Re-lubricate slide with specified grease until slide reservoir is full (minimum of  $0.6\ CC$ ).
- 4. If slide is damaged or wear is apparent, contact your Branson Representative or Branson Customer Service.
- 5. Using a setup rail (Branson #105-355); slide the block the full length of the rail 5-10 times manually to re-circulate the rollers through the grease reservoir.
- 6. Re-assemble the slide assembly within the actuator.
- If, after the 1st and 2nd inspections, the slide grease is abnormally low, has discoloration, or there is dust/dirt in the slide block, more frequent inspections will be required.

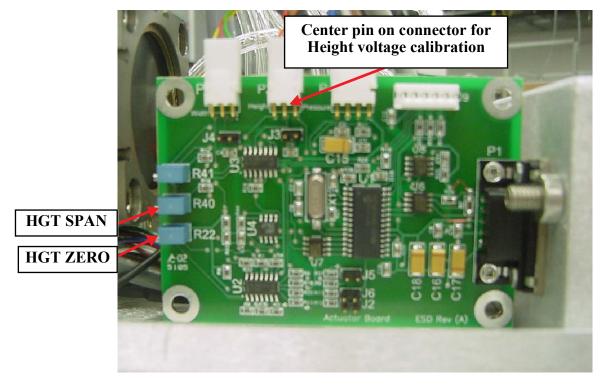
### 7.2 Calibration

This product does not require scheduled calibration. However, if you are operating under requirements that mandate periodic calibration, for example, the FDA's Good Manufacturing Practices, contact your Branson representative for additional information.

#### 7.2.1 Encoder Board Calibration

Encoder board calibration is factory set and generally does not need to be changed. Any calibration required due to tool wear or adjustment is built into the controller software and may be accomplished using touchscreen commands (refer to your power supply manual). If a new encoder board is installed it will be necessary to calibrate Height as follows.

Figure 7.5 Encoder Board Calibration



#### 7.2.1.1 Height Zero and Span Adjustment

- 1. From the Controller Maintenance Screen, enter the Height Calibration Screen.
- 2. Press **HORN** button to lower the horn.
- 3. Remove the top cover from the actuator and locate the actuator board.
- 4. Read voltage that is displayed on controller screen.
- 5. Voltage should read between +2 to +50 millivolts DC. If not, adjust the HGT ZERO (R22) potentiometer (see Figure 7.5) until the voltmeter reads between +2 to +50 millivolts DC (voltage must be positive).
- 6. From the Controller Maintenance Screen, raise the horn (press HORN button).
- 7. Adjust R40 until the displayed Calibrated Height reaches approximately 2300 mV and stop turning R40 to set the maximum value.

#### 7.2.1.2 Height Zero and Span Adjustment (alternate)

- 1. Verify that R22 (102-242-632R Board) is adjusted fully clockwise.
- 2. From the Main screen, press MAINTAIN.
- 3. Press HEIGHT
- 4. Adjust R40 until the displayed Calibrated Height reaches approximately 1974 mV and stop turning R40 to set the maximum value.
- 5. Using the L-Tool, press the encoder shaft down until it stops at the bottom.
- 6. Verify that the displayed Calibrated Height is between 2 mm to 8 mm.
- 7. Slowly let the encoder shaft rise with the L-Tool.

#### 7.2.1.3 Height Calibration

CAUTION	General Warning
<u>^</u>	Read all steps completely and exercise caution as tooling moves during the calibration process.

- 1. Position a 1 mm shim on the tip.
- 2. From the controller press CALIBRATE. The horn comes down 8 times on the 1 mm shim. "Calibration Step 1 done" message is displayed.
- 3. Position a 6 mm shim on the tip.
- 4. From the controller press CALIBRATE. The horn comes down 8 times on the 6 mm shim. "Calibration done" message is displayed. If message "Unsuccessful Calibration" is displayed, repeat steps 1 through 4.

## 7.3 Troubleshooting

This section shows how to fix some of the possible errors and problems which may occur in normal use of the Ultraweld L20 welding system.

#### 7.3.1 Weld Overload

Weld overloads are premature shut downs of the power supply. Overloads signify excessive loads and must be corrected if continued reliability of the equipment is to be maintained. Hardware internal to the power supply are controlling this function and it can not be defeated.

The control system analyzes the end of weld characteristics to check for overloads. If the system determines an overload an alarm occurs. The control halts action until the system is reset.

Some of the possible causes for overloads are:

- The tool clearances are too small, horn and anvil touch during welding
- Excessive air pressure with low amplitude
- · Defective Stack assembly
- Defective Power Transistors in power supply

#### 7.3.2 Low Air Pressure

The control system and its components were designed to run with a clean air supply of from 90 to 100 psi. The control system monitors the air pressure from the low air pressure switch (optional). The low pressure threshold is set from the controller. An alarm occurs when incoming line pressure the drops below the set pressure.

### 7.3.3 Ready Check

The system undergoes a Ready Check operation at every startup, the end of every weld, and at the exit of Setup mode. This procedure checks the height encoder position. If an incorrect height value is returned, an alarm occurs.

Some of the possible causes of a Ready Check alarm are:

- The horn is stuck in the closed position
- Maintenance has moved the height encoder to an out of limit condition
- · Defective encoder or electronics
- Encoder not plugged into its connector

### 7.3.4 Troubleshooting Chart

Table 7.1 Troubleshooting

Problem	Solution
System will not turn on.	<ul> <li>Power cable plugged in</li> <li>Power turned on at the outlet</li> <li>Check internal fuses on the Controller Line Board</li> </ul>
Plant fuse fails or circuit breaker trips when plugging the unit into an electrical outlet.	<ul><li>Inspect power cord, replace if shorted</li><li>Check line filter, replace if failed</li></ul>

Table 7.1 Troubleshooting

Problem	Solution	
Plant fuse fails or circuit breaker trips during weld cycle	Check current rating of the plant fuse or the circuit breaker, replace if failed	
Line fuse fails	<ul><li>Check fuse current rating, replace if incompatible</li><li>Check fan motor, replace if failed</li></ul>	
Horn will not move down or up	<ul><li>System not connected to air supply</li><li>Air not turned on</li></ul>	
Get Emergency Stop when system is turned on	<ul> <li>Check Emergency Stop Switch</li> <li>All cables properly connected</li> <li>Twist red switch on foot pedal (if system is equipped with one)</li> </ul>	
No Sonics when test button is pressed	<ul> <li>RF Cable connected</li> <li>Check RF cable for broken wire</li> <li>Ribbon cable in power supply between SPM and programmer unplugged</li> </ul>	
No sonics during weld cycle	<ul> <li>Check all cable connections</li> <li>Check start cable for broken wires</li> <li>Check inside power supply for loose start cable from rear of unit to programmer board</li> <li>Check thermal switch in power supply</li> </ul>	
Overloads when welding	<ul> <li>Stack not tuned properly</li> <li>Tooling not set up properly</li> <li>Crash gap not set properly</li> <li>Tip nut cracked, replace if needed</li> <li>Check weld parameters</li> <li>Check stack interfaces for fretting</li> <li>Check for loose or failed horn or booster, tighten or replace as necessary</li> </ul>	
When touching the system you get a slight electrical shock	<ul><li>Inspect power cord, replace if needed</li><li>Inspect system ground, repair if needed</li></ul>	
Tooling heats up after machine runs a while	<ul><li>Cooling air is not turned on or is not on long enough</li><li>Cooling air is not directed at tooling</li></ul>	
Low weld strength	<ul> <li>Check weld parameters</li> <li>Check tooling gaps</li> <li>Check knurl on tooling</li> <li>If worn replace tooling</li> <li>Increase Energy</li> <li>Check the Down stop adjustment</li> <li>Check for part contamination</li> <li>Ensure all hardware is tight</li> </ul>	

**Table 7.1** Troubleshooting

Ducklan		
Problem	Solution	
Excessive welding	<ul> <li>Reset parameters</li> <li>Reset amplitude</li> <li>Reset pressure</li> <li>Measure and re-calibrate amplitude display</li> </ul>	
Time limit error or peak power error displayed after weld cycle	<ul> <li>Reset limits</li> <li>Check tip, rotate or replace if worn</li> <li>Check anvil for wear, rotate or replace if worn</li> <li>Check air pressure setting</li> <li>Check up stop for proper adjustment</li> <li>Process settings have to be opened up due to part variance or limits should be adjusted according to the part/wire being run</li> <li>Check anvil clamp for proper torque</li> </ul>	
Squealing sound during welding or when test key is depressed	<ul><li>Reset gaps</li><li>Re-square horn/tip and reset gaps</li><li>Reset horn tip and gap</li></ul>	
Weld heights are inconsistent	<ul> <li>Re-calibrate encoder with 1mm gauge</li> <li>Ensure the connector for the encoder is tightly plugged into the actuator card</li> </ul>	
Horn is stuck in down position	<ul><li>Check air pressure</li><li>Ensure air lines are installed properly</li><li>Check for kinks in air lines</li></ul>	
Air leaking from machine	<ul><li>Ensure all air line connections are tight</li><li>Check for cracked or broken air lines</li></ul>	
Unusual sound during weld cycle	<ul><li>Check tooling gap</li><li>Check converter</li><li>Check stack assembly</li></ul>	
Squealing sound from power supply when unit is turned on	Check cooling fans in rear of unit	
Maintenance counter alarm	Reset maintenance counter	
Actuator moves sluggish	<ul> <li>Check air lines for contamination</li> <li>NOTICE     Air must be filtered to 5 microns and be oil and water free.</li> <li>Check solenoid valve, replace if needed</li> <li>Check air regulator</li> </ul>	
System has READY CHECK message	<ul> <li>The horn is stuck in the closed position</li> <li>Maintenance has moved the height encoder to an out of limit condition</li> <li>Defective encoder or electronics</li> <li>Encoder not plugged into the actuator card</li> </ul>	

Table 7.1 Troubleshooting

Problem	Solution
Time, height and energy inconsistent	<ul> <li>Switch to energy mode &amp; open height window</li> <li>Make some sample welds</li> <li>Check the time and the height of the welds for consistency</li> <li>If the time or weld thickness varies greatly, check the air regulator</li> </ul>

### 7.4 Parts Lists

The following tables list the available Accessories (<u>Table 7.2</u>) and Parts (<u>Table 7.3</u>) and <u>Table 7.4</u>) for the Ultraweld L20 Actuator:

Table 7.2 Available Accessories

Description	EDP Number
Low Gain Booster (1: 0.6)	11003-02-133
Medium-Low Gain Booster (1 : 0.8)	10000-00-180
Medium-Low Gain Booster (1 : 0.9)	11008-03-133
1 to 1 Gain Booster (1 : 1)	11003-02-033
Medium-High Gain Booster (1 : 1.11)	A8A03A12
Medium-High Gain Booster (1 : 1.28)	10000-00-080
High Gain Booster (1: 1.6)	11003-02-233
Super High Gain Booster (1:1.8)	K1A90A09
Ultra High Gain Booster (1 : 1.9)	K1A90A15
Converter 105	101-135-033R
Horn Solid 2-Lobe Pocket	L1A90A62
Horn Solid 2-Lobe Special	N5A92145
Horn MTS Thread on Tip	G3A90A43
Horn Half Wave Solid Cantil	L1A90A83
Tip Nut	11003-01-043
Tip	G3A90A71

The following table lists items that are highly recommended to have readily available to prevent extended equipment down time and/or setup time.

Table 7.3 Primary Spare Items

Description	EDP Number
Actuator Board	102-242-632R
Linear Encoder	103-096
Spring, Front Diaphragm	N5A50A46
Spring, Rear Diaphragm	N5A50A47



The following table lists items that are recommended to have readily available to prevent extended equipment down time and/or setup time.

Table 7.4 Secondary Spare Items

Description	EDP Number
Solenoid Valve Assembly	206-151
Electronic Pressure Regulator 207-048	
Air Cylinder (63mm Bore)	205-231
Air Cylinder (100mm Bore)	205-230
Slide	105-356

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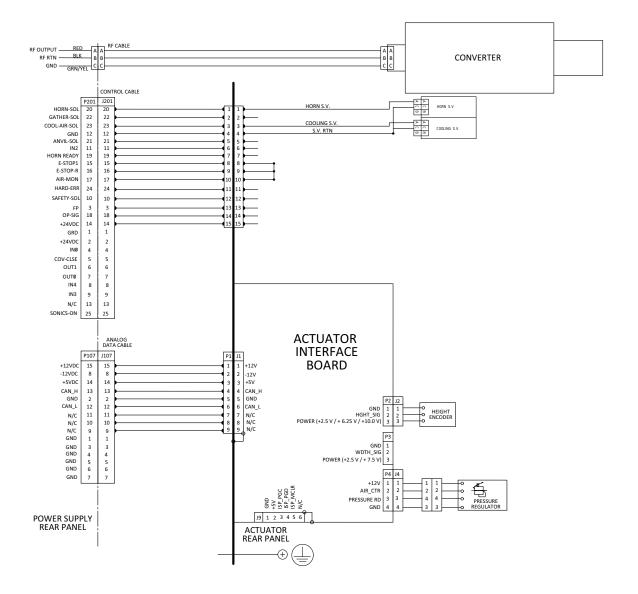
# **Appendix A: Interconnect Diagram**

4.1	Interconnect Diagram	8	,2	1
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#### A.1 Interconnect Diagram

Figure A.1 Ultraweld L20 Interconnect Diagram



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# **Appendix B: Declaration of Conformity**

3.1	<b>Declaration of Conformity</b>		36	ć
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#### **B.1** Declaration of Conformity

#### Figure B.1 Declaration of Conformity

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#### EC DECLARATION OF CONFORMITY

According to the Machinery Directive 2006/42/EC and the EMC Directive 2014/34/EU.

We, the manufacturer

#### **BRANSON DE MEXICO**

Carretera Nacional km 8.5 Modulo Industrial America, Lote 4 Nuevo Laredo, Tamaulipas 88277 Mexico

represented in the community by

#### BRANSON ULTRASONICS, a.s.

Piestanska 1202 915 01 Nove Mesto nad Vahom Slovak Republic

expressly declare under our sole responsibility that the equipment L20 Ultrasonic Welder System consisting of:

Branson welder model Ultraweld L20 Spot used with a Branson ultrasonic power supply model (TS or VGX) L20 (20:2.2 or 20:3.3 or 20:4.0) and associated cables.

in the state in which it was placed on the market, fulfills all the relevant provisions of the Machinery Directive 2006/42/EC and the EMC Directive 2014/30/EU. The safety objectives set out in the Low Voltage Directive 2014/35/EU were kept in accordance Annex 1 No. 1.5.1 of the Machinery Directive 2006/42/EC.

The object of this declaration is in conformity with relevant Union harmonization legislation. The equipment, to which this declaration relates, is in conformity with the following standards:

EN 60204-1:2018 EN ISO 12100:2010 EN ISO 13849-1:2015 EN ISO 13849-2:2012 EN ISO 13850:2015 EN 55011:2016/A1:2017 EN 61000-6-2:2005

Nuevo Laredo, Tamaulipas, MX April 8, 2022

CE Marking Affixed: 2022

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Person authorised to compile the technical file: BRANSON ULTRASONICS, a.s. Piestanska 1202 91501 Nove Mesto nad Vahom Slovak Republic Luis Benavides

O182368FCDE147C

Luis Benavides

Branson Product Safety Officer

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#### Figure B.2 UK Declaration of Conformity

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#### UK DECLARATION OF CONFORMITY



We, the manufacturer

#### **BRANSON DE MEXICO**

Carretera Nacional km 8.5 Modulo Industrial America, Lote 4 Nuevo Laredo, Tamaulipas 88277 Mexico

expressly declare under our sole responsibility that the equipment L20 Ultrasonic Welder System consisting of:

Branson welder model Ultraweld L20 Spot used with a Branson ultrasonic power supply model (TS or VGX) L20 (20:2.2 or 20:3.3 or 20:4.0) and associated cables,

in the state in which it was placed on the market, fulfills all the relevant provisions of:

Supply of Machinery (Safety) Regulations 2008
Electromagnetic Compatibility Regulations 2016
Restriction of the Use of Certain Hazardous Substances in Electrical and Electronic Equipment Regulations 2012.

