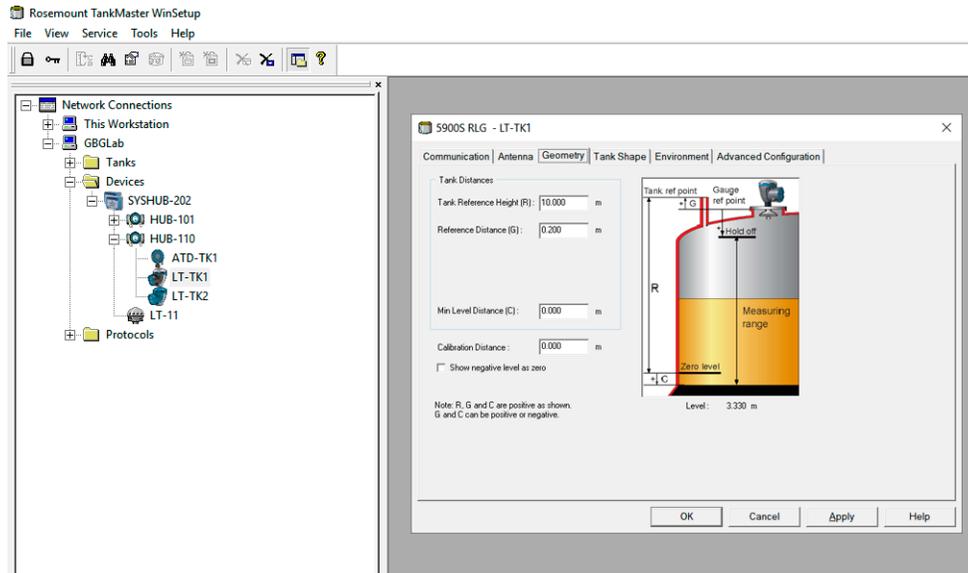


# Rosemount™ Tank Gauging System Configuration

## System configuration



## NOTICE

Read this manual before working with the product. For personal and system safety, and for optimum product performance, ensure you thoroughly understand the contents before installing, using, or maintaining this product.

For equipment service or support needs, contact your local Emerson Automation Solutions/Rosemount Tank Gauging representative.

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### Version

This manual is based on the functionality of TankMaster WinSetup version 6.x. For older TankMaster versions all functionality described in this manual may not be available and the Graphical User Interface (GUI) may look different.

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# 1 Introduction

## 1.1 Manual overview

This manual provides information on installation, configuration and maintenance of the Rosemount™ 2410 Tank Hub.

Chapter [Introduction](#) provides a brief description of the various components in a Rosemount Tank Gauging system.

Chapter [Device installation](#) is a description of how to use TankMaster WinSetup to install devices in a Rosemount Tank Gauging system.

Chapter [Tank installation](#) is a description of how to use TankMaster WinSetup to install tanks and associate devices to tanks in a Rosemount Tank Gauging system.

Chapter [Device handling](#) is a short description of the basic functions for changing device configuration and how to uninstall devices from the WinSetup workspace.

## 1.2 Technical documentation

The Rosemount™ Tank Gauging System includes a wide portfolio of user documentation. For a complete list, see product pages on [Emerson.com/Rosemount](https://www.emerson.com/Rosemount).

### Reference manuals

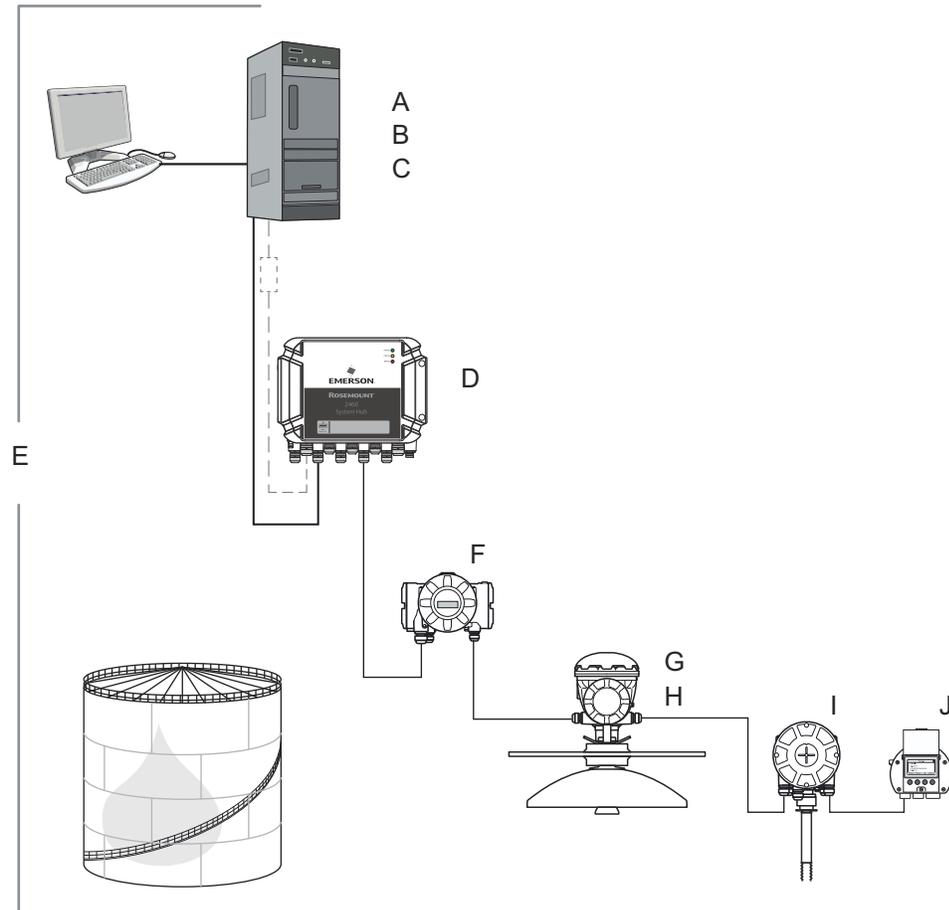
- Rosemount Tank Gauging System Configuration Manual (00809-0300-5100)
- Rosemount 2460 System Hub (00809-0100-2460)
- Rosemount 2410 Tank Hub (00809-0100-2410)
- Rosemount 5900S Radar Level Gauge (00809-0100-5900)
- Rosemount 5900 Proof Test with Reference Reflector (00809-0200-5900)
- Rosemount 5900C Radar Level Gauge (00809-0100-5901)
- Rosemount 2240S Multi-Input Temperature Transmitter (00809-0100-2240)
- Rosemount 2230 Graphical Field Display (00809-0100-2230)
- Rosemount 5300 Guided Wave Radar (00809-0100-4530)
- Rosemount 5408 Radar Level Transmitter (00809-0300-4408)
- Rosemount Tank Gauging Wireless System (00809-0100-5200)
- Rosemount TankMaster WinOpi (00809-0200-5110)
- Rosemount TankMaster Software Installation Manual (00809-0400-5110)
- Rosemount TankMaster WinSetup (00809-0100-5110)
- Rosemount TankMaster Floating Roof Monitoring (00809-0500-5100)
- Rosemount TankMaster Network Configuration (303042EN)
- Rosemount 5900 Radar Level Gauge and Rosemount 2410 Tank Hub Safety Manual Option S (00809-0400-5100)
- Rosemount TankMaster Mobile User Guide (00809-0100-5120)
- Rosemount TankMaster Mobile Installation Manual (00809-0200-5120)