The object of this declaration is in conformity with relevant UK Statutory Instruments and their amendments. The equipment, to which this declaration relates, is in conformity with the following designated standards:

EN 60204-1:2018 EN ISO 12100:2010 EN ISO 13849-1:2015 EN ISO 13849-2:2012 EN ISO 13850:2015 EN 55011:2016/A11:2020 EN 61000-6-2:2005/AC:2005

Brookfield, CT, USA October 19, 2022

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Luis Benavides

Branson Product Safety Officer

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VersaGraphix
Ultraweld L20

Operating Manual

Branson Ultrasonics Corp. 120 Park Ridge Road Brookfield, CT 06804 (203) 796-0400 http://www.bransonultrasonics.com





#### **Manual Change Information**

At Branson, we strive to maintain our position as the leader in ultrasonics metal welding, plastics joining, cleaning, and related technologies by continually improving our circuits and components in our equipment. These improvements are incorporated as soon as they are developed and thoroughly tested.

Information concerning any improvements will be added to the appropriate technical documentation at its next revision and printing. Therefore, when requesting service assistance for specific units, note the Revision information found on this document, and refer to the printing date which appears on this page.

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#### **Foreword**

Congratulations on your choice of a Branson Metal Welding system!

The Branson VersaGraphix Series system is process equipment for the joining of metal parts using ultrasonic energy. It is the newest generation of product using this sophisticated technology for a variety of customer applications. This Operating Manual is part of the documentation set for this system, and should be kept with the equipment.

Thank you for choosing Branson!

#### Introduction

This manual is arranged into several structured chapters which will help you find the information you may need to know to safely handle, install, set up, program, operate, and/or maintain this product. Please refer to the <u>Table Of Contents</u> of this manual to find the information you may be looking for. In the event you require additional assistance or information, please contact our Product Support department (see <u>1.4 How to Contact Branson</u> for information on how to contact them) or your local Branson representative.

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# **Chapter 1: Safety and Support**

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#### 1.1 Safety Requirements and Warnings

This chapter contains an explanation of the different Safety Notice symbols and icons found both in this manual and on the product itself and provides additional safety information for ultrasonic welding. This chapter also describes how to contact Branson for assistance.

#### 1.1.1 Symbols found in this Manual

These symbols used throughout the manual warrant special attention:

WARNING	Indicates a possible danger
	If these risks are not avoided, death or severe injury might result.

CAUTION	Indicates a possible danger
<u>^</u>	If these risks are not avoided, slight or minor injury might result.

NOTICE	Indicates a possible damaging situation
1	If this situation is not avoided, the system or something in its vicinity might get damaged.  Application types and other important or useful information are emphasized.

#### 1.1.2 Symbols found on the Product

The VersaGraphix Ultraweld L20 has several warning labels on it to indicate the presence of hazardous voltages inside the unit.

#### 1.2 General Precautions

Take the following precautions before servicing the VersaGraphix:

- Be sure the power switch is in the Off position before making any electrical connections
- To prevent the possibility of an electrical shock, always plug the VersaGraphix into a grounded power source
- Power supplies produce high voltage. Before working on the VersaGraphix module, do the following:
  - Turn off the VersaGraphix;
  - · Unplug main power; and
  - Allow at least 2 minutes for capacitors to discharge.
- High voltage is present in the VersaGraphix Ultraweld L20. Do not operate with the cover removed
- High line voltages exist in the ultrasonic VersaGraphix module. Common points are tied to circuit reference, not chassis ground. Therefore, use only non-grounded, battery-powered multimeters when testing these modules. Using other types of test equipment can present a shock hazard
- Be sure power is disconnected from the VersaGraphix before setting a DIP switch
- Keep hands from under the horn. Down force (pressure) and ultrasonic vibrations can cause injury
- Do not cycle the welding system if either the RF cable or converter is disconnected

WARNING	
<u>\( \)</u>	Sound level emissions of up to 84.9 dB have been measured using a standard test load. To prevent the possibility of hearing loss, use appropriate hearing protection.

# Sound level and frequency of the noise emitted during the ultrasonic assembly process may depend upon a. type of application, b. size, shape and composition of the material being assembled, c. shape and material of the holding fixture, d. welder setup parameters and e. tool design. Some parts vibrate at an audible frequency during the process. Some or all of these factors may result in sound levels of up to 84.9 dB. In such cases operators may need to be provided with personal protective equipment. See 29 CFR (Code of Federal Regulations) 1910.95 Occupational Noise Exposure. For all other countries, follow your local regulations.

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NOTICE	
	Because the Branson SBC Ultraweld L20 runs on a Windows XP <sup>®a</sup> based PC Platform, it is susceptible to computer viruses. Reasonable steps have been taken to protect our software but all customers are advised to take all necessary steps to ensure that no virus contamination occurs. Do not attempt to run any applications other than the Branson SBC Ultraweld L20 application. If you chose to connect the SBC controller to a computer network, added precautions must be taken in the form of firewalls, etc. No liability will be accepted for any loss or damage sustained as a consequence of any virus transmission.

a. Windows XP is a registered trademark of Microsoft Corporation.

#### 1.2.1 Intended Use of the System

The Branson VersaGraphix Ultraweld L20 and Actuator are components of an ultrasonic welding system. These are designed for a wide variety of welding or processing applications.

#### 1.2.2 Regulatory Compliance

The Branson products (VersaGraphix Ultraweld L20 Welders) are designed to be in compliance with the following U.S. regulatory and agency guidelines and standards:

- ANSI Z535.1 Safety Color Code
- ANSI Z535.3 Criteria for Safety Symbols
- ANSI Z535.4 Product Safety Signs and Labels
- ANSI Z535.6 Product Safety Information in Product Manuals, instructions, and other collateral materials
- NFPA 70 National Electric Code Article 670 Industrial Machinery
- NFPA 79 Electrical Standard for Industrial Machinery
- UL 61010-1
- CSA 22.2 No. 61010-1
- 29 CFR 1910.212 OSHA General Requirements for all machines
- 47 CFR Part 18 Federal Communications Commission

Branson products (VersaGraphix Ultraweld L20 Welders) are designed to be in compliance with the following listed European standards as specified by the Directives issued by the European Parliament and The Council of the European Union:

- Machinery Directive 2006/42/EC
- Low Voltage Directive 2014/35/EU
- EMC Directive 2014/30/EU
- BS EN ISO 13850 Safety of Machinery Emergency stop equipment, Functional aspects Principles for design
- EN 13849-1 Safety of Machinery Safety of related parts of control systems
- EN ISO 12100 Safety of Machinery Risk assessment Part 1: Principles
- EN 55011 Limits and methods of measurement of radio disturbance of industrial, scientific and medical radio-frequency equipment
- EN 60204-1 Safety of Machinery Electrical Equipment of machines
- EN 61000-6-2 Electromagnetic Compatibility Generic standards Immunity for industrial environments



• EN 61310-2 Safety of Machinery - Indication, marking, actuation

All products with CE Mark require: Same as above plus



Branson products (VersaGraphix Ultraweld L20 Welders) are designed to be in compliance with relevant UK Statutory Instruments and their amendments:

\*Supply of Machinery (Safety) Regulations 2008

\*Electromagnetic Compatibility Regulations 2016

All products with UKCA Mark require: Same as above plus



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### 1.3 Warranty

For warranty information please reference the warranty section of Terms and Conditions found at: <a href="https://www.emerson.com/branson-terms-conditions">www.emerson.com/branson-terms-conditions</a>.



#### 1.4 How to Contact Branson

Branson is here to help you. We appreciate your business and are interested in helping you successfully use our products. To contact Branson for help, use the following telephone numbers, or contact the field office nearest you.

- Brookfield Main Number (all Departments): (203) 796-0400 (Eastern Time Zone)
- Parts Store: Direct Number for Parts Store in Brookfield (203) 796-9807

Tell the operator which product you have and which person or department you need. If after hours, please leave a voice message with your name and return telephone number.

#### 1.4.1 Before Calling Branson for Assistance

This manual provides information for troubleshooting and resolving problems that could occur with the equipment (see <a href="Chapter 6: Maintenance">Chapter 6: Maintenance</a>). If you still require assistance, Branson Product Support is here to help you. To help identify the problem, use the following questionnaire which lists the common questions you will be asked when you contact the Product Support department.

Before calling, determine the following information:

- 1. Your company name and location.
- 2. Your return telephone number.
- 3. Have your manual with you.
- 4. Know your equipment model and serial numbers (found on a gray data label on the units). Information about the Horn (part number, gain, etc.) or other tooling may be etched into the tooling. Software- or firmware-based systems may provide a BIOS or software version number, which may be required.
- 5. What tooling (horn) and booster are being used?
- 6. What are the setup parameters and mode?
- 7. Is your equipment in an automated system? If so, what is supplying the "start" signal?
- 8. Describe the problem; provide as much detail as possible. For example, is the problem intermittent? How often does it occur? How long before it occurs if you are just powering up? If an error is occurring, which error (give error number or name)?
- 9. List the steps you have already taken.
- 10. What is your application, including the materials being processed?
- 11. Have a list of service or spare parts you have on hand (tips, horns, etc.)

12. No	Notes:							
_	· · · · · · · · · · · · · · · · · · ·					 		

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#### 1.5 Returning Equipment for Repair

NOTICE	
1	To return equipment to Branson, you must first obtain an <b>RGA number</b> from a Branson Metal Welding representative, or the shipment may be delayed or refused.

If you are returning equipment to Branson for repair, you must first call the Repair department to obtain a <u>Returned Goods Authorization</u> (**RGA**) number. (If you request it, the repair department will fax a Returned Goods Authorization form to fill out and return with your equipment).

**Branson Metal Welding Repair Department** 

120 Park Ridge Road

Brookfield, Connecticut 06804 U.S.A.

direct telephone number: (203) 796-0807

fax number: (203) 796-0574

- Provide as much information as possible that will help identify the need for repair
- · Carefully pack the equipment in original packing cartons
- Clearly label all shipping cartons with the RGA number on the outside of cartons as well as on your packing slip, along with the reason for return
- Return general repairs by any convenient method. Send priority repairs by air freight
- You must prepay the transportation charges FOB Brookfield, Connecticut, U.S.A.

1.5.1	Get ar	า RGA	Number
-------	--------	-------	--------

RGA#

If you are returning equipment to Branson, please call the Repair Department to obtain a
Returned Goods Authorization (RGA) number. (At your request, the Repair Departmen
will fax an RGA form to fill out and return with the equipment).

#### 1.5.2 Record information about the Problem

Before sending equipment for repair, record the following information and send a copy of it with the equipment. This will greatly increase Branson's ability to address the problem.

1.	Describe the problem; provide as much detail as possible. For example, is the problem intermittent? How often does it occur? How long before it occurs after powering up?

2. Is your equipment in an automated system? NO / YES



3. If the problem is with an external signal, which signal? If known, include plug/pin # (e.g., P29, pin #3) for that signal:				
4.	What are the Weld Parameters?			
5.	What is your application? (Type of weld, metal material, etc.)			
6.	Name and phone number of the person most familiar with the problem:			
 7.	Contact the Branson Metal Welding office prior to shipping the equipment.			
8.	For equipment not covered by warranty, to avoid delay, include a Purchase Order.			
Se	end a copy of this page with the equipment being returned for repair.			
C	ontact Information			
	ll your local Branson Metal Welding Representative, or contact Branson by calling (203) 06-0400.			
My	My Local Branson Representative's name is:			

## 1.5.4 Pack and Ship the Equipment

I can reach this representative at:

1.5.3

- 1. Carefully pack the system in original packing material to avoid shipping damage. Plainly show the RGA number on the outside of cartons as well as inside the carton along with the reason for return. Make a list of all components packed in the box. KEEP YOUR MANUAL.
- 2. Return general repairs by any convenient method. Send priority repairs by air freight. Prepay the transportation charges FOB the repair site (either the Branson field office or Brookfield, Connecticut USA location).

NOTICE	
<b>f</b>	Items that are sent Freight Collect will be refused.

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#### 1.6 Obtaining Replacement Parts

You can reach the Branson Parts Store at the following telephone numbers:

- Direct Telephone Number: (203) 796-9807
- Fax number: (203) 926-2678

Many parts can be shipped the same day if ordered before 2:30 p.m., Eastern time.

A parts list is found in <u>Chapter 6: Maintenance</u> of this manual, listing descriptions and EDP part numbers. If you need replacement parts, coordinate the following with your purchasing agent:

- Purchase order number
- 'Ship to' information
- 'Bill to' information
- Shipping instructions (air freight, truck, etc.)
- Any special instructions (for example, "Hold at the airport and call"). Be sure to give a name and phone number
- Contact name information

# **Chapter 2: The Branson VersaGraphix Ultraweld L20**

2.1	About this Operating Manual
2.2	Model Covered
2.3	Overview of this Model
2.4	Compatibility with Branson Products
2.5	Ultrasonic Theory
2.6	Terminology

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#### 2.1 About this Operating Manual

This manual provides detailed instructions for the setup, operation, and maintenance of the Branson VersaGraphix Ultraweld L20. For detailed information on operation and maintenance of other components connected to the Ultraweld L20, refer to appropriate Actuator instruction manual.

The VersaGraphix Ultraweld L20 contains a microprocessor-based controller that provides for control and monitoring of welding operations.



#### 2.2 Model Covered

This document is intended for use with a 2032S actuator. This document is intended for use in conjunction with others to form a complete manual for your Branson Metal Welding system. Please refer to the <u>Table Of Contents</u> of this Instruction Set to find specific information.

#### 2.3 Overview of this Model

The Branson welder generates ultrasonic electrical energy through an ultrasonic converter for welding metals. Several models are available, depending on the desired frequency (for example, 20 kHz) or the desired power range (for example, 2.2 kW). The VersaGraphix also contains a microprocessor-based controller module that provides for control and monitoring of welding operations.



#### 2.4 Compatibility with Branson Products

The Branson VersaGraphix Ultraweld L20 is designed to be used with:

- Branson Metal Welding Actuators: 2032S, Ultrasplice 40, Ultrasplice XL, Auto Terminator, Ultraweld L20, WSX ERGO, and Ultraseal 20
- Branson Metal Welding converters: see <u>Table 2.1 VersaGraphix Ultraweld L20 compatibility with</u>
  <u>Branson Metal Welding Converters</u> below

Table 2.1 VersaGraphix Ultraweld L20 compatibility with Branson Metal Welding Converters

Branson Model	Converter
20 kHz/1250 W	
20 kHz/2500 W	503, 105
20 kHz/3300 W	303, 103
20 kHz/4000 W	
20 kHz/5000 W	High Power
40 kHz/400 W	4TJ, 4TR, 4TH
40 kHz/800 W	+1J, +1N, +111

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#### 2.5 Ultrasonic Theory

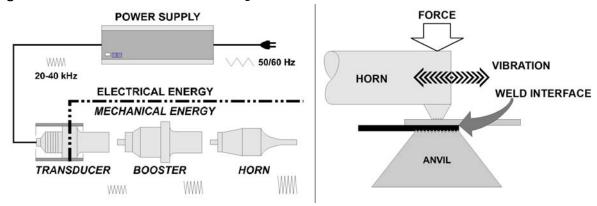
#### 2.5.1 What Is An Ultrasonic Weld?

Ultrasonic welding joins metal parts by applying the energy of high frequency vibrations onto the interface area between the parts to be welded.

#### 2.5.2 How Does It Work?

Electrical Energy is transformed into high frequency mechanical vibration. This mechanical vibration is transferred to a welding tip through an acoustically tuned horn. The parts are "scrubbed" together under pressure at 20,000 or 40,000 cycles per second. This high frequency vibration, applied under force, disperses surface films and oxides, creating a clean, controlled, diffusion weld. As the atoms are combined between the parts to be welded, a true, metallurgical bond is produced.

Figure 2.1 How does Ultrasonic Welding Work?



#### 2.5.3 Benefits of Ultrasonic Welding

Ultrasonic metal welding exhibits unique welding properties that include:

- Excellent electrical, mechanical, and thermal connections between similar and dissimilar metals
- Low heat build up during the ultrasonic process (no annealing of materials)
- Compensation for normal surface variations of the material
- Ability to clean surface oxides and contaminants prior to welding
- Ability to weld large areas using minimal energy
- · Ability to weld thin materials to thick materials
- Low cost per weld

#### 2.5.4 How Is An Ultrasonic Weld Made?

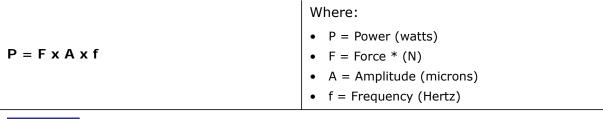
Although the theoretical process of producing an ultrasonic weld is uncomplicated, the interactions of the various weld parameters are important and should be understood. When producing an ultrasonic weld, there are three primary variables that interact; they are:

- Time: The duration of applied ultrasonic vibration
- Amplitude: The longitudinal displacement of the vibration
- Force: The compressive force applied perpendicular (normal) to the direction of vibration



The power required to initiate and maintain vibration (motion) during the weld cycle can be defined as

Table 2.2 Calculating Power



#### NOTICE

Force = (Surface Area of the Cylinder) X (Air Pressure) X (Mechanical Advantage)

Table 2.3 Calculating Energy

Where:
<ul> <li>E = Energy (joules)</li> <li>P = Power (watts)</li> <li>T = Time (seconds)</li> </ul>
• I = IIIIe (Seconds)

Thus the complete 'Weld To Energy' process would be defined as:

$$E = (F \times A \times f) \times T$$

A well designed ultrasonic metal welding system will compensate for normal variations in the surface conditions of the metals by delivering the specified energy value. This is achieved by allowing Time (T) to adjust to suit the condition of the materials and deliver the desired energy.

#### 2.5.5 Welding To Energy - Why?

Most metal welding applications are produced by 'Welding To Energy' in order to compensate for the various surface oxides and contaminants associated with the metals being joined. In a few applications 'Welding To Time' or 'Welding To Height' will yield better results. Since the majority of all metal welds are produced using energy as the controlling factor we will confine our discussion to that condition.

Welding to energy is necessary because of the non-metallic oxides that form on the metal's surface as well as other contaminates such as grease and dirt. To produce quality welds reliably it is necessary that the surfaces to be joined are clean. The high frequency scrubbing action, combined with pressure, cleans the weld interface at the beginning of the weld process.

The following graph (Figure 2.2 Weld Power Graph for Clean Components, Dirty Components, and when Part is Missing) illustrates a weld produced. The weld 'power graph' is sometimes referred to as weld 'footprint'. It can be used to visualize the weld cycle and assists in parameter optimization. Graphs from consecutive welds will vary slightly as the system dynamically adjusts time to accommodate varying surface conditions. The weld power data is gathered by sampling the power used in 5 millisecond intervals.

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Clean Component Parts (Area under curve = 1,000 joules) Quick ramp up to peak power and short cycle time to dissipate energy Dirty Component Parts and or Worn tooling (Area under curve = 1,000 joules) Slow ramp up to peak power and longer cycle time to dissipate energy **Component Part Missing** 100 (Area under curve = 500 joules) T, No ramp up to peak power and long cycle time to dissipate energy. Cycle terminated after 5 seconds. т, 80 P, 60 40 0 1.0 5.0 4.0

Figure 2.2 Weld Power Graph for Clean Components, Dirty Components, and when Part is Missing

#### 2.5.6 Power

The converter/booster/horn, (stack assembly), requires minimal electrical power to initiate and maintain motion (vibration) at a 'no-load' condition. As the mechanical load increases, the power required to maintain the mechanical vibration also increases. The maximum power required during a weld cycle is 'Peak Power'.

By increasing Pressure and maintaining all other parameters, the mechanical load or force on the weld joint increases, therefore, the amount of Power required to maintain the vibration of the stack increases. Subsequently, because of the increased Power Level, less time is required deliver the same amount of Energy. This relationship is illustrated on Figure 2.3 Pressure Variable with Increased Power.

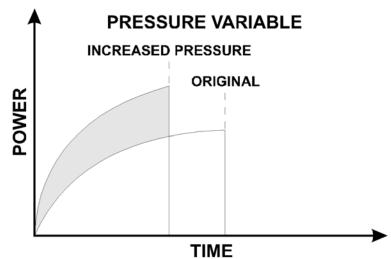


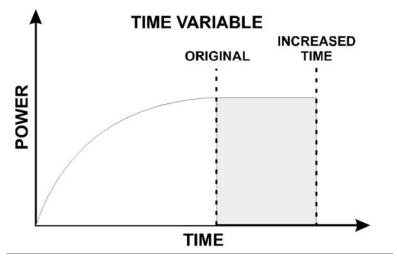
Figure 2.3 Pressure Variable with Increased Power

The difference in the appearance of each of the above weld graphs is the result of increased Power loading. Based upon an increase in Pressure, additional Power is required to maintain the motion of vibration. Thus, the same amount of energy is delivered in less time. This approach is typically used to raise the loading of the power supply during a weld cycle to the desired level as determined by the application.

#### 2.5.7 Time

The time required to deliver the necessary energy is defined as the Weld Time. For most welds, the time required will be less than one second. If more energy is required and all other weld parameters are maintained, the weld time will increase (<u>Figure 2.4 Pressure Variable with Increased Time</u>).

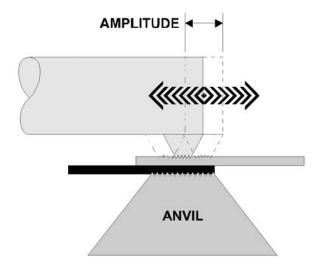
Figure 2.4 Pressure Variable with Increased Time



#### 2.5.8 Amplitude

An ultrasonic tool is a resonant acoustical device. The term Amplitude is used to describe the amount of longitudinal expansion and contraction that the tooling endures as it vibrates (<u>Figure 2.5 Scrubbing Action on Weld Interface</u>). The amplitude correlates to the scrubbing action at the weld interface. This scrubbing action combined with pressure is what advances the weld by a diffusing or mixing of the base materials.

Figure 2.5 Scrubbing Action on Weld Interface



As previously mentioned, the converter/booster/horn, (stack assembly), requires minimal electrical power to initiate and maintain vibration in a 'no-load' condition. As the amplitude increases, the power required to maintain the increased velocity of vibration also increases. Subsequently, because of the increased Power less time is required deliver the

same amount of Energy. This relationship is illustrated in the following power diagram (Figure 2.6 Amplitude's Influence on Weld Power and Time):

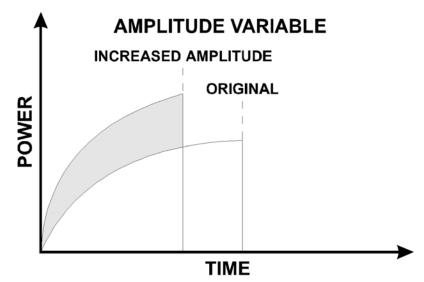
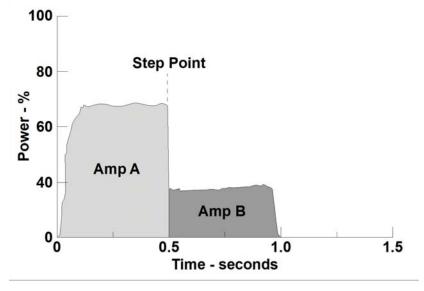


Figure 2.6 Amplitude's Influence on Weld Power and Time

#### 2.5.9 Amplitude Stepping

In standard practice, the scrubbing amplitude at the weld interface is maintained constant during a weld cycle. Recent advances in technology have made it possible to change the amplitude of the horn face during the weld cycle. This is known as Amplitude Profiling. Figure 2.7 Amplitude Stepping Profile illustrates a typical profile where the amplitude is reduced during the cycle. This type of profile is used mostly with welding aluminum to increase weld strength and to help prevent sticking to the tooling.



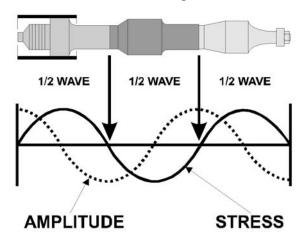


#### 2.5.10 Resonant Frequency

The ultrasonic tooling acts as a spring having node points and anti-node points. The mechanical energy used to vibrate the tool is created by the converter. As the vibrations are propagated through the acoustical tool, a harmonic resonance is established consisting of nodes and antinodes. This action results in a resonant wave being transferred through the tooling (Figure 2.8 Harmonic Resonance on Ultrasonic Tooling). The efficiency of the resonant wave transfer depends on the natural resonant frequency of the horn and is determined by two factors:

- The speed of sound through the material
- The geometric shape of the object

Figure 2.8 Harmonic Resonance on Ultrasonic Tooling



## 2.5.11 Avoiding An Overload Condition

It is possible to increase the Amplitude and or the Pressure to a point where the power available is not adequate to initiate or maintain vibration under the given mechanical load. At this point, the power supply will stall resulting in an Overload condition. Electronic circuits in the system will protect the power supply if this condition exists.

#### 2.5.12 Welding To Time

In specific applications, 'Welding To Time' may be desired. As previously mentioned, there are three primary variables that interact; they are:

- TIME: The duration of applied ultrasonic vibration
- AMPLITUDE: The longitudinal displacement of the vibration
- FORCE: The compressive force applied perpendicular (normal) to the direction of vibration

Generally, welding for a specific time will produce acceptable results when:

- The equipment is installed on an automated production line and each station must complete its process within a certain time limit
- Very small low energy welds on clean components are being made

#### 2.5.13 Welding Temperature

Ultrasonic welding produces a localized temperature rise from the combined effects of elastic hysteresis, interfacial slip and plastic deformation. The weld interfaces reach approximately 1/3 the temperatures needed to melt the metals. Since the temperature does not reach the melting point of the material, the physical properties of the welded material are preserved. As the ultrasonic welding process is an exothermic reaction, as welding time increases so does weld temperature.

## 2.6 Terminology

**Actuator:** A mechanical device which houses the converter/booster/horn (stack) assembly in a rigid mounting and is utilized to move the stack up or down. This allows for precise control of welding pressure while delivering mechanical vibrations from the ultrasonic stack to the work piece(s).

After Burst: A short duration (burst) of ultrasonic energy that begins after the weld is complete and at 1mm from the final height reading. Used when the splice nugget is sticking to the tooling.

**After Burst Delay:** The amount of time, in seconds, between the completion of the ultrasonic welding cycle and the start of the AFTER BURST. (Also see AFTER BURST).

**Amplitude**: Amplitude is the peak-to-peak displacement of mechanical motion as measured at the face of the horn tip. Amplitude is measured either in thousandths of an inch or in microns (e.g. a standard 40 kHz *Converter* produces approximately .0004" or 10 microns of amplitude), Inches x 25.4 = microns. -- This is adjustable depending on system frequency and application tooling.

**Anti-Node**: The anti-node is the area of the horn and booster that exhibits maximum longitudinal displacement and where the internal dynamic forces are equal to zero. This area is at the face and back surface on half-wave technology.

**Anvil**: A device specially designed to grip the lower component and hold it stationary against the energy of vibration(s) which allows a weld to be created.

**BBR**: Nonvolatile random access memory (battery back-up random access memory). Equipped with long life built in batteries, this memory area preserves weld parameters and menu settings when the system is powered off. (Also known as BRAM).

**Booster**: The central component of an ultrasonic stack assembly. A device which transfers mechanical energy from the *Converter* to the ultrasonic horn. The booster will, depending on design, increase, decrease, or maintain the specific amplitude as received from the converter.

**Calibration**: The process of adjusting a device to a known position for purposes of inspection and/or monitoring position, direction, speed, and/or velocity.

**Consumable Spare Tooling:** The tooling portion of the ultrasonic system that wears and requires replacement due to production use. This includes but is not limited to ultrasonic horns, replaceable tips, anvil, and positioning mask. A Spare Tooling Specification Sheet is included within the Actuator Operation Manual to document the spare tooling for a specific metal welding application.

**Ultraweld L20**: The portion of the welding system that provides specific settings & instruction(s) to the overall welding system.

**Converter:** A device which utilizes a PZT (lead-zirconate-titanate) electrostrictive element to change high frequency electrical energy into high frequency mechanical energy.

**Counter:** A programmable device used to monitor system cycles and alert personnel when specific conditions are met.

**Data**: Any representation(s) of instructions, characters, information, or analog quantities to which meaning may be assigned.

**Default:** A chosen system setting or parameter in which the system does not require external data input. In some cases the default value will be changed based upon equipment use.

**Dynamic Spring:** An, adjustable, energy storage mechanism (shock absorber) which allows for stack follow through upon engagement of application tooling with the work pieces to be welded.



**Energy**: Energy is the area beneath the ultrasonic power curve and is calculated in joules, (Watts X Seconds = Joules). When the ultrasonic welding system is setup in the "Weld In Energy" mode the system will deliver the amount of energy as programmed. **NOTE**: The maximum (default) time allowed for delivering ultrasonic energy is five (5) seconds.

**Energy Mode**: A welding method in which the ultrasonic power supply is active until the required amount of energy is delivered (see ENERGY).

**Fixture:** A device for positioning and or holding a component for assembly.

**Force**: The amount of mechanical pressure that is used to deliver (bring down) the mechanical actuator. This programmed force is also called TRIGGER FORCE and is used to engage the knurl pattern into the component part(s) prior to the initiation of ultrasonic energy.

**Frequency**: The number of complete oscillations per second expressed in Hertz (Hz) or kilohertz (1 kilohertz = 1000 Hz). Typically 20 kHz or 40 kHz.

**Gain**: The ratio of the amplitude of motion produced by the *Converter* and delivered by the horn is called the gain. It is determined by the difference in mass on either side of the nodal point.

**Height**: A value, in millimeters (mm), as registered by a linear encoder upon completion of an ultrasonic welding cycle. -- Programmable, in millimeters, with Upper Control Limit & Lower Control Limit.

**Height Encoder**: A device utilized to monitor position, direction, speed, and/or velocity.

**Horn:** An acoustically designed metal tool that delivers mechanical energy from the converter/booster into the work piece. Most applications utilize half wave technology.

**Hold Time**: The amount of time after delivery of ultrasonic energy until the stack tooling begins to retract from the component material(s).

**Joint**: The area where the surfaces are welded together.

**Linear Height Encoder**: See Height Encoder.

**Loading Meter:** A meter which indicates the power drawn from the ultrasonic power supply.

**Maintenance Counter:** Used to alert production personnel of the need to review/ inspect application tooling and/or the ultrasonic system for preventive maintenance purposes. (See Counters).

**Mode**: The method of operating the system (also see WELDING MODE).

**Node**: The node is the area of the horn, (and booster), that exhibits no longitudinal displacement and where the internal dynamic forces are at the maximum. This area is in the center location on half-wave technology.

**Parameter(s):** Programmable units used to control and or monitor the ultrasonic process. --Include but not limited to ENERGY, FORCE, PRESSURE, AMPLITUDE.

**Parts Counter:** Used to monitor system cycles and alert personnel when specific conditions are met. (See Counters).

**Peak Power:** Peak power is the maximum amount of power in watts that was required to keep the ultrasonic stack in motion during the weld cycle.

**Power**: Power, measured in watts, is a function of pressure and amplitude. The amount of power, (watts) required to keep the ultrasonic stack in motion is monitored and used to develop a power curve. This power curve is used to calculate the amount of energy delivered/ dissipated, (Watts = Joules/Time). The power as displayed on the control box is peak power.

**Power Supply (Ultrasonic)**: An electronic device that converts 50/60 cycle electrical current into 40 kHz, (40,000) or 20 kHz, (20,000) cycles per second high frequency electrical energy.

**Power Supply Overload (Ultrasonic):** The point or limit at which the amount of power in watts, required to keep the ultrasonic stack in motion, exceeds the available power from the power supply. The system will go into an overload condition in order to prevent system damage.

**Pre-Burst:** A short duration (burst) of ultrasonic energy that begins after the Squeeze Time and before capturing the Pre-Height. Used when welding magnet wire. It helps to break up the insulation around the copper, and provide a small cooling period before the weld takes place.

**Pre-height:** A pre-sonic inspection display, in millimeters (mm), as registered by a linear encoder prior to initiation of the ultrasonic welding cycle. -- Programmable, in millimeters, with Upper Control Limit & Lower Control Limit.

**Presets:** Welding parameters stored in the controller memory.

**Pressure:** The amount of mechanical pressure supplied to the ultrasonic stack assembly while delivering ultrasonic energy to the components.

**Quality Widows & Limits:** Programmable values used by the system to compare actual process data. Actual process data must be within limits or an alarm be issued.

**Quick After Burst**: Once this option is enabled, the after burst needs to be implemented immediately after each weld cycle finished without any time delay or condition judgment.

**Squeeze Time:** The amount of time after the ultrasonic tooling engages the component(s) and before delivery of ultrasonic energy. -- Adjustable from 0 - 2 seconds.

**Stress**: Stress is the amount of dynamic force per cross sectional area.

**Time**: Time is the duration of the ultrasonic, mechanical, activity. Time is a component used to calculate the amount of ultrasonic energy delivered during a weld cycle, (Time = Joules/Watts).

**Tip:** Device specially designed to grip the upper component, to be welded, and to direct the ultrasonic energy into the work piece, (Also Horn Tip & Replaceable Horn Tip).

**Tip Nut:** Device specially designed to securely clamp a replaceable tip onto the horn.

**Trigger Force**: See Force.

**Tuning:** Adjusting to optimize power supply performance according to resonance frequency, especially with regard to the horn and converter.