### Product data sheets

- Rosemount Tank Gauging System ([00813-0100-5100](#))
- Rosemount TankMaster Inventory Management Software ([00813-0100-5110](#))
- Rosemount TankMaster Mobile Inventory Management Software ([00813-0100-5120](#))
- Rosemount 2460 System Hub ([00813-0100-2460](#))
- Rosemount 2410 Tank Hub ([00813-0100-2410](#))
- Rosemount 5900S Radar Level Gauge ([00813-0100-5900](#))
- Rosemount 5900C Radar Level Gauge ([00813-0100-5901](#))
- Rosemount 2240S Multi-input Temperature Transmitter ([00813-0100-2240](#))
- Rosemount 565/566/765/614 Temperature and Water Level Sensors ([00813-0100-5565](#))
- Rosemount 2230 Graphical Field Display ([00813-0100-2230](#))
- Rosemount 5300 Level Transmitter ([00813-0100-4530](#))
- Rosemount 5408 Level Transmitter ([00813-0100-4408](#))

## 1.3 Document structure

Figure 1-1: System and User Documentation Structure



- A. *Rosemount TankMaster WinSetup Reference Manual*
- B. *Rosemount TankMaster WinOpi Reference Manual*
- C. *Rosemount TankMaster Software Installation Manual*
- D. *Rosemount 2460 System Hub Reference Manual*
- E. *Rosemount Tank Gauging System Configuration Manual*
- F. *Rosemount 2410 Reference Manual*
- G. *Rosemount 5900S Reference Manual*
- H. *Rosemount 5900C Reference Manual*
- I. *Rosemount 2240S Reference Manual*
- J. *Rosemount 2230 Reference Manual*

## 2 Device installation

This section describes how to install and configure a Rosemount Tank Gauging system by using the Rosemount TankMaster WinSetup configuration program.

### 2.1 System configuration overview

#### 2.1.1 Preparations

Before installing a Rosemount Tank Gauging system you should ensure that the following information is available:

- A plan of all field devices and tanks.
- Unit IDs of each device (Unit ID is a unique identifier given to each device at factory).
- Modbus® addresses of level devices and ATD devices. The devices are shipped with default addresses which will be changed at system configuration. The Modbus addresses are configured in the Rosemount 2460 System Hub's Tank Database as well as the Rosemount 2410 Tank Hub's Tank Database as described below.
- Tank geometry parameters and reference distances such as tank Reference height (R) and distance between Zero level (datum plate) and tank bottom.
- Antenna type for the various level gauges.

#### 2.1.2 Installation procedure

Installation and configuration of a Rosemount Tank Gauging system includes the following steps as briefly described below.

##### Procedure

1. Setup communication protocols.

Specify communication protocol parameters:

- The Modbus® Master Protocol handles communication between a TankMaster work station and field devices such as the Rosemount 2460 System Hub and the Rosemount 2410 Tank Hub.
- The Slave Protocol handles communication with a host computer.
- Communication with TankMaster can be supervised by logging various error types and function codes.

2. Configure preferences.

Specify measurement units, tag prefixes for tank and device labels, inventory parameters, and parameters to be displayed when viewing tank data.

3. Install and configure the Rosemount 2460 System Hub.

The Rosemount 2460 System Hub has to be installed and configured prior to installing other devices such as a Rosemount 2410 Tank Hub and a Rosemount 5900S Radar Level Gauge.