**Velocity**: The rate of motion at a specific time [velocity = distance time] Also referred to as speed.

# **Chapter 3: Shipping and Handling**

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3.4	Returning Equipment	29

## 3.1 Shipping and Handling

CAUTION	
<u>^</u>	The VersaGraphix Ultraweld L20's internal components are sensitive to static discharge. Many components can be harmed if the unit is dropped, shipped under improper conditions or otherwise mishandled.

## 3.1.1 Environmental Specifications

The VersaGraphix Ultraweld L20 is an electronic unit that converts line voltage to ultrasonic energy and controls user input for regulating the weld process. Its internal components are sensitive to static discharge, and many of its components can be harmed if the unit is dropped, shipped under improper conditions, or otherwise mishandled.

The following environmental guidelines should be respected when shipping the VersaGraphix Ultraweld L20 and Touchscreen Monitor:

 Table 3.1
 Environmental Requirements

Environment	Range
Storage / Shipping Temperature	-13° F to +131° F (-25° C to +55° C)
Shock / Vibration (Transit)	40 g shock / 0.5 g and (3-100 Hz) vibration per ASTM 3332-88 and 3580-90
Humidity	30% to 95%* non condensing

<sup>\*</sup>Above 40° C the humidity drops to 90%

## 3.2 Receiving

The VersaGraphix Ultraweld L20 is a sensitive electronic device. Many of its components can be harmed if the unit is dropped or otherwise mishandled.

CAUTION	
	The Actuator and the VersaGraphix Ultraweld L20 are heavy. Handling, unpacking, and installation might require assistance or the use of a lifting device.

#### **Scope of Delivery**

Branson units are carefully checked and packed before dispatch. It is recommended, however, that you follow the inspection procedure below after delivery.

To inspect the VersaGraphix Ultraweld L20 when it is delivered, take the following steps:

 Table 3.2
 Inspect the VersaGraphix upon delivery

Step	Action
1	Verify that all parts are complete according to the packing slip.
2	Check the packing and the unit for damage (visual inspection).
3	Report any damage claims to your carrier immediately.
4	Determine if any component has become loose during shipping and, if necessary, tighten screws.

NOTICE	
	If the goods delivered have been damaged during shipping, please contact the forwarding agent immediately. Retain packing material (for possible inspection or for sending back the unit).

CAUTION	
	The Actuator and the VersaGraphix Ultraweld L20 are heavy. Handling, unpacking, and installation might require assistance or the use of a lifting device.

# 3.3 Unpacking

The VersaGraphix is fully assembled. It is shipped in a sturdy cardboard box. Some additional items are shipped in the box with the Ultraweld L20.

#### When unpacking the Ultraweld L20, take the following steps:

 Table 3.3
 When unpacking the Ultraweld L20

Step	Action	
1	Unpack the VersaGraphix Ultraweld L20 as soon as it arrives. Save the packing material.	
2	Inspect the unit for signs of damage.	
3	Remove the cover of the VersaGraphix Ultraweld L20 (see Section <u>6.3 Parts Replacement</u> ) to check if any components became loose during shipping.	
4	Store or ship the VersaGraphix Ultraweld L20 only within a temperature range of -13 $^{\circ}$ F to +131 $^{\circ}$ F (-25 $^{\circ}$ C to +55 $^{\circ}$ C).	

NOTICE	
1	If damage has occurred, notify the shipping company immediately. Retain packing materials for inspection.



# 3.4 Returning Equipment

If you are returning equipment to Branson, please call your Branson Metal Welding Representative or Customer Service to receive approval to return goods to Branson.

If you are returning equipment for repair refer to Section <u>1.5 Returning Equipment for Repair</u> of this manual, for appropriate procedure.

# **Chapter 4: Technical Specifications**

4.1	Environmental Requirements
4.2	Electrical Requirements
4.3	Pneumatic Requirements
4.4	Operating System

# 4.1 Environmental Requirements

The VersaGraphix Ultraweld L20 and Touchscreen Monitor have the following Environmental Requirements:

**Table 4.1** Environmental Requirements

Environmental Concern	Ultraweld L20/Power Supply	Touchscreen
Ambient Operating Temperature	+41° F to +122° F (+5° C to +50° C)	+32° F to +104° F (0° C to +40° C)
Storage / Shipping Temperature	-13° F to +131° F (-25° C to +55° C*)	-4° F to +131° F (-20° C to +55° C)
Humidity	30% to 95%**non condensing	30% to 80%
Operating Altitude	1000 m (3280 ft)	3658 m (12000 ft)
IP Rating	2X	

<sup>\*70°</sup> C for 24 hours

<sup>\*\*</sup>Above 40° C the humidity drops to 90%



# 4.2 Electrical Requirements

The following tables list input voltages, current requirements, and fuse requirements for the VersaGraphix Welding System, and includes power required when it is used with Branson Metal Welding Actuators.

 Table 4.2
 Electrical Input Operating Voltages

Power Supply Rating	Nominal Input Operating Voltage, +/- 10%
20 kHz / 2200 W	200-230 V, 50/60 Hz, Single Phase
20 kHz / 3300 W	200-230 V, 50/60 Hz, Single Phase
20 kHz / 4000 W	200-230 V, 50/60 Hz, Single Phase

**Table 4.3** Input Current and Fuse Requirements

Model	Input Current	Fuse Requirements
	2200 W 200V - 230V	14 Amp Max. @ 200V / 20 Amp fuse
For 20 kHz Models	3300 W 200V - 230V	21 Amp Max. @ 200V / 20 Amp fuse
	4000 W 200V - 230V	25 Amp Max. @ 200V / 25 Amp fuse

# 4.3 Pneumatic Requirements

The factory compressed air supply must be "clean (to a 5 micron level), dry and unlubricated" air with a regulated maximum pressure of 80 psig (5.5 bar).

## 4.4 Operating System

The VersaGraphix Ultraweld L20 uses an embedded Single Board Computer (SBC) to offer advanced user interface functions. It uses Windows XP Embedded (Windows XPE) as its operating system.

#### 4.4.1 About Microsoft Windows XP Embedded

While Windows XPE is similar to the standard desktop version of Windows XP there are some differences that the advanced user should be aware of.

The VersaGraphix Ultraweld L20's SBC uses a solid state hard disk in the form of a Compact Flash card. While this Compact Flash card appears to be the same type used in digital cameras, it is a special industrial version which allows the Windows XPE operating system to boot.

To protect the application and the operating system, Windows XPE employs a File Based Write Filter (FBWF). This filter uses a RAM overlay to record changes to the Compact Flash Hard Drive. Any changes made to the C: drive are lost during a power cycle. Only the C:\AmtData folder remains unprotected allowing the VersaGraphix application to write directly to the Compact Flash card in order to save presets, sequences, setup parameters and log files.

The FBWF must be disabled before modifying the Windows XPE configuration. Changes made to Windows XPE configuration such as printer driver installation or Local Area Network configuration will be lost if the FBWF has not been previously disabled. Once all changes have been saved, the FBWF must be re-enabled before resuming controller operations. Enabling and disabling the FBWF goes beyond the scope of this application user manual. Contact customer support if this becomes necessary (see <a href="https://linear.com/linear.co

NOTICE	
<b>1</b>	Operating the system while the FBWF is disabled will not allow the application to save presets, sequences, setup parameters and log file information.

# **Chapter 5: Operation**

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# 5.1 Before You Begin

# High voltage might be present in the Branson VersaGraphix Ultraweld L20 (VersaGraphix). When setting up and operating the welding system, observe the potential hazards listed below.

- Do not operate the VersaGraphix with the cover removed
- To prevent the possibility of electric shock, always plug the VersaGraphix Ultraweld L20 into a grounded power source
- Do not cycle the welding system if either the RF cable or the converter is disconnected. High voltage could be present at open power connections
- Ensure power switch is in the OFF position before making or breaking any electrical or pneumatic connections to the VersaGraphix and/or Welder
- Do not touch Ultrasonic Horn during or immediately following the welding cycle. Vibrations and heat can burn skin



# 5.2 Pop Up Alphanumeric Keypad

Figure 5.1 Pop up Alphanumeric Keypad



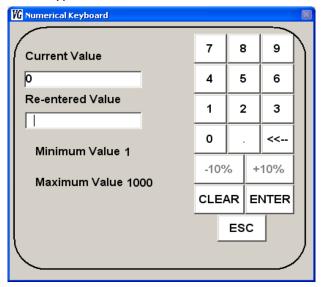
A pop up keypad will be displayed on the touchscreen when it is necessary to enter alphanumeric data using the touchscreen. This keyboard includes upper case letters A through Z, numbers 0 through 9, space, backspace, enter, clear and cancel. It also includes the following symbols:  $! @ # $\% ^ & () - = / + and$ ,.

Using non permitted characters when naming a preset or a sequence may happen if you use an external keyboard. To avoid system errors due to invalid name, please refer to the alphanumeric characters in the image above when naming a preset or a sequence with an external keyboard.



# 5.3 Pop Up Numeric Keypad

Figure 5.2 Pop up Numeric Keypad



A numeric keypad will pop up on the touchscreen when it is necessary to input numeric data. This Keypad includes buttons for the numbers 0 through 9, decimal point, Backspace (<<--), ENTER, CLEAR, and ESC. It also has a +10% button and a -10% button, which are used to enter values +/-10% of the currently set value, allowing quicker setups.

## 5.4 Editing Buttons

Edit

#### **Edit**

When the "Edit" is highlighted, it allows you to edit sequences.



#### **Delete**

When the "Delete" button is highlighted, you may remove unwanted sequence steps. On the file manager screen the "Delete" buttons allows you to eliminate unwanted files in the Browse and Application folders.



#### **Enter**

Touching the "Enter" button saves changes.

Сору

#### Copy

When highlighted, the "Copy" button allows you to create a copy of a sequence step.



#### **Escape**

Touching the "Escape" button undoes the previous change.



#### Copy To

"Copy To" buttons are available on the File Manager screen. You may use them to copy files between the Browse and Application folders.



#### Move To

"Move To" buttons are available on the File Manager screen. You may use them to move files between the Browse and Application folders.



#### Select All

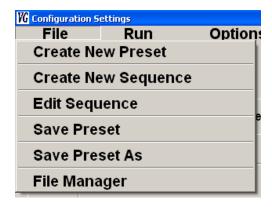
"Select All" buttons are available on the File Manager screen. You may use them to **Move**, **Copy**, or **Delete** at once all files in the user's or Branson's Application folders.

#### 5.5 Pull Down Menus

Use the pull down menus at the top of each screen to navigate between different screens. The title of each screen appears in the screen's title bar.

#### 5.5.1 File Menu

Figure 5.3 File Menu



#### 5.5.1.1 Create New Preset

Select Create New Preset to input new weld Preset names into the controller. The Presets will be saved into the controller's library with default preset values. You may then proceed to the Setup screen to enter the preset's weld parameters. See Section <u>5.10.3 Setup</u> Screen (When Running a Preset) for more information on entering weld parameters.

#### 5.5.1.2 Create New Sequence

Select Create New Sequence to input weld sequences. A sequence is a series of grouped weld presets which are to be executed in a particular quantity and order. Sequences are constructed using existing weld presets stored in the Ultraweld L20's library.

#### 5.5.1.3 Edit Sequence

Touching this option will take you to the Edit Sequence screen where you can modify Sequences.

#### 5.5.1.4 Save Preset

When a preset is modified on the Setup Screen, the preset is modified in running memory. An '\*' symbol is appended to the preset name to indicate that the preset has not been saved. By selecting Save Preset, changes to the preset that is currently running on the Ultraweld L20 are made permanent. This also causes the '\*' to disappear from the preset name.

NOTICE	
<b>f</b>	Unless the preset is saved by selecting Save Preset, all unsaved setup changes will be lost when loading a different preset, closing the VersaGraphix application, or powering off the VersaGraphix Ultraweld L20.

#### 5.5.1.5 Save Preset As

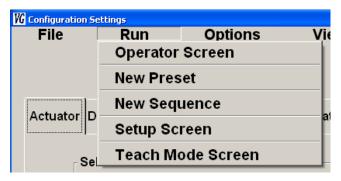
By selecting Save Preset as you can create a copy of the preset currently running on the Ultraweld L20. You will be prompted to supply a new preset name. This new preset will be automatically loaded to memory.

#### 5.5.1.6 File Manager

Selecting File Manager will take you to the Branson File Manager screen. From this screen files can be moved and copied between your directories and Branson's Application Directory. You can also delete files from either your own folders or from Branson's application folders.

#### 5.5.2 Run Menu

Figure 5.4 Run Menu



#### 5.5.2.1 Operator Screen

Touching this button will take you to the operator screen. You can choose the Operator Screen to be the start screen when you turn on your controller. For information see Section 5.11.1.5 System Configuration.

#### 5.5.2.2 New Preset

Select New Preset to load a preset from the Ultraweld L20's library. After selecting a preset the Operator Screen will be displayed.

#### 5.5.2.3 New Sequence

Select New Sequence is used to load a Sequence from the Ultraweld L20's library. After selecting a sequence the Operator Screen will be displayed.

#### 5.5.2.4 Setup Screen

When running a preset, select Setup Screen to change individual weld parameters which are the basic elements required to make a weld. See Section <u>5.10.3 Setup Screen (When Running a Preset)</u> for more details on entering weld parameters.

When running a Sequence, the Setup Screen can be used to monitor results for each weld. Weld parameters cannot be edited when running a sequence.

You can choose the Setup Screen to be the start screen when you turn on your controller. For information see Section 5.11.1.5 System Configuration.



#### 5.5.3 Options Menu

Figure 5.5 Options Menu



#### 5.5.3.1 Configuration

Select this option to access the Configuration screen where Ultraweld L20 features can be setup. These features include: Actuator model; default weld settings; Teach Mode settings; System Configuration; and COM settings.

#### 5.5.3.2 Maintenance

Select this option to access the Maintenance screen. This screen allows adjustment and on-demand control of motion devices used in the actuator. This screen also allows access to the maintenance log, maintenance counters, and limit settings.

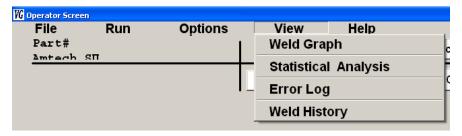
#### 5.5.3.3 Administrator

Select this option to access the Administrator screen. From this screen you can exit the Ultraweld L20 program; determine if Windows should shut down at exit; rename auxiliary buttons; enable password requirement; edit the Administrator and Technician passwords; and set screen permissions.



#### 5.5.4 View Menu

Figure 5.6 View Menu



#### 5.5.4.1 Weld Graph

Selecting this option will display a popup window with a graph showing how the last weld developed over time.

#### 5.5.4.2 Statistical Analysis

Select this option to view weld result data for Time, Power, Pre-Height and Height in relation to their quality windows.

#### 5.5.4.3 Error Log

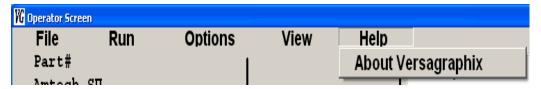
Selecting this option will take you to the Error Log window. In this window the date/time, part name, error type and value for unsuccessful welds can be viewed and printed.

#### 5.5.4.4 Part History

Select this option to view and/or print weld results.

#### 5.5.5 Help Menu

Figure 5.7 Help Menu



#### 5.5.5.1 About VersaGraphix

Select About VersaGraphix to display the VersaGraphix's software version, and Ultraweld L20 version.

#### 5.5.6 Branson Logo

Touching the Branson logo in any of the screens will cause the Language Settings window to pop up.

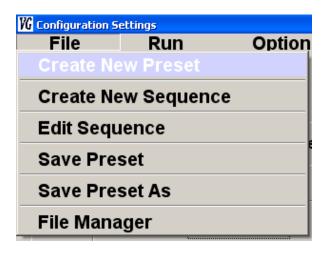
Figure 5.8 Branson Logo



#### 5.6 Create New Preset

Table 5.1 Create New Preset

Step	Action
1	Select Create New Preset from the File Menu.



Step	Action
2	Touch the field next to Preset Name. (An alphanumeric keyboard will pop up). Input the preset name (20 characters max).





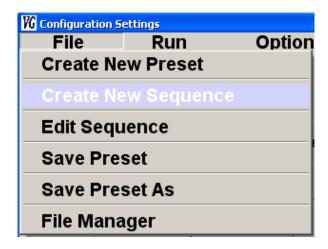
Step	Action
3	Select either Global or Special Teach Mode settings for your preset. Global Settings are set on the Teach tab in the Configuration Screen. For more information, see Section <u>5.11.1.3 Teach Mode Settings</u> .
4	Touch the Insert Pic button to include an image to be displayed on the Operator screen as a visual aid for manufacturing.
5	Press the Enter button to save the preset.

Presets will be saved into the controller's library with default preset values. You may then proceed to the Setup screen to enter the preset's weld parameters. See Section  $\underline{5.10.3}$  Setup Screen (When Running a Preset) for more information on entering weld parameters.

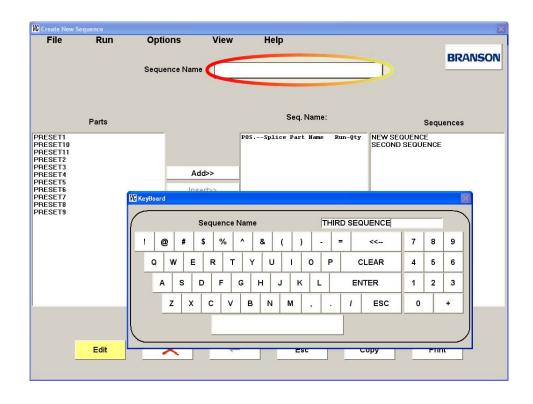
# 5.7 Create New Sequence

Table 5.2 Create New Sequence

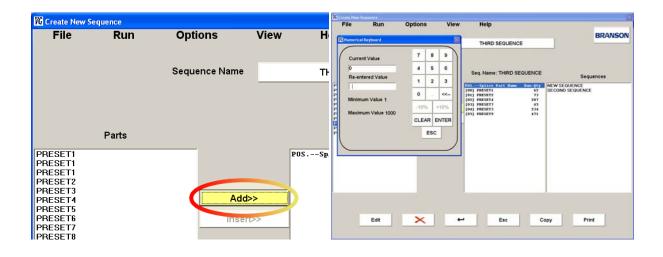
Step	Action
1	From the File menu select Create New Sequence.



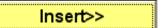
Step	Action
2	Touch the field next to <b>Sequence Name</b> . (An alphanumeric keyboard will pop up). Input the sequence name (20 characters max).



Step	Action
3	Touch the ADD>> button then choose a Preset from the Parts list to add a step. A numerical keyboard will pop up. Enter the number of welds for the step. Each step in a sequence can support multiple welds of a single weld preset.



NOTICE	
1	Touching the <b>Insert</b> button allows user to insert steps. After touching the Insert button select a part from the Parts list. Then touch the position above which you wish to insert it. A numeric key pad will pop up. Enter the amount of welds you wish to make and press enter to insert the step.



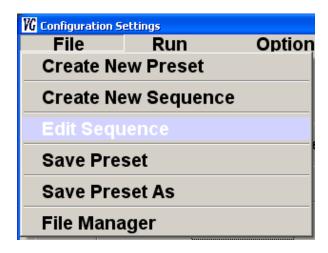
Step	Action
4	Once sequence has been completed touch the <b>Enter</b> button to save it. The VersaGraphix supports up to 250 presets per sequence.

# 5.8 Edit Sequence

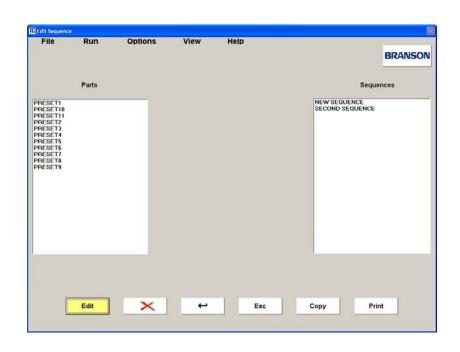
Existing Sequence presets may be edited from the Edit Sequence Screen.

Table 5.3Edit Sequence

Step	Action
1	From the File menu touch the Edit Sequence.



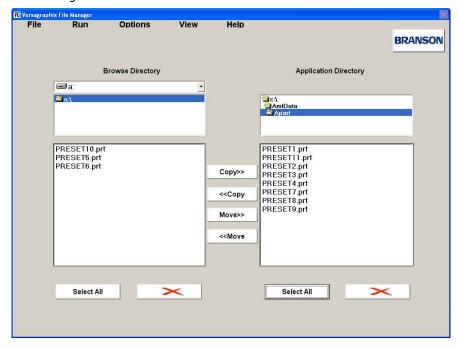
Step	Action
2	Touch the <b>Edit</b> button so that it is highlighted. Select <b>the Sequence</b> preset to be edited from the preset library.



Step	Action
3	A list box with the sequence's steps will appear in the middle of the window. The steps may now be edited (go to Section <u>5.7 Create New Sequence</u> for more information on sequences).
4	Press the enter button to save the changes.

## 5.9 File Manager

Figure 5.9 File Manager screen



The File Manager screen is used to maintain data files used by the application. You may copy Presets, Sequences and History files to and from the VersaGraphix to other storage devices such as USB memory sticks, and external network drives. The Application Directory box shows the files that are available to the application. They are stored in a fixed directory structure as shown. The user's browsing on the controller files is limited to these three directories:

Presets: C:\AmtData\Apart\Prstname.prt

Sequences: C:\AmtData\Aseq\Segname.seg

Log Files: C:\AmtData\history\Wename.tsv

### 5.9.1 Copying Files To The Application

Table 5.4 To copy files from the Application Directory to the Browse Directory

Step	Action
1	Touch the < <copy button,="" highlighted.<="" is="" it="" so="" td="" that=""></copy>
2	Touch the file(s) on the <b>Application Directory</b> that you wish to copy into the <b>Browse Directory</b> .

Table 5.5 To copy files from the Browse Directory to the Application Directory

Step	Action
1	Touch the <b>Copy</b> >> button, so that it is highlighted.

Table 5.5 To copy files from the Browse Directory to the Application Directory

Step	Action
2	Touch the file(s) on the <b>Browse Directory</b> that you wish to copy into the <b>Application Directory</b> .

NOTICE	
1	Only files of types .prt, .seq, and .tsv can be copied using the file manager. They will automatically be put into the appropriate application library directory.

## 5.9.2 Moving Files

Table 5.6 To move files from the Application Directory to the Browse Directory

Step	Action
1	Touch the < <move button,="" highlighted.<="" is="" it="" so="" td="" that=""></move>
2	Touch the file(s) on the <b>Application Directory</b> that you wish to move into the <b>Browse Directory</b> .

Table 5.7 To move files from the Browse Directory to the Application Directory

Step	Action
1	Touch the <b>Move</b> >> button, so that it is highlighted.
2	Touch the file(s) on the <b>Browse Directory</b> that you wish to move into the <b>Application Directory</b> .

NOTICE	
6	Moving files works the same as Copying with the exception that the source file is deleted after the transfer.



## 5.9.3 Deleting Files

 Table 5.8
 To delete files from the either the Application Directory or the Browse Directory

Step	Action
1	Touch the Delete button under the appropriate directory, so that it is highlighted.
2	Touch the files you wish to delete (You will be prompted to confirm).
3	Select Yes to delete the file.
4	Repeat steps 2 and 3 for all the files you wish to delete.

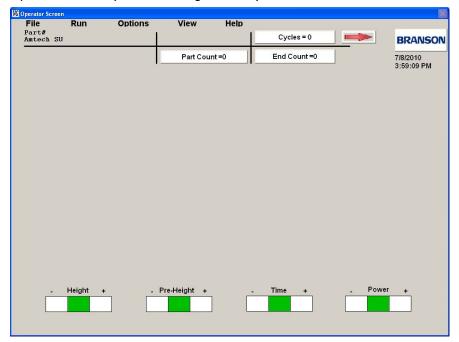
NOTICE	
<b>f</b>	If you Touch the Select All button when the Delete button is highlighted you will be prompted to confirm the deletion of all the files in the directory.

## 5.10 Run Menu

The Run pull down menu contains the following choices:

# 5.10.1 Operator Screen (When Running a Preset)

Figure 5.10 Operator screen (When running a Preset)

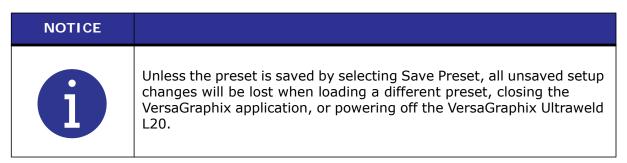


This is the Operator Screen when running a preset. You can choose this screen to be the start screen when you turn on your controller. For information see Section 5.11.1.5 System Configuration.

Displayed on the upper section of the screen are the Preset's name, the part counter (Part Count), cycle counter (Cycles), and the batch size (End Count). The cycle counter keeps track of the amount of welds performed. When the Part Counter equals the End Count the controller will ask if you want to reset the part counter to zero. Touch the **Part Count** or the **Cycles** button to reset the cycle or part counter. Touch the End Count button to enter a new batch size.

Touch the red arrow to switch between the Operator and Setup screens.

When running a preset on the Operator Screen, changes made to the End Count are kept in memory only. The preset name will display a '\*' symbol to note that the preset has not been saved. If a different preset is loaded, the VersaGraphix application is closed, or the VersaGraphix Ultraweld L20 is powered off, unsaved changes will be lost. To save the End Count change to the preset file, select Save Preset from the File menu, or select Save Preset As to save the changes into a new preset file.





# If an image was selected for the preset, it will be displayed on the middle of the screen.

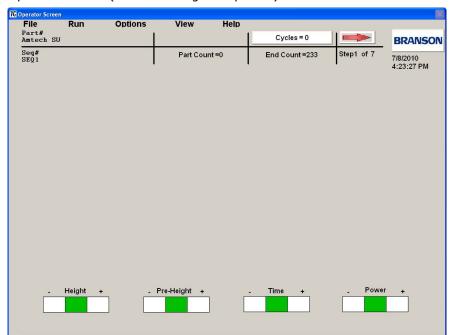
On the bottom of the screen you can see the quality indicators. These indicate visually if the **Height**, **Pre-Height**, **Time**, and **Power** readings fell within the acceptable range for the last weld. They each have three sections. The section in center is the pass section and it will light green when the parameter reading fell within the acceptable range. The left and right sections are, respectively, the fail low, and fail high sections. These sections will light red when the parameter reading fell outside the acceptable range. The controller will also display a pop up window with an alarm message for unsuccessful welds.

Figure 5.11 Result is taller than maximum height message



# 5.10.2 Operator Screen (When Running Sequence)

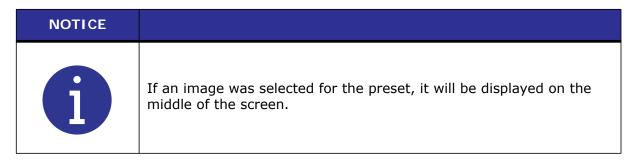
Figure 5.12 Operator screen (When running a Sequence)





This is the Operator Screen when running a sequence. You can choose this screen to be the start screen when you turn on your controller. For information see Section 5.11.1.5 System Configuration.

Displayed on the upper section of the screen are the sequence's name, the current step's Preset name, the part counter (Part Count), cycle counter (Cycles), the step's batch size (End Count) and the current step number. The cycle counter keeps track of the total amount of welds performed while the part counter keeps track of the welds performed for the current step. Touch the **Cycles** button to reset the cycle counter. Touch the red arrow on the upper right side of the screen to go the next step on the sequence.



On the bottom of the screen you can see the quality indicators. These indicate visually if the **Height**, **Pre-Height**, **Time**, and **Power** readings fell within the acceptable range for the last weld. They each have three sections. The section in center is the pass section and it will light green when the parameter reading fell within the acceptable range. The left and right sections are, respectively, the fail low, and fail high sections. These sections will light red when the parameter reading fell outside the acceptable range. The controller will also display a pop up window with an alarm message for unsuccessful welds.

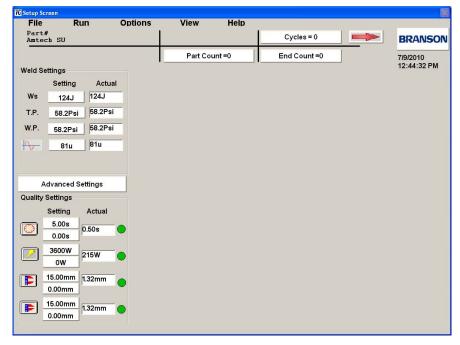
Figure 5.13 Result is smaller than minimum height message





# 5.10.3 Setup Screen (When Running a Preset)

Figure 5.14 Setup screen (When running a Preset)



This screen can be used to setup and fine-tune your weld presets. On this screen you can run and edit Weld, Advanced, and Quality settings for your currently loaded preset. You can choose this screen to be the start screen when you turn on your controller. For information see Section 5.11.1.5 System Configuration.

Displayed on the upper section of the screen are the Preset's name, the part counter (Part Count), cycle counter (Cycles), and the batch size (End Count). The cycle counter keeps track of the amount of welds performed. When the Part Counter equals the End Count the controller will ask if you want to reset the part counter to zero. Touch the **Part Count** or the **Cycles** button to reset the cycle or part counter. Touch the End Count button to enter a new batch size.

Touch the red arrow to switch between the Operator and Setup screens.

In the middle of the screen on the left side are the Weld Settings Box, the Advanced Settings button, and the Quality Settings box. On the right side of each quality parameter a circle is displayed. The circle will light green for successful welds and red for unsuccessful welds. If an image was selected for the preset, it will be displayed on the screen. The controller will also display a pop up window with an alarm message for unsuccessful welds:

Figure 5.15 Result is taller than maximum height





While on the Setup Screen, when running a preset, all changes made to a preset setup are kept in memory only. The preset name will display a ' \* ' symbol to note that the preset has not been saved and a Save Preset Button will appear in the lower-left section of the screen. If a different preset is loaded, the VersaGraphix application is closed, or the VersaGraphix Ultraweld L20 is powered off, unsaved changes will be lost. To save the setup changes to the preset file, touch the Save Preset button, select Save Preset from the File menu, or select Save Preset As to save the changes into a new preset file.

NOTICE	
1	Unless the preset is saved by selecting Save Preset, all unsaved setup changes will be lost when loading a different preset, closing the VersaGraphix application, or powering off the VersaGraphix Ultraweld L20.

#### 5.10.3.1 Weld Settings

In the Weld Settings box you can see the actual readings for the last weld on the rightmost column. You may alter the parameter settings by touching the buttons on the center column. The parameters:

Watt/seconds (Ws): The amount of energy (in joules) delivered on each weld.

**Trigger Pressure (T.P):** The clamping pressure that needs to be exerted to the parts before applying ultrasonic energy.

Weld Pressure (W.P): The clamping pressure applied to the parts during a weld.

**Amplitude (** ): The amplitude (in microns) of the applied ultrasonic vibration. If an amplitude stepping mode has been selected on the Advanced Settings window, you will be able to enter Amplitude A, Amplitude B, and a Step Point.

#### 5.10.3.2 Quality Settings

In the Quality Settings box you can see the actual readings for the Time, Energy, Pre-Height, and Height of the last weld. You may also adjust the acceptable range for the following quality parameters.

**Time(**) max/min: The max/min time that the ultrasonic energy may be applied to a weld.

Energy( ) max/min: The max/min power which may be applied to a weld.

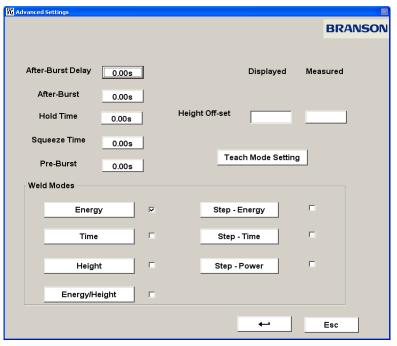
**Pre-Height( parts**) max/min: The max/min height of the parts before welding. This is a pre-welding inspection reading from the height encoder.

Height ( ) max/min: The max/min height of the resulting weld.



#### 5.10.3.3 Advanced Settings Screen

Figure 5.16 Advanced Settings screen



This window allows access to the advanced weld settings described below. These values will normally reflect the default settings made in the Configuration Settings screen on the Settings tab. Values set on this window will only affect the current preset's settings.