- a) Assign a Modbus communication address
- b) For each communication port, configure protocol and appropriate communication parameters
- c) Configure the Tank Database with information about the devices connected to the fieldbus

4. Install and configure Rosemount 2410 Tank Hubs.

The Rosemount 2410 Tank Hub should be installed after the Rosemount 2460 System Hub and prior to the other field devices. In case no system hub is used, the tank hub can be connected directly to a TankMaster work station. Installing a Rosemount 2410 Tank Hub includes the following main steps:

- a) Specify a device tag
- b) Assign a Modbus communication address
- c) Configure the Tank Database to map devices to tanks
- d) Optional: Configure the local display

5. Install and configure field devices

In a Rosemount Tank Gauging system, the field devices such as level gauges and temperature transmitters, are installed in TankMaster WinSetup as part of the Rosemount 2410 installation procedure. The devices are configured at a later stage by using the Properties window for each device.

Installation and configuration of devices include the following steps:

- a) Communication: specify protocol and address.
- b) Configuration: specify tank geometry parameters, device specific parameters, temperature element positions, and other parameters depending on the device type.

6. Install and configure tanks.

Installing a tank includes the following steps:

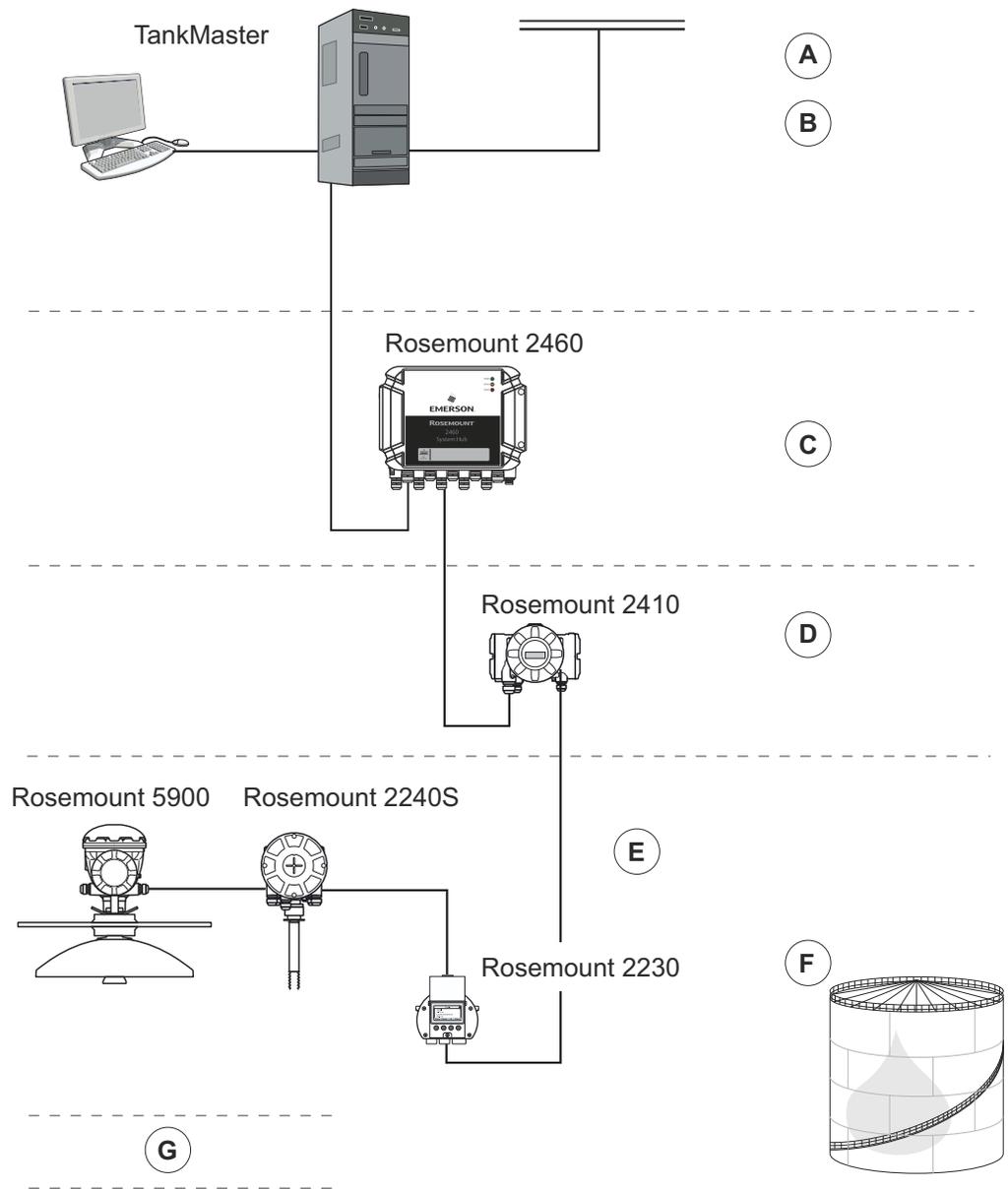
- a) Select tank type. Select one of the available options such as Fixed Roof, Floating Roof, Sphere LPG, Horizontal LPG, or any other suitable tank type.
- b) Specify a tank tag. The name will be used as an identifier in the Workspace window and other TankMaster windows.
- c) Select devices. Associate devices to the tank.
- d) Configuration. Specify the available source signals for parameters such as Free Water Level, Vapor Pressure and Liquid Pressure.
- e) Value Entry. Specify an approved value range for Level, Ullage, and Free Water Level. In case there is no source instrument available, you can specify manual values to be used instead.

7. Calibrate.

Once a Rosemount 5900 Radar Level Gauge is installed and configured, the **Calibration Distance** parameter may have to be adjusted in order to ensure that measured level and actual product level match. The adjustment should be performed once at the final commissioning.