#### Parameters:

- After Burst (s): Used to fire sonics for a predetermined amount of time after the weld is complete and after After burst delay times out
- After Burst Delay (s): Used to delay after burst. Delay should be set so that no force is on the part
- Hold time (s): Delays the release of the weld. Used to remove discoloration from the weld
- Squeeze Time (s): Delay the weld for a predetermined amount of time. Allows the force of the cylinder to build up on the part before welding
- **Pre Burst (s)**: Used to fire sonics for a predetermined amount of time after the Squeeze Time and before capturing the Pre-Height. Used when welding magnet wire. It helps to break up the insulation around the copper, and provide a small cooling period before the weld takes place

#### Weld Modes:

- Energy: Ultrasonics are activated until the specified amount of Energy (Watts integrate over time) has been applied
- Time: Ultrasonics fire for a predetermined amount of time
- **Height**: Ultrasonic energy is applied until a predetermined height is reached
- Energy/Height Compensation: Used for contaminated parts. The controller will first put in the predetermined amount of Energy, it will then look at the final height window. If the final height is not within the window, the controller will then put in up to 3 times more energy to get to the center of the window. Note quality window for time may need to be adjusted when using this mode. Ultraweld L20 will shut down when the upper time limit is exceeded
- Amplitude stepping: There are three stepping modes available: Step Energy, Step Time, and Step Power. If a stepping mode is selected, you must also set the start amplitude, end amplitude, and a step point. After choosing a stepping mode, set the start amplitude, end amplitude and step point by editing the Amplitude setting located in the Weld Settings area of the Setup screen. See Section 2.5.9 Amplitude Stepping for more information

#### Off-set:

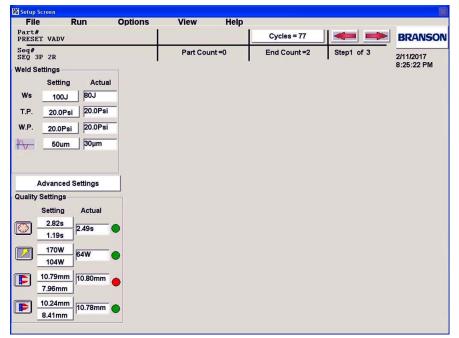
 Height Off-set: Displays the height measurement for the last weld. Touching the button under the Measured column allows the user to enter the height he measured on the last welded piece. The controller automatically adds a corrective offset to its measurements, so displayed values to match the user's measurements

#### **Teach Mode Setting:**

- **Global**: Select Global to use the Teach Mode settings set on the Teach tab on the configuration screen. For more information, see Section <u>5.11.1.3 Teach Mode Settings</u>
- Special: Select Special to enter different Teach Mode settings for the current preset

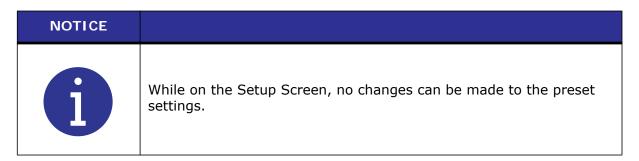
# 5.10.4 Setup Screen (When Running a Sequence)

Figure 5.17 Setup screen (When running a Sequence)



This screen can be used to monitor actual weld and quality results for each weld.

You can choose this screen to be the start screen when you turn on your controller. For information see Section 5.11.1.5 System Configuration.



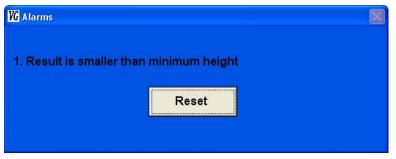
Displayed on the upper section of the screen are the sequence's name, the current step's Preset name, the part counter (Part Count), cycle counter (Cycles), the step's batch size (End Count) and the current step number. The cycle counter keeps track of the total amount of welds performed while the part counter keeps track of the welds performed for the current step. Touch the **Cycles** button to reset the cycle counter. There are two red arrows on the upper right side of the screen. Touching the arrow pointing to the left will

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take you to the previous step on the sequence. Touching the arrow pointing to the right will take you to the next step on the sequence.

In the middle of the screen on the left side are the Weld Settings Box, the Advanced Settings button, and the Quality Settings box. On the right side of each quality parameter a circle is displayed. The parameters shown are the same as the ones described in sections 5.10.3.1 Weld Settings, 5.10.3.2 Quality Settings, and 5.10.3.3 Advanced Settings Screen, but they cannot be modified within the sequence. The circle will light green for successful welds and red for unsuccessful welds. The controller will also display a pop up window with an alarm message for unsuccessful welds.

Figure 5.18 Result is smaller than minimum height



## 5.10.5 Teach Mode Screen

In the Teach Mode screen, the controller automatically derives the quality window's limits based on calculations performed on results from a weld sample set. It is operational in three run screens: Setup Screen, Operator Screen and Statistical Analysis Screen. There are three available teach modes: Standard Teach Mode, Auto Teach Mode, and Sigma Teach Mode. To run Teach Mode click on: Run > Teach Mode Screen. The controller will run in the teach mode currently selected in the TEACH tab in the Configuration Settings window. See Section 5.11.1.3 Teach Mode Settings.

NOTICE	
<b>1</b>	While in any of the Teach Modes, the screen background is orange and the Quality settings are not editable.

NOTICE	
6	Exit the Teach Mode by closing the application, loading a Preset/ Sequence, Saving/Editing a Preset/Sequence, or by switching to following screens: Run New Preset/Sequence, File Manager, Maintenance, Configuration Settings, and Administrator.

NOTICE	
<b>1</b>	You can switch between the Operator Screen, Statistical Analysis screen, Weld Graph screen, Weld History screen and Error Log screen without affecting the Teach process. While in teach mode, the Operator Screen and Statistical Analysis screen will also be shown in orange background.

NOTICE	
1	To start a new Teach process click [Run -> Teach Mode Screen] and select the required preset to be loaded from the list.

NOTICE	
	If you change any Weld/Advanced settings at any time, the Teach mode restarts with wide open quality windows. The preset will be saved at this point.

#### 5.10.5.1 Standard Teach Mode

In the Standard Teach Mode the default quality windows (wide open) are used, and you may accept or reject each weld as part of the sample set. Upon successful completion of the sample set, the average values for Time, Power, Pre-Height, and Height are computed; the allowable min/max deviation percentages are factored in; and the resultant is used to calculate the weld settings and the quality window settings. The quantity of samples to be run and the allowable deviation percentages for each weld parameter are set in the TEACH tab in the Options > Configuration window. See Sections 5.11.1.3 Teach Mode Settings. After completing the Teach process, the Preset and the quality windows settings are saved; the gray Operator Screen is displayed; and you will no longer be in Teach Mode.

#### 5.10.5.2 Auto Teach Mode

In the Auto Teach Mode you may not reject samples. If no changes are made to the Weld/ Advanced settings, the previously saved quality windows are used for the first five welds, which form a basis. Their averaged values for Time, Power, Pre-Height and Height, plus or minus ten percent tolerance, are used to evaluate the acceptability of the remaining samples. If one of the remaining samples falls outside of this range, it is rejected and an alarm occurs. Up to three welds may be rejected in a teach session. If a fourth bad weld is encountered the Auto Teach process starts over with wide open quality windows. The run quantity for Auto Teach Mode can be set in the Teach tab in the Configuration settings window. When the Teach process is complete, the Preset and the quality window settings are saved; the gray Operator Screen is displayed; and the system will be in monitoring mode. While in monitoring mode you can weld normally. The system will restart a complete Auto Teach session automatically if you change any of the weld parameters,

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quality windows settings, recall a new preset, or go to the File Manager, Maintenance, Configuration or Administration screens.

NOTICE	
1	In Auto Teach mode File > Create New Sequence, File > Edit Sequence, Run > New Preset, and Run > New Sequence menu options are always grayed out.

NOTICE	
1	If you go to the Statistical Analysis or the Operator Screen just after selecting Auto Teach option in Configuration screen, the application will go directly into monitoring mode and you will be allowed to weld normally with the currently loaded preset.

NOTICE	
<b>f</b>	If Auto Teach mode is left selected in the configuration screen before powering down, the system will display the operator screen; load the previously loaded preset or default preset; and go directly in to monitoring mode in Auto Teach mode on the next power up.

NOTICE	
1	After Creating a New preset while in Auto Teach mode both Run > Operator Screen and Run > New Sequence menu options are grayed out. The only way to weld is to first go through the Auto Teach process for the newly created preset by clicking Run > Teach Mode Screen.

#### 5.10.5.3 Sigma Teach Mode

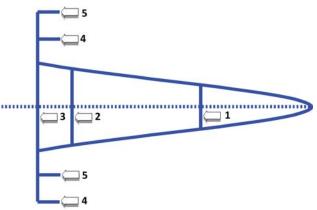
The Sigma Teach mode collects data for the last 128 samples taken for each weld. It limits itself to the last 128 samples to keep data and statistics that will be meaningful to the current sample. The Sigma Teach mode calculates the average and standard deviation for each or the monitored parameters (Time, Power, Preheight, and Height). The early samples are displayed starting on the left of the screen and, as they are added, continue from the left to right.

At 128 and later samples, the oldest data point on the left is removed and the latest data point is added at the right position. Average and standard deviation are always based on the latest data. Removed data has no influence on the calculations.

Standard deviation is calculated with an (n-1) weighting. This tends to make the smaller values of the n have wider standard deviations.

The collected data is displayed between the Upper Specification Limit (USL) and the Lower Specification Limit (LSL). These are the limits as shown on the Run screen. If there are more the 3 samples in the data a Gaussian curve is displayed. The Gaussian curve is positioned between the limits and as much of its data as possible is displayed. There are markers on the curve to show 1, 2, 3, 4, 5, standard deviations. The 1, 2, and 3 markers are vertical while the 4 and 5 are horizontal (see <u>Figure 5.19 Sigma markers</u> below). The most desirable situation is narrow limits with a tight curve.

Figure 5.19 Sigma markers



After completing the Teach process, the Preset and the quality windows settings are saved; the gray Operator Screen is displayed; and you will no longer be in Teach Mode.

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# 5.11 Options Menu

The Options pull down menu contains the following choices:

## 5.11.1 Configuration

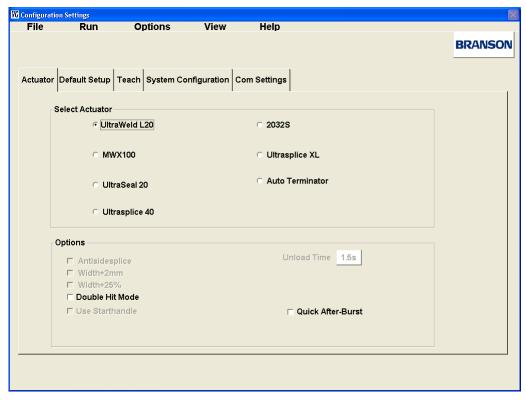
User is allowed to configure the following features of the application.

- Actuator
- · Default Setup
- Teach
- · System Configuration
- Com Settings

#### 5.11.1.1 Actuator

The Actuator tab found in the Configuration screen allows you to setup the VersaGraphix to work with your Actuator model.

Figure 5.20 Actuator Tab



The VersaGraphix can be setup to work with any of the following actuators:

- UltraWeld L20
- MWX100
- Ultraseal 20
- Ultrasplice 40
- Ultrasplice XL
- Auto Terminator

On this tab you may also set the following:

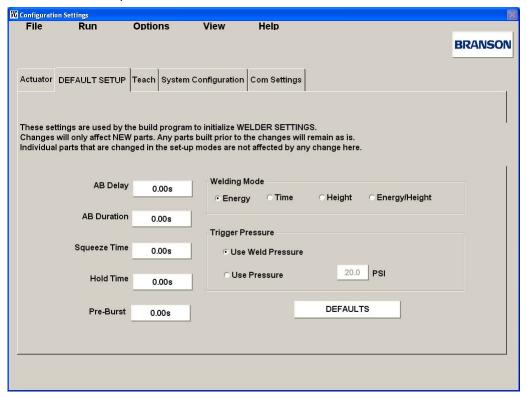
• Double Hit Mode: Used for Automation. Do not activate unless instructed by Branson



 Quick After Burst: The after burst function is implemented immediately after each weld cycle finished without any time delay or condition judgment

## 5.11.1.2 Default Preset Settings

Figure 5.21 Default Setup Tab



Set the default weld settings for all new presets on the Default Setup tab. These settings will only affect new presets. You may set the following parameters:

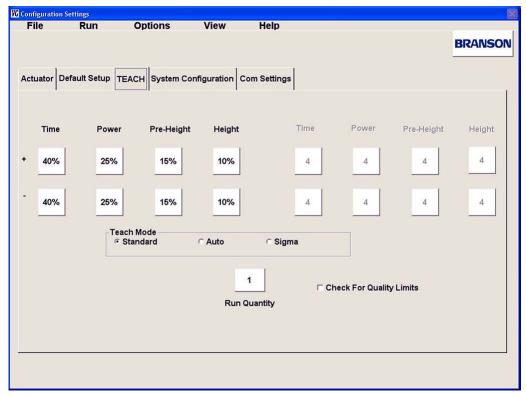
- AB Delay
- AB Duration
- Squeeze Time
- · Hold Time
- Pre-Burst
- Welding Mode
- Trigger Pressure

See Sections <u>5.10.3.1 Weld Settings</u> and <u>5.10.3.3 Advanced Settings Screen</u> for more information on these parameters.



## 5.11.1.3 Teach Mode Settings

Figure 5.22 Teach Tab



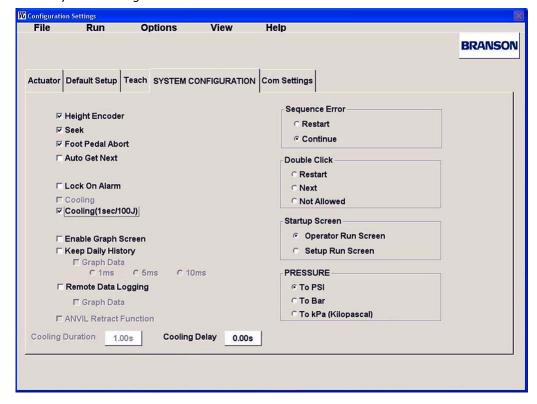
On the Teach tab you may select the teach mode the VersaGraphix will use. There are three different teach modes available: Standard, Auto, and Sigma. On this tab you can set the run quantity and allowable deviation percentages for the Standard or Auto teach modes. See Section 5.10.5 Teach Mode Screen for more information on Teach modes.

#### 5.11.1.4 Check for quality limits

Add the "check for quality limits" check box in the teach tab of the configuration menu to enable/disable (turn ON/OFF) the "Check for Quality Limits" mode. When in the "Check for Quality Limits" mode, if the recalled preset has never been through the teach mode yet, then the preset will be automatically recalled into the teach mode menu; else the system will work as usual and go to Run mode with the recalled preset. If the check box is disabled, the system will also work as usual. In this scenario, all the splices/presets of sequence need to be checked in the sequence mode when a new sequence is recalled. An error message will be shown up on the screen as long as there is anyone unqualified splice/preset in the recalled sequence. Error Message says the following: "Teach Mode Required" then shows the unqualified splice/preset.

#### 5.11.1.5 System Configuration

Figure 5.23 System Configuration Tab



**Height Encoder**: Toggles the height encoder on/off.

**Seek:** Toggles Seek function on/off. This pulses ultrasonic energy to the stack prior to each weld in order to allow the system to tune to stack frequency.

**Foot Pedal Abort**: When this box is checked, foot pedal must be maintained until sonic starts or the weld cycle will be aborted.

**Auto Get Next**: When this box is checked the Ultraweld L20 automatically sequence to the next part. Used in sequencing.

**Lock On Alarm**: Toggles between locking or allowing a weld to continue when an alarm condition exists. When set to lock the actuator will not release the part until a password is entered.

**Cooling:** Enables the setting of a predetermined amount of time the cooling air will stay on after a weld.

**Cooling (1sec/100J):** Automatically sets cooling duration after a weld to 1 second per 100J of energy applied.

**Enable Graph Screen**: Enable Disable Power Graph data.

**Keep Daily History:** When this box is checked the Ultraweld L20 will create a daily folder on the hard drive to store all weld results. If the **Graph Data** box is checked the Ultraweld L20 will also store the weld power readings, sampled every 1ms, 5ms or 10ms (depending on the option that is selected) into a text file.

**Remote Data Logging:** When this box is checked the Ultraweld L20 will send weld results out the Ethernet port at the end of each weld cycle. If the **Graph Data** box is checked the Ultraweld L20 will also send the weld power readings, sampled every 1ms, 5ms or 10ms (depending on the option that is selected).