## Installation procedure

Figure 2-1: Rosemount Tank Gauging system installation Procedure



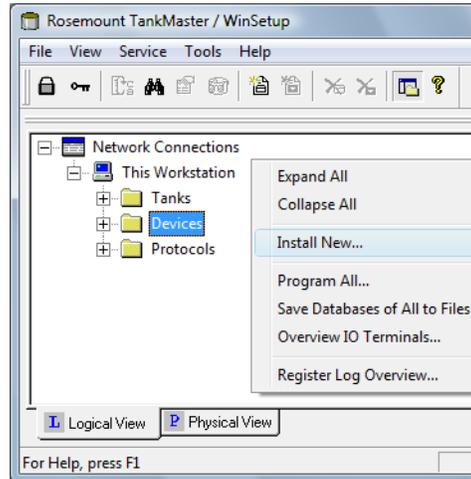
- A. Communication setup
- B. Preferences
- C. Rosemount 2460 System Hub installation and configuration
- D. Rosemount 2410 Tank Hub installation and configuration
- E. Device installation and configuration
- F. Tank installation and configuration
- G. Calibration

## 2.1.3 Using the device installation wizard

The device installation wizard guides you step-by-step through the installation procedure.

### Procedure

1. In the TankMaster WinSetup workspace, select the **Devices** folder.



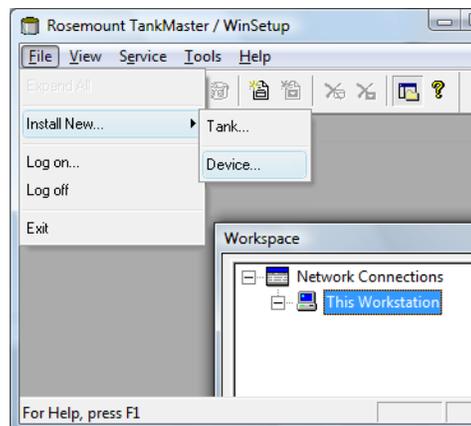
2. Do one of the following:
  - Click the right mouse button and select **Install New** from the popup menu.
  - From the **Service** menu select **Devices** → **Install New**.

## Starting device installation wizard from File menu

As an alternative method to start the device installation wizard you can use the following method.

### Procedure

1. In the TankMaster WinSetup workspace, select the server where your system is installed.



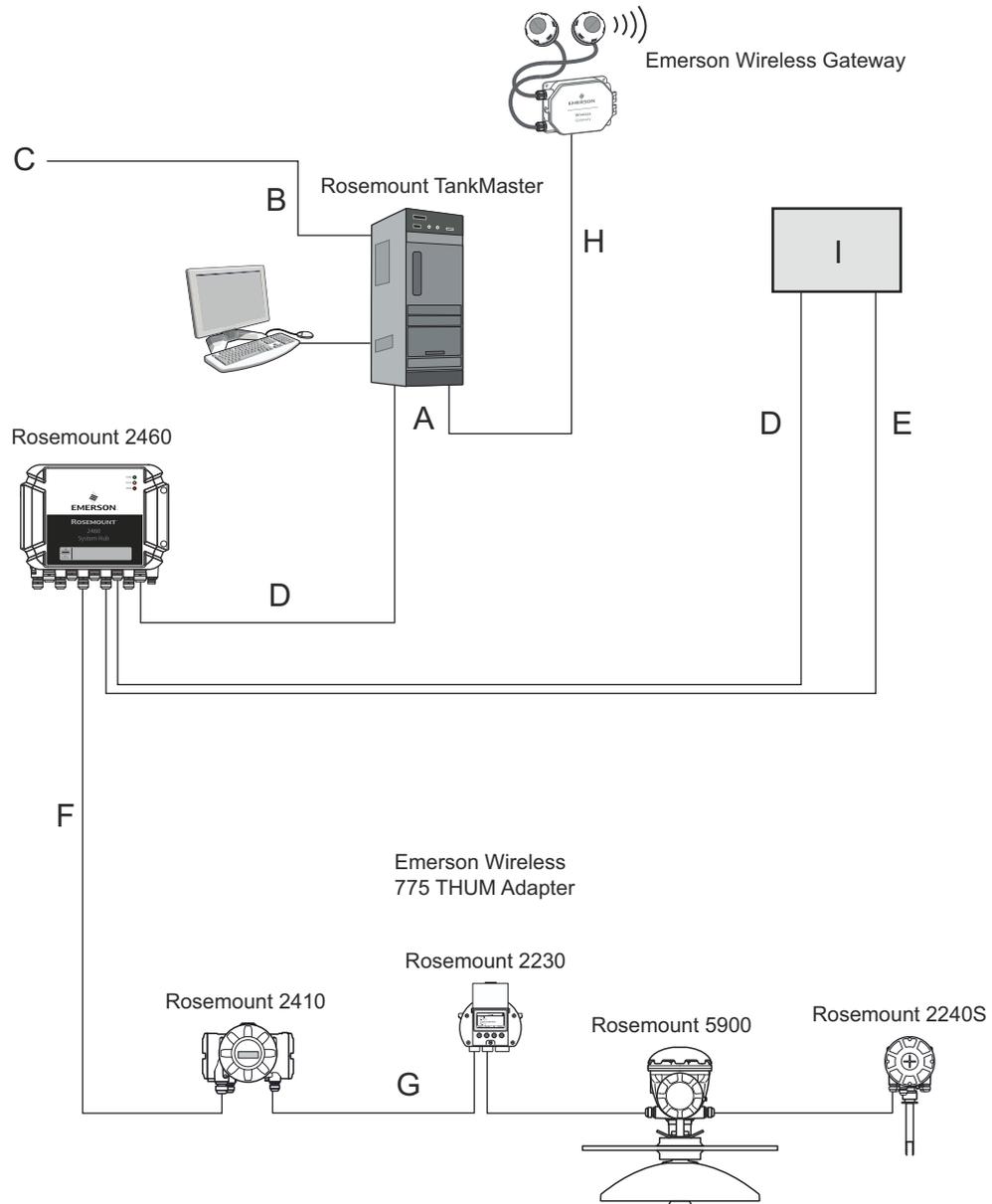
2. From the **File** menu select **Install New** → **Device**.