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**Sequence Error**: Sets what the Ultraweld L20 should do when a weld error occurs when running a sequence. It has two Options:

- Restart to restart the sequence from step 1
- Continue To reweld the same step in the sequence

Double Click: Sets double click action when running a sequence. The options are:

- Restart the sequence to restart the sequence from step 1
- Next to move to the next step of the weld sequence
- Not allowed to disable double click inputs

**Startup Screen**: Sets the screen that will be displayed on powerup. The options are:

- · Operator Run Screen
- · Setup Run Screen

**Cooling Duration**: To change the amount of time the cooling air is on after each weld cycle.

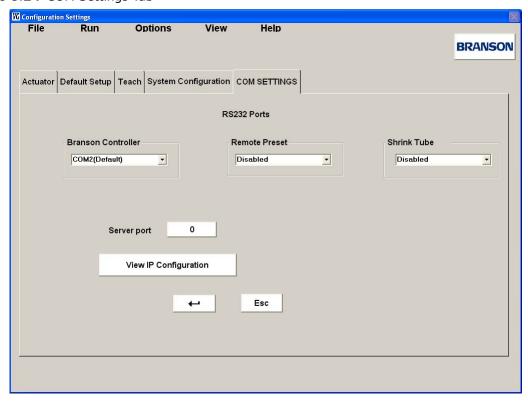
Cooling Delay: To change the delay period after a weld and before cooling is turned on.

**Pressure**: Toggles pressure units between the 3 options available:

- To PSI
- To Bar
- T kPa (Kilopascal)

## **5.11.1.6 COM Settings**

Figure 5.24 COM Settings Tab



On the COM SETTINGS tab you can configure serial port and Ethernet settings to communicate to its internal controller and an external devices.

#### **Branson Ultraweld L20**

The Branson Ultraweld L20 is connected to port COM2 by default.

#### **Remote Preset**

Presets and sequences can be recalled by an external user application connected to one of the available RS-232 serial ports. Use this drop-down selection list to set the serial port to which the application will be connected. The ports available for Remote Preset recall are COM1, through COM4. Baud rate is fixed at 115000 baud.

To recall a Sequence or Preset, a string containing the 'Preset Name' or a 'Sequence Name' followed by a carriage return must be sent by the user application:

#### NAME<CR>

NOTICE	
1	The application will search sequences first, then search presets.

Sequence or Preset to the VersaGraphix application.

The VersaGraphix application returns one of three responses:

**sNAME**<**CR**><**LF**> Application found sequence.

**pNAME**<**CR**><**LF**> Application found preset.

**nNAME**<**CR**><**LF**> Application found neither a sequence or a preset or it found a sequence with a missing preset.

The VersaGraphix application will timeout after 5 seconds if characters are sent without a carriage return <CR>. A response "Timeout" will be sent and the receive buffer will be reset.

#### Shrink tube

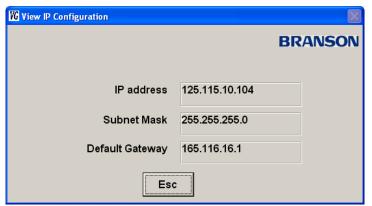
The VersaGraphix Ultraweld L20 can be connected to an external Raychem<sup>®</sup> RBK-ILSProcessor shrink tube machine. Use this drop-down selection list to set the serial port to which the shrink tube machine will be connected.

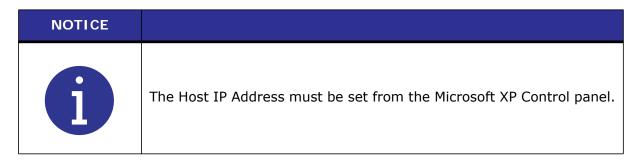


## **View IP Configuration**

Displays the current IP configuration.

Figure 5.25 View IP Configuration





# **Server Port**

Sets the server port that will be used to communicate between the VersaGraphix and user data logging application.

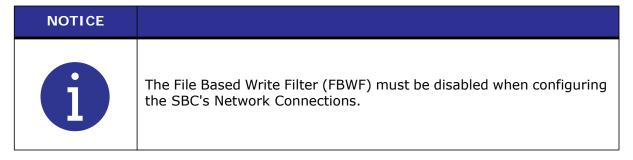
# 5.12 Remote Data Collection

At the end of each weld cycle the VersaGraphix writes a line to the daily history log file if "Keep Daily History" is enabled.

This special will echo this line to a remote user application through an Ethernet socket connection. For this special the data format will be hard coded.

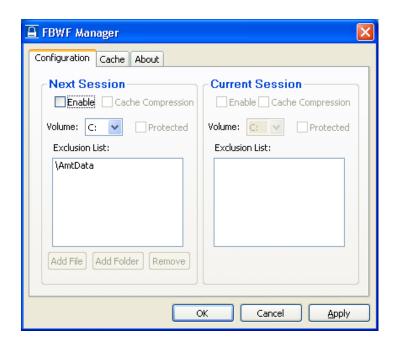
A header will be sent every time the user connects to the socket.

# 5.12.1 Connection to VersaGraphix SBC will be through a TCP/IP socket



The 'Host IP Address' will be set outside the application at the system level.

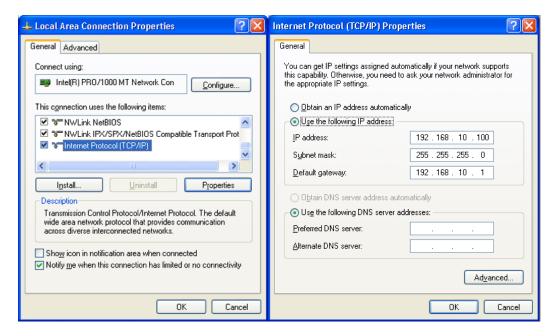
Exit the VGX application Disable the FBWF



Allow the unit to reboot Exit the VGX application

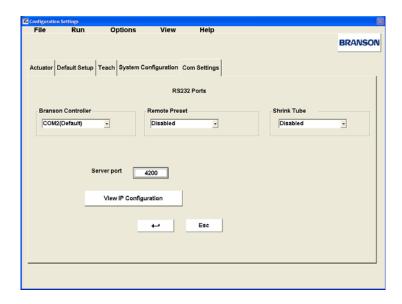
# **BRANSON**

Set the 'Host IP Address' in Windows.



Open the VGX application

Set the 'Server Port Number' to 4200.



Options/Configuration/COM SETTINGS/Server Port'. Default= 4200.

# 5.12.2 Testing Remote Data Collection

Testing and verification will be done using TeraTerm.

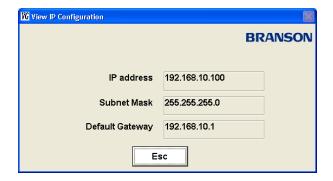
Connect to the VersaGraphix SBC using an Ethernet Cable.

Start TeraTerm Terminal on the remote PC.

Connect Using: TCP/IP



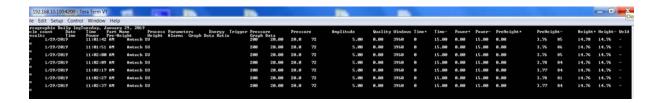
Host Address: (Use IP address of VersaGraphix SBC)



Port Number: 4200 (default)

Make a Weld Cycle

Weld results should be displayed as follows:

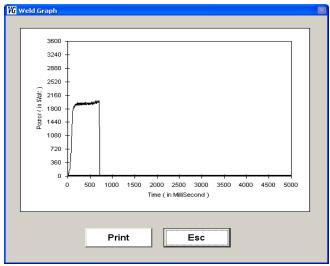


# 5.13 View Menu

The pull down View menu contains the following choices:

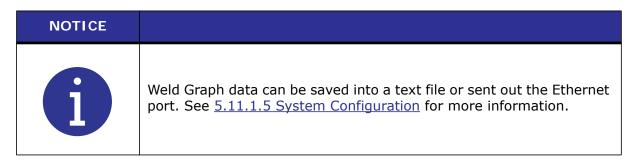
# 5.13.1 Weld Graph

Figure 5.26 Weld Graph



Touch View > Weld Graph to display a pop up window containing a graph of Power (Watts vs. Time) for the last weld performed.

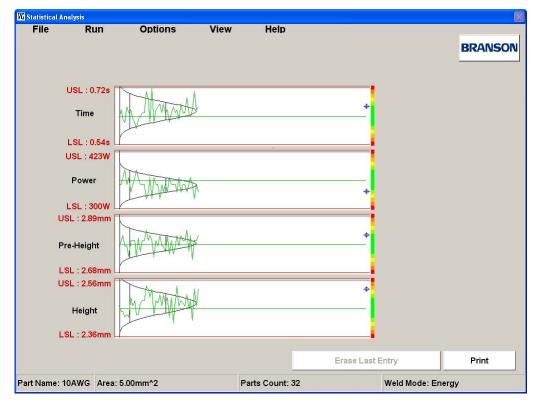
Weld graphs are sometimes referred to as weld "foot print". It can be used to visualize the weld cycle and assists in parameter optimization. Graphs from consecutive welds will vary slightly as the system dynamically adjusts time to accommodate varying surface conditions. (See <u>Figure 2.2 Weld Power Graph for Clean Components</u>, <u>Dirty Components</u>, <u>and when Part is Missing</u>).





# 5.13.2 Statistical Analysis Screen

Figure 5.27 Statistical Analysis Screen



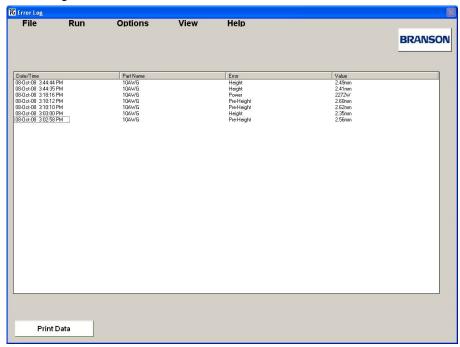
The Statistical Analysis screen displays a histogram and Gauss curves for an accumulation of up to 128 samples of the current part.

The program keeps a file on each part and records each sample as it is run. The file is updated at the end of each weld cycle that does not contain any faults. Weld cycles that contain faults are not included in the data nor is the parts counter increments. The file contains data for the last 128 weld cycles for the current part. If less than 128 cycles are available, only those available are displayed. If more than 128 parts are on the counter, the file is updated by discarding the oldest sample data and adding the latest sample data. The average, standard deviation, and Gauss curves are based on the latest data.

The labels USL and LSL are the upper and lower Specification Limits set on the Setup Screen. The Gauss curves are displayed proportional to the upper and lower specification limits and have markers for the 1, 2, 3, 4, 5 and 6 sigma deviations if they fall inside the limits. No Gauss curves are displayed if the parts counter is less than 3.

# **5.13.3** Error Log

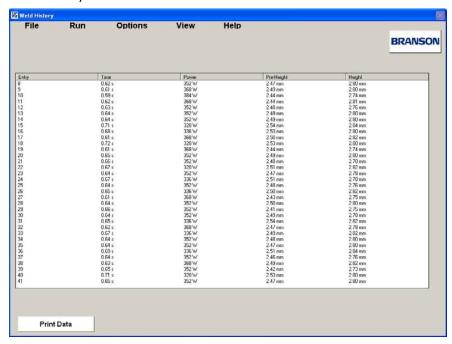
Figure 5.28 Error Log



The Error log keeps track of all unsuccessful welds and their fault cause. You can generate a printout of all errors by touching the Print Data button.

# 5.13.4 Weld History

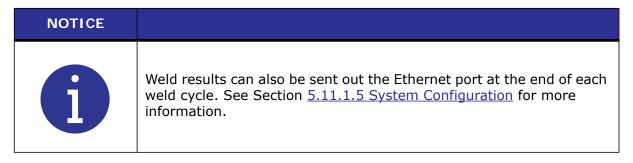
Figure 5.29 Weld History





On the Weld History screen you can view all saved weld results. You can generate a printout of all weld results by touching the Print Data button.

NOTICE	
6	The Keep Daily History checkbox on the Settings tab on the Configuration screen must be checked for the controller to store weld results.



# **BRANSON**

# 5.14 Help Menu

In the Help pull down menu you can select About VersaGraphix to view the VersaGraphix software version and Ultraweld L20 version.

Figure 5.30 About VersaGraphix

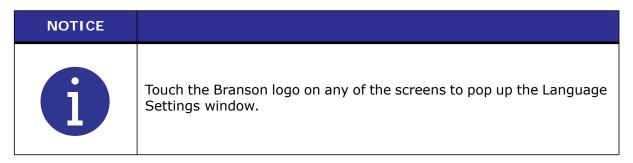


# 5.15 Language Support

Figure 5.31 Language Settings



The VersaGraphix software supports 18 user selectable languages. The supported languages are: English, French, German, Japanese, Russian, Romanian, Portuguese, Spanish, Hungarian, Korean, Polish, Czech, Turkish, Italian, Simplified Chinese, Traditional Chinese, Thai and Slovenian.



# **BRANSON**

# **Chapter 6: Maintenance**

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## 6.1 Preventive Maintenance

WARNING	
<u> </u>	Use LOTO (Lock Out Tag Out) lockable plug cover over line cord plug during any maintenance
	All system components must be disconnected from the main electrical supply
	All system components must be disconnected from the main air supply and system air pressure must be released via the pressure regulator
	When performing maintenance on the welder, make sure that no other automated systems are active

The following preventive measures help assure long term operation of your Branson equipment.

# 6.1.1 Periodically Clean the Equipment

Air is continuously drawn into the Branson VersaGraphix Ultraweld L20. Periodically disconnect the unit from power, remove the cover and vacuum out any accumulated dust and debris. Remove material adhering to the fan blades and motor, transistors, heat sinks, transformers, circuit boards, cooling intake vents, and exhaust ports. Filters can be added to the VersaGraphix cooling fans for dusty environments. External covers may be cleaned with a damp sponge or cloth using a solution of mild soap and water. Do not allow cleaning solution to enter the unit. To prevent rust in areas of high humidity, exposed steel surfaces, such as handles, hardware, and the main column may require a very light film of oil, such as WD-40<sup>®1</sup>.

NOTICE	
<b>1</b>	When it is necessary to clean the touch screen, wipe gently with a soft cloth dampened with a mild window glass commercial cleaner or 50/50 mixture of water and isopropyl alcohol. Use a soft cloth moistened with mild detergent to clean the display housing. Do not use abrasive cleaners, waxes or solvents to clean the touch screen monitor.

# 6.1.2 Routine Component Replacement

The lifetime of certain parts is based on the number of cycles the unit has completed, or on hours of operation, e.g., at 20,000 hours, cooling fans should be replaced.

<sup>1.</sup> WD-40 is a registered trademark of WD-40 Manufacturing Company Corporation.

# 6.2 Parts List

This section provides the list of replacement parts.

Figure 6.1 VersaGraphix Ultraweld L20

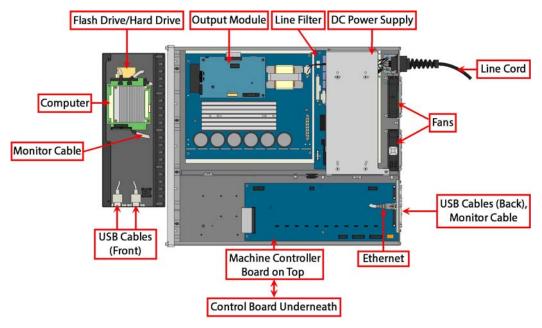


Table 6.1 Suggested Spares

Description	Part Number
Control Board <sup>1</sup>	102-242-1272R
Machine Controller Board	102-242-968
DC Power Supply	200-132-294R
Line Filter	100-242-1199R (100-242-1230R for 4KW units only)
Output Module <sup>2</sup>	Call Branson
Fan	100-126-015R
Line Cord	100-246-947
Touchscreen monitor	200-220-030
Monitor Cable	100-241-426
Computer	Call Branson
Flash Drive/Hard Drive <sup>1</sup>	Call Branson
Ethernet	Call Branson
USB Cables (Front)	100-241-423
USB Cables (Back)	100-241-422

Please go to "About Branson" on the Help dropdown menu for software version and controller version.

<sup>&</sup>lt;sup>2</sup>Have power supply wattage and frequency available for costumer service.



# 6.3 Parts Replacement

CAUTION	
	The Branson VersaGraphix Ultraweld L20 contains components that can be degraded or damaged by electrostatic discharge. Always use a Grounded Wriststrap and use a grounded work area when handling or servicing the VersaGraphix.

The VersaGraphix is designed for a long service life. In the event the system malfunctions, many of the internal components (Modules) are replaceable as a unit. If a particular module has failed, it should be replaced or repaired at an Branson Depot Facility.



# 6.4 Troubleshooting

When the Branson VersaGraphix Ultraweld L20 encounters a situation that is outside normal conditions, an alarm is generated. If there is any alarm condition, the Touchscreen displays an alarm message and generates an audible alarm (see <u>Table 6.2 System Alarms with Probable Cause and Corrective Action</u>). If you use the Emergency Stop button to terminate a weld, the welder will not operate until reset.

# 6.4.1 System Alarms

The following table details alarms that you can encounter on the VersaGraphix, listed alphabetically by the Display Message that is presented on the touchscreen. The message on the touchscreen of VersaGraphix is shown in the first column. The second and third columns indicate the condition that led to the alarm and the corrective action you should take.

 Table 6.2
 System Alarms with Probable Cause and Corrective Action

Alarm Message	Cause	Corrective Action
COM port Error		
EMERGENCY STOP ON!	Emergency stop is active	Unlock emergency stop button
FILE ERROR		
Height System failure	Ultraweld L20 did not see the encoder move 1mm in 1 second	Check air pressure. Check flow controls.
Highest power is above power maximum	Power result above the maximum quality window	
Highest power is below power minimum	Power result below the minimum quality window	
Invalid PASSWORD Re- enter data	Wrong password entered	Enter correct password
Lock On Alarm	Quality windows exceeded. Part is locked down	Enter password to release part.
Password Exists!	Enter different password	
Power OVERLOAD	Power results above the maximum available power	
Result is smaller than minimum height	Final height is below quality window	
Result is taller than maximum height	Final height is above quality window	
Safety System Abort!	Safety system	
Weld longer than maximum time	Weld cycle too long	Check for parts contamination. Make sure correct preset is used. Check tooling for wear.

# **BRANSON**

 Table 6.2
 System Alarms with Probable Cause and Corrective Action

Alarm Message	Cause	Corrective Action
Weld shorter than minimum time	Weld cycle too quick	Check proper preset is used. Check air pressure. Check correct parts are being welded.
Insufficient Storage	Memory has reaches 90% of Capacity	Transfer the History files to an external drive.

# 6.4.2 Safety Circuit Alarms

The Safety Control System within the Controller constantly monitors the system's safety related components for correct operation. When this system detects a fault condition, operation is interrupted and the system immediately goes to a safe state. A beeper is used to signal a safety system alarm.

Use the following procedure to troubleshoot safety circuit alarms:

- 1. Verify that the 9-pin footswitch cable is properly connected to the back of the Controller.
- 2. Power down and then power up the Controller to reset the system.
- 3. If the alarm persists, call Branson Support. See <u>1.5.3 Contact Information</u>

# 6.5 Service Events

WARNING	
	Service events should be performed only by qualified individuals. The potential for injury or death exists, as well as that for damage to the equipment (which can include loss of product warranty) or loss of valuable setup information for your application. When servicing the system, the service person(s) can have a need for certain conventional hand tools, and you might need to have the following information for testing or returning the system to service.

# 6.5.1 Required Tools

Special tools for the ultrasonic Converter, such as spanner wrenches, are provided with your system. You might also need the following hand tools or service tools:

- Six-inch or longer Phillips-head screwdriver with a magnetic tip or screw starter
- Good-quality multi-meter for continuity, AC and DC voltages, and resistance, with insulated test probes

#### 6.5.2 Cold Start Procedure

The VersaGraphix's internal memory stores the system default settings and the parameters that you set. It also provides temporary storage to support the Ultraweld L20's internal functions. A Cold Start clears Battery Backed RAM (BBR) values and restores them to their original factory defaults. It is not necessary to perform a cold start during normal operation and servicing, but you might find a cold start helpful when:

- You suspect the system is not operating properly
- You want to reset the system to its factory default setup

## 6.5.2.1 Performing a Cold Start

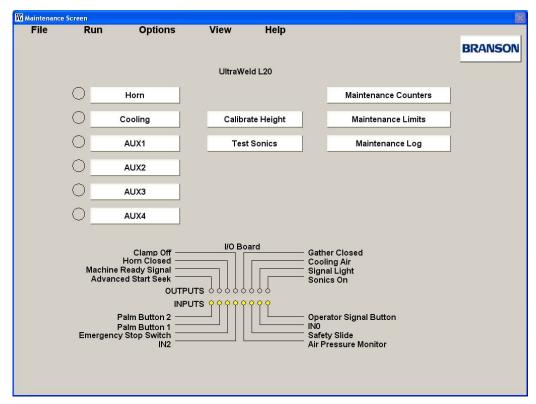
NOTICE	
<b>(1)</b>	Before performing a cold start, the power supply power rating and maximum amplitude should be written down. This information will be needed for input after clearing the BBR. It can be found in the Maintenance Screen under Test Sonics.

To perform a Cold Start touch the Init BBR button on the Options tab in the Administrator screen (see <u>6.5.4.1 Administrator Options Tab</u>). Once a cold start is performed the Height needs to be recalibrated, along with reinstating the calibrated amplitude and power rating.



## 6.5.3 Maintenance Screen

Figure 6.2 Maintenance Screen



The maintenance screen allows the adjustment and on-demand control of electromechanical devices in your actuator. This screen also allows you to clear maintenance counters, set maintenance limits and make entries to the maintenance log.

The left hand set of buttons have indicators associated with them. Touching each of these buttons allows you to:

Horn: Toggle the horn between the up and down positions.

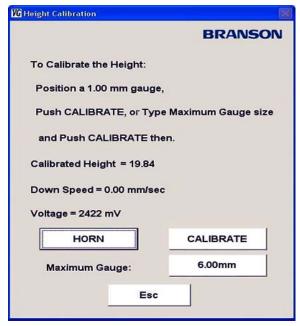
**Cooling:** Toggle the cooling air control solenoid on and off.

**Aux 1-Aux 4**: Toggle auxiliary actuators (used on special equipment). You may rename the auxiliary buttons in order to describe their given function (see <u>6.5.4 Administrator</u> for more information on renaming auxiliary buttons).

The indicators under the **I/O BOARD** label show the current state of digital inputs and outputs.

## 6.5.3.1 Calibrate Height

Figure 6.3 Height Calibration



This window is used to perform a height (from horn to anvil) calibration. The instructions on screen explain the calibration procedure.

The following buttons are used to perform a height calibration:

Horn: To move the horn up and down against the anvil.

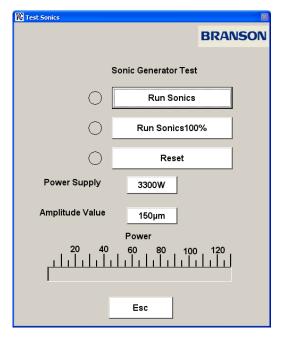
Calibrate: To calibrate the height.

Press the ESC button to return to the Maintenance Screen.

**Maximum Gauge**: To set up the second gauge. Default setting is 6mm. If entered a value which is out of range, a alarm message will show up.

#### 6.5.3.2 Test Sonics

Figure 6.4 Test Sonics



This screen allows the on-demand control of ultrasonic weld energy and the calibration of amplitude.

Amplitude calibration requires a dial indicator to be temporarily mounted in line with, and in front of, the horn, usually on a magnetic base. The Run Sonics 100% is held and the gage reading is viewed.

The gage reading  $x^2 = total$  amplitude, this is the value to be entered as the amplitude value when calibrating.

The following buttons are used to test the Power supply and to calibrate the amplitude:

Run Sonics: Used to fire ultrasonic energy at the current amplitude setting.

**Run Sonics 100%:** Used to fire ultrasonic energy at 100% amplitude. Used when calibrating amplitude.

**Power:** Power rate is displayed in real-time.

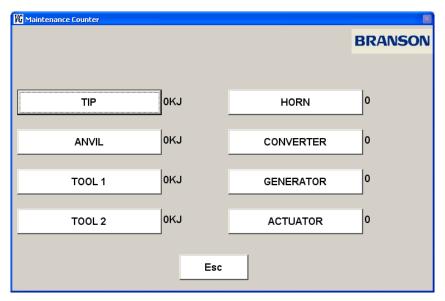
**Power supply button:** This value is set by Branson for a given actuator and should not be changed. Generally the setting for 20 kHz actuators is 3300W and the setting for 40 kHz actuators is 800W.

**Amplitude Value Button:** Used to set the amplitude value based on the gage reading. See above.

Press the **ESC** button to return to the Maintenance Screen.

#### 6.5.3.3 Maintenance Counters

Figure 6.5 Maintenance Counters



The lifetime of certain parts of your Branson system is based on the number of weld cycles performed, or the energy delivered for welding. Other parts require periodic maintenance depending on the number of cycles performed, or the energy delivered for welding. Maintenance Counters allow you to easily keep track of your system's maintenance requirements.

Maintenance counters and Maintenance limits are related. They are used in conjunction to schedule component maintenance or replacement. Maintenance counters increment after each weld cycle up to the limits set by the user on the Maintenance Limits screen. When a limit is exceeded the VersaGraphix will display warning on screen the next time it is turned on. Any maintenance counter which value is less than its corresponding limit does not produce an alarm. See <u>6.5.3.4 Maintenance Limits</u> for more information on maintenance limits.

The maintenance counter window allows you to reset the counters to zero. Touch the name of the counter you want to reset (you will be prompted to confirm).

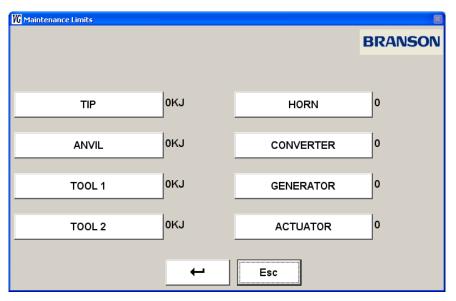
A maintenance counter should be reset after a maintenance is performed on the part it relates to.

Press **ESC** to return to the maintenance screen.



#### 6.5.3.4 Maintenance Limits

Figure 6.6 Maintenance Limits



The lifetime of certain parts of your Branson system is based on the number of weld cycles performed, or the energy delivered for welding. Other parts require periodic maintenance depending on the number of cycles performed, or the energy delivered for welding. Maintenance Counters allow you to easily keep track of your system's maintenance requirements.

Maintenance counters and Maintenance limits are related. They are used in conjunction to schedule component maintenance or replacement. Maintenance counters increment after each weld cycle up to the limits set by the user on the Maintenance Limits screen. When a limit is exceeded the VersaGraphix will display warning on screen the next time it is turned on. Any maintenance counter which value is less than its corresponding limit does not produce an alarm. See Section <u>6.5.3.3 Maintenance Counters</u> for more information on maintenance counters.

The **Maintenance Limits** window allows you to set the maintenance limits for the listed items. Touch the name of the counter limit you want to set and a numeric keypad will pop up so you can set the counter limit. If a limit is set to 0 the controller will not yield an alarm for the counter regardless of its maintenance count.

The left side counter limits for the Tip, Anvil, Tool 1 and Tool 2 are set in kilo-joule units. For example, if the energy weld setting in use is 1500 joules, a limit setting of 7500 kilo joules will produce about 5000 cycles before reaching its limit. The Tool 1 and Tool 2 counters may be used to represent any special fixture tooling.

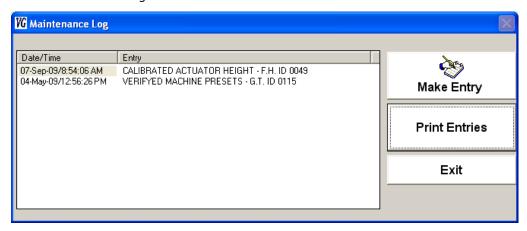
The right side four values on the screen for horn, converter, generator (ultrasonic power supply), and actuator are set in number of weld cycles.

Press the enter button to save the changes.

Press **ESC** to return to the maintenance screen without saving the changes.

## 6.5.3.5 Maintenance Log

Figure 6.7 Maintenance Log

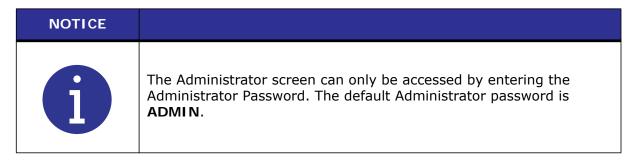


The VersaGraphix has a built in Maintenance log that allows you to keep track of maintenance or testing done to your system.

On the Maintenance Log pop up window you can make entries to the controller maintenance log. Entries are limited to 100 characters per entry. You may also generate a printout of all currently stored entries.

## 6.5.4 Administrator

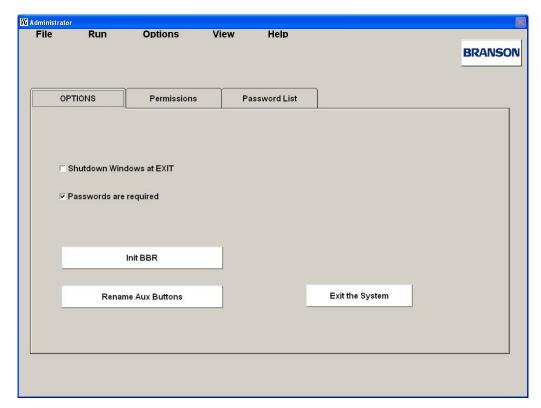
On the Administrator screen you can perform a system Cold Start; exit the VersaGraphix software; shut down the system; and manage password requirements and screen access permissions.





## 6.5.4.1 Administrator Options Tab

Figure 6.8 Administrator Options Tab

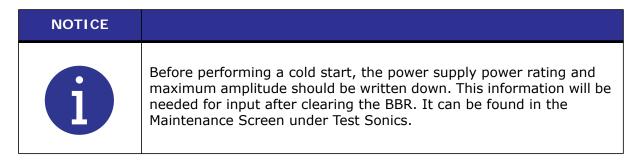


On this Tab you have the following check boxes and buttons:

**Shutdown Windows at EXIT**: Set this checkbox if you want the system to shut down when the Exit System button is pressed. If left unchecked the Software will give control to windows when the Exit System button is pressed.

**Passwords are required:** Set this checkbox to make passwords required when accessing the Maintenance, Setup, Configuration, Create Preset/Sequence, Edit Preset/Sequence, and Teach Mode screens, as set on the Permissions tab. See  $\underline{6.5.4.2}$  Administrator Permissions Tab.

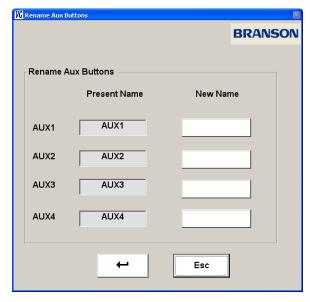
**Init BBR**: Touch the init BBR button to perform a Cold start. Touching this button resets the VersaGraphix's BBR (Battery Backed Ram) to its initial factory defaults. See Section <u>6.5.2 Cold Start Procedure</u> for more information on performing a Cold Start.



Rename Aux Buttons: Touching this button will cause the Rename Aux Buttons window to pop up. On this Window you may rename the four Auxiliary buttons shown on the maintenance screen. These buttons are used to control additional actuators on special

systems in order to perform maintenance activities. See Section <u>6.5.3 Maintenance Screen</u>.

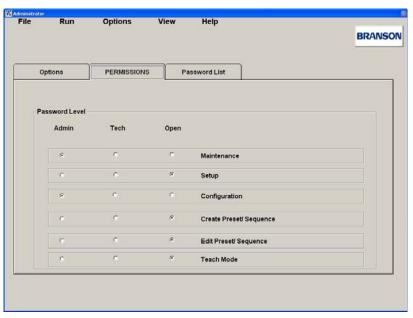
Figure 6.9 Rename Aux Buttons



**Exit the system:** Touch this button to exit the VersaGraphix's software. If the Shutdown Windows at EXIT checkbox is checked, the system will shut down completely. If left unchecked, the software will exit and give control to the Windows OS.

#### 6.5.4.2 Administrator Permissions Tab

Figure 6.10 Administrator Permissions Tab



On this tab you can assign password requirements for the Maintenance, Setup, Configuration, Create Preset/Sequence, Edit Preset/Sequence, and Teach Mode screens. There are three possible security levels you can assign to these screens:

**Open:** Set the radio button to Open to make this screen accessible without a password.

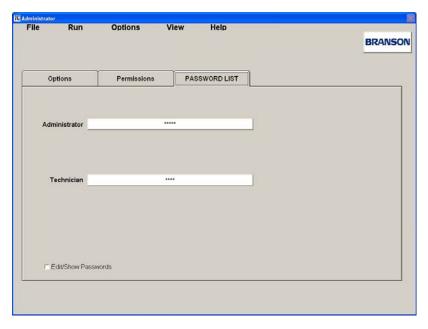
**Tech**: Set the radio button to Tech to make this screen accessible using either the Technician or Administrator passwords.



**Admin**: Set the radio button to Admin to make this screen accessible only by using the Administrator password.

## 6.5.4.3 Administrator Password List Tab

Figure 6.11 Administrator Password List Tab



On this tab you may edit Both the Administrator and Technician passwords. First you must check the Edit/Show Passwords check box, to make the passwords visible and editable. Having this checkbox unchecked protects the passwords from being modified.