## 2.2 Communication protocol setup

The TankMaster work station can be connected to field devices and host computers by using Master and Slave protocols. The Modbus Master protocol is available as default protocol when the Rosemount TankMaster software is installed on a TankMaster work station. Optional protocols, such as the Modbus<sup>®</sup> Slave protocol for communication with host systems, can be obtained as well. Please contact Emerson Automation Solutions/Rosemount Tank Gauging for more information.

A Modbus protocol offers up to eight channels. Enraf and HART protocols support 16 channels. For each channel you can specify various settings such as communication type (for example Modbus TCP or Modbus RTU) and which PC communication port (USB/COM) to connect to, as well as standard communication parameters such as Baud Rate, Parity, and number of Stop Bits.

**Figure 2-2: Communication with Various Rosemount Tank Gauging Devices**



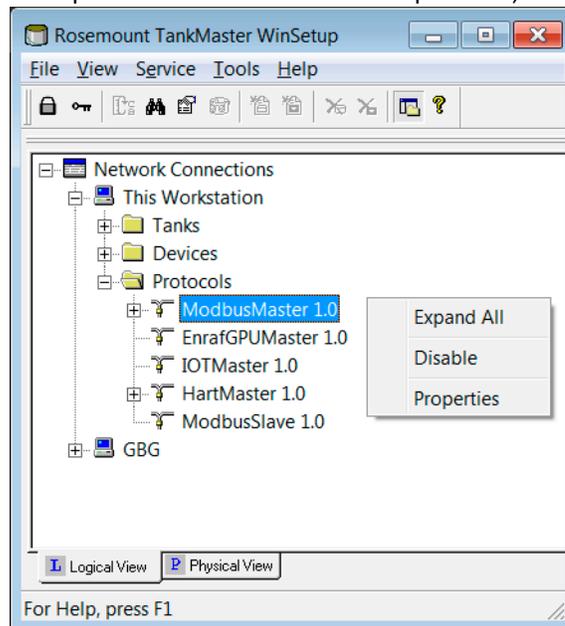
- A. Master protocol (OPC, Modbus RTU)
- B. Slave protocol
- C. To host computer (PLC, SCADA, DCS)
- D. Modbus TCP (Ethernet)
- E. Modbus RTU (RS232/RS485)
- F. Modbus RTU (TRL2/RS485)
- G. Tankbus
- H. HART TCP (Ethernet)
- I. Host computer

## 2.2.1 Master protocol channel configuration

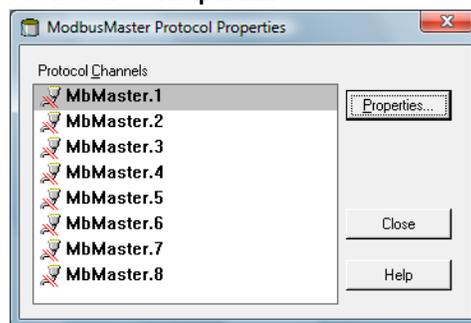
This section describes how to configure the Modbus® Master protocol channel by using Rosemount TankMaster WinSetup.

### Procedure

1. Open the **Protocols** folder in the Workspace window.
2. Select the icon that corresponds to the particular protocol to be configured (this example shows the Modbus Master protocol).

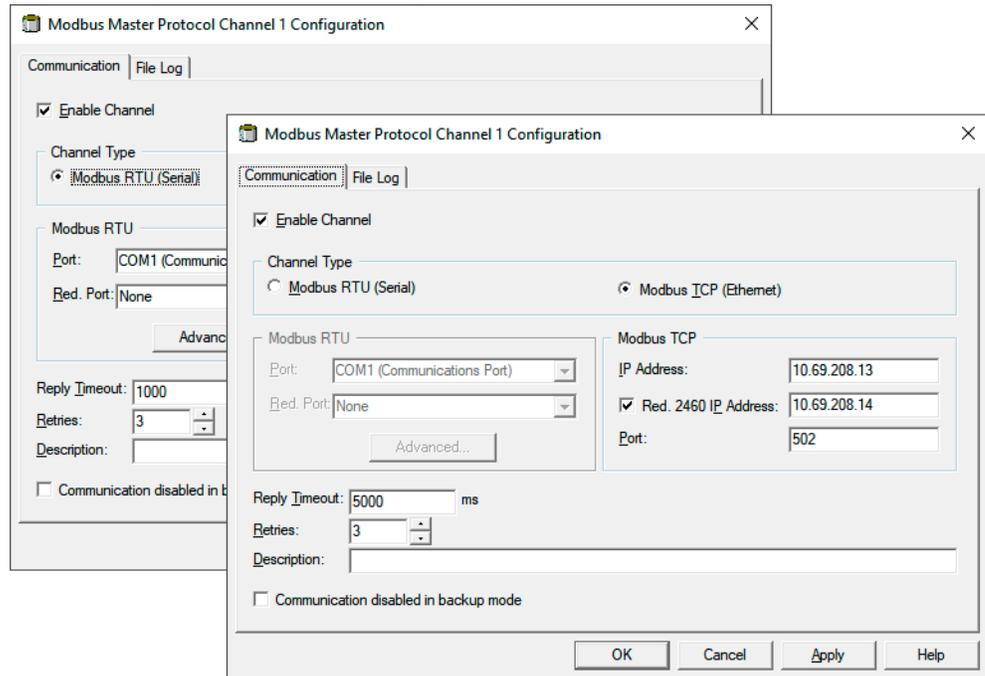


3. Click the right mouse button and select **Properties**, or from the **Service** menu select **Protocols → Properties**.



4. The **Protocol Properties** window lists the available protocol channels. For each channel the corresponding icon indicates whether the channel is enabled or disabled.
5. Select the desired channel.

6. Click the **Properties** button to configure the protocol channel.

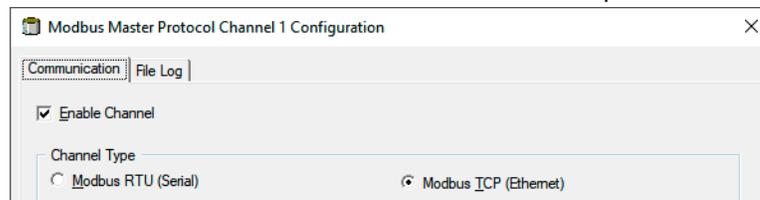


7. Select the **Communication** tab. It allows you to configure parameters for communication between field devices and TankMaster work station.
- Modbus TCP; specify IP address for the Rosemount 2460 System Hub that the TankMaster server is connected to. For redundant system hubs, you may use a separate IP address for the backup server.
  - Modbus RTU; click the **Advanced** button in case you need to configure the communication parameters.

**Note**

If the communication is interrupted and handshaking includes DSR, no query will be sent from the TankMaster Protocol Server. This may result in a Query Timeout.

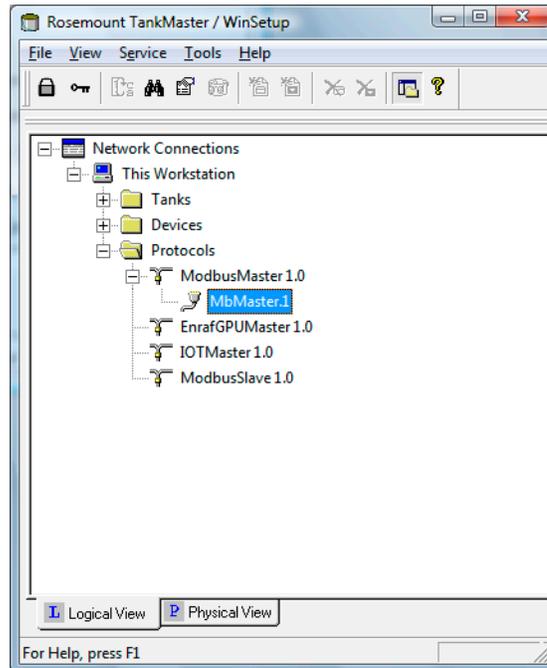
8. The **Communication disabled in backup mode** check box can be used for systems with redundant tank servers. If the check box is selected, the ModbusMaster will not send any queries if the local tank server is in backup mode.
9. Select the **Enable Channel** check box to activate the protocol channel.



10. The **File Log** tab lets you specify what type of information to be logged and saved to disk.

11. Click the **OK** button to store the current configuration and close the configuration window.

The **Modbus Master Channel** icon (channel no. 1 in this example) appears in the WinSetup workspace:



### Related information

[Default Modbus RTU communication parameters](#)  
[Rosemount 2460 Reference Manual](#)

## Default Modbus RTU communication parameters

**Table 2-1: Default Communication Parameters for Modbus RTU**

Parameter	Description
Port	The COM port that the Rosemount 2180 will be connected to
Baud rate	4800
Stop bits	1
Parity	None
Modem	Choose FBM 2180 for the Rosemount 2180 Field Bus Modem Available options: <ul style="list-style-type: none"> <li>• FBM 2180</li> <li>• FBM 2170/71</li> <li>• RS232</li> <li>• RS485</li> </ul>
Handshaking	<ul style="list-style-type: none"> <li>• FBM 2180: None</li> <li>• FBM 2170/2171: RTS/CTS/DTS/DSR</li> <li>• RS485: RTS/CTS</li> <li>• RS232: None</li> </ul>
Reply timeout	1000 ms
Retries	10
Description	Text that describes the configured channel

### Related information

[Master protocol channel configuration](#)

## 2.2.2 Slave protocol channel configuration

A Slave protocol allows you to collect data from the TankMaster workstation to a host computer.

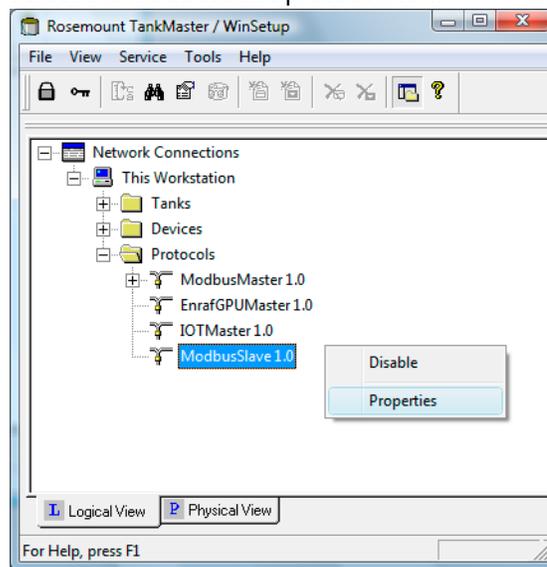
### Modbus® communication setup

#### Prerequisites

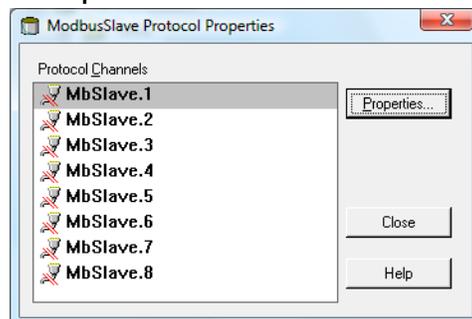
A hardware key must be installed in order to run a slave protocol server. Host communication needs to be enabled.

#### Procedure

1. Open the **Protocols** folder in the **Workspace** window.
2. Select the ModbusSlave protocol icon.

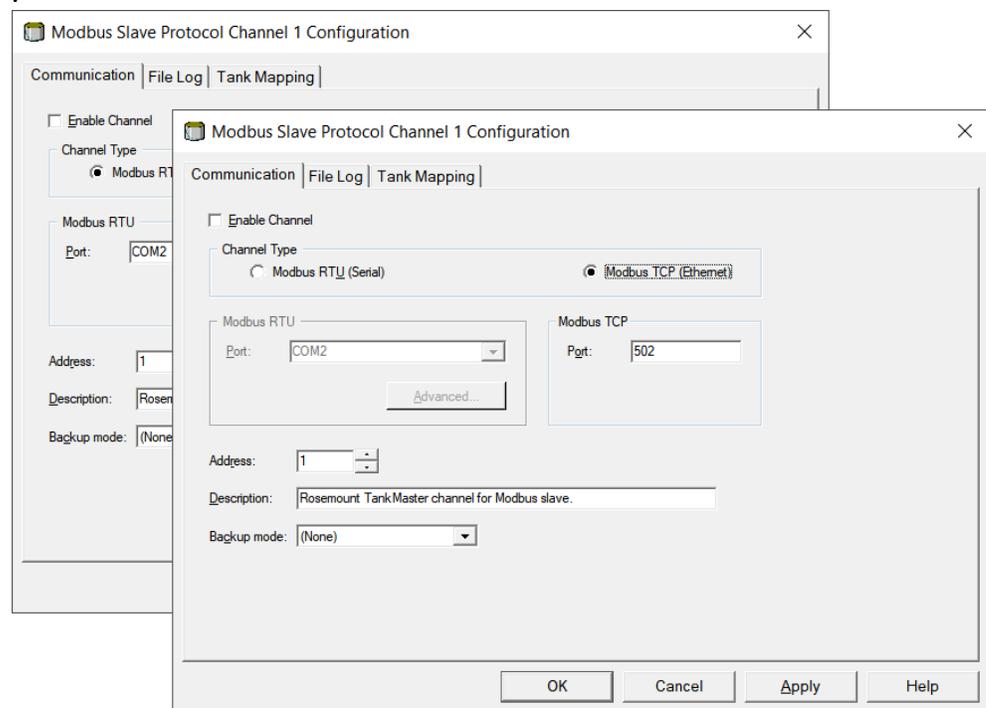


3. Click the right mouse button and select **Properties**, or select **Service** → **Protocols** → **Properties**.



4. The **Protocol Properties** window lists enabled and disabled protocol channels.

5. Select the desired protocol channel and click the **Properties** button to open the configuration window.



6. Select the **Communication** tab.
  - a) Modbus TCP; verify correct port.
  - b) Modbus RTU; click the **Advanced** button in case you need to configure parameters for proper communication with the host.

**Note**

If the communication is interrupted and handshaking includes DSR, no query will be sent from the TankMaster Protocol Server. This may result in a Query Timeout.

7. Select the **Enable Channel** check box to activate the protocol channel.
8. Verify communication address and enter optional description:

**Address** Set the Modbus address to be used by the host computer to identify the TankMaster workstation.

**Description** Optional text to describe the configured channel.

**Backup mode**

- None
- **Write Commands Rejected** means that TankMaster does not accept any write commands from the host system to device database registers

- In **Silent** mode the Modbus Slave protocol will not send any replies to requests coming from the host computer while the local tankserver is in backup mode

---

**Note**

If the communication is interrupted and handshaking includes DSR, no query will be sent from the TankMaster Protocol Server. This may result in a Query Timeout.

---

9. Click the **OK** button to store the current configuration and close the configuration window.

**Related information**

[Advanced Modbus RTU slave protocol configuration](#)

## Advanced Modbus® RTU slave protocol configuration

The *Advanced Communication* window lets you configure modem communication parameters, delay times, and time-outs for the **Modbus RTU Slave** protocol.

### Procedure

1. In the *Slave Protocol Channel Configuration* window, select the *Communication* tab and click the **Advanced** button:

2. The following **default** values are used for the TRL2 Modbus Slave protocol:

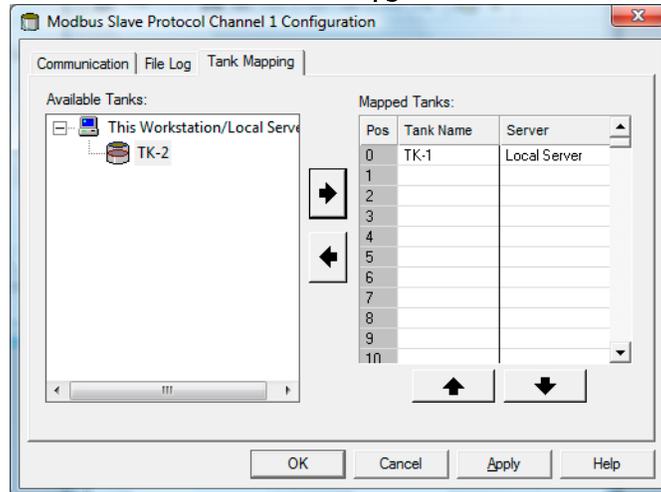
<b>Modem</b>	Choose the appropriate interface
<b>Baud rate</b>	Enter appropriate value for communication with the host
<b>Stop bits</b>	Enter appropriate value for communication with the host
<b>Parity</b>	Enter appropriate value for communication with the host
<b>Handshaking</b>	<ul style="list-style-type: none"> <li>• FBM 2180: None</li> <li>• RS485, RS232: See specifications for the communication software used on the host system</li> </ul>
<b>Query to Response Delay</b>	10 ms
<b>Query interval</b>	100 ms
<b>Read Query Timeout</b>	400 ms
<b>Write Response Timeout</b>	400 ms
<b>Max. Response Time</b>	800 ms

## Tank mapping configuration

The slave protocol allows you to send data from a Rosemount Tank Gauging system to a host computer. In the **Tank Mapping** window you can specify from which tanks to collect data for the host system.

### Procedure

1. In the **Slave Protocol Channel Configuration** window, select the **Tank Mapping** tab.



2. From the list of tanks that appear in the Available Tanks pane, select the tanks that the host will connect to.
3. Click the  (right arrow) button to move the selected tanks to the list of mapped tanks.

---

### Important

Ensure that the tanks appear in the order required by the host system.

When the host sends a query, TankMaster responds by sending tank data in the order as the tanks are listed in the Mapped Tanks column. You can easily change the position of mapped tanks by using the **up arrow** and **down arrow** buttons.

4. Click the **OK** button to save the current configuration and close the window.

## 2.2.3 Log file configuration

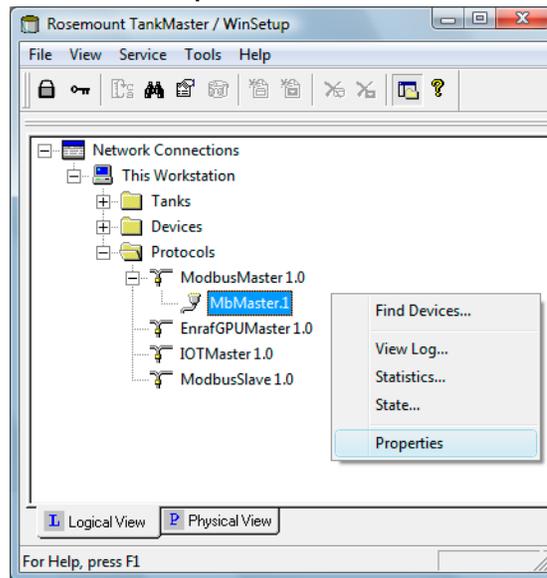
See the Rosemount TankMaster WinSetup [Reference Manual](#) for more information on how to store a communication log on disk.

## 2.2.4 Changing the current protocol channel configuration

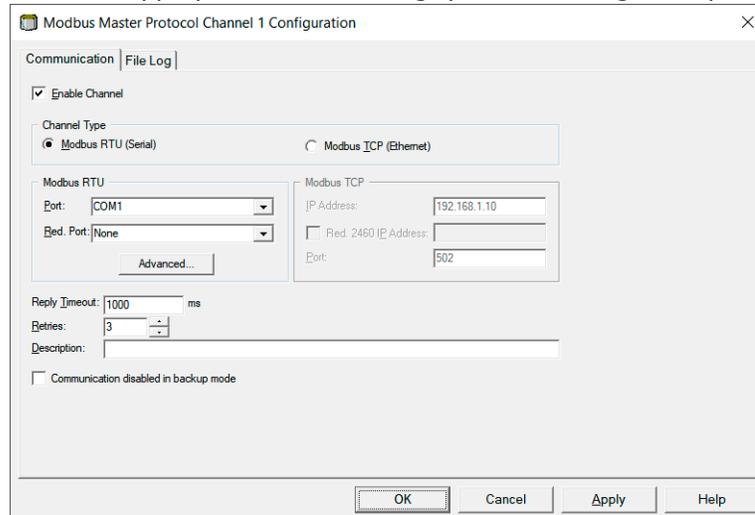
The channel configuration can be changed at any time.

### Procedure

1. In the WinSetup Workspace, open the **Protocols** folder and the protocol sub folder with the enabled channels.
2. Select the desired channel icon.
3. Click the right mouse button and select **Properties**, or from the **Service** menu select **Channels** → **Properties**.



4. Select the appropriate tab and change protocol settings as required.

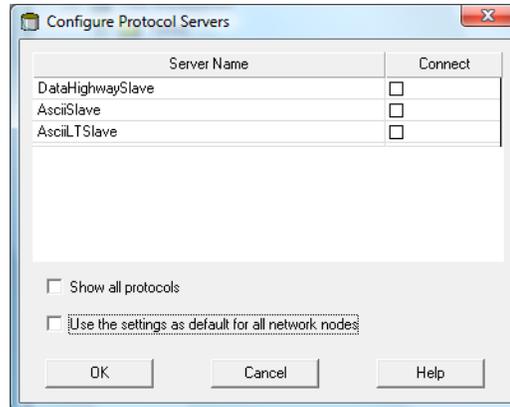


## 2.2.5 Protocol server configuration

You can specify which protocol servers that will be connected when starting TankMaster WinSetup.

### Procedure

1. In the WinSetup workspace select the **Protocols** folder.
2. Click the right mouse button and select **Configure**.



3. In the **Connect** column, select check boxes of the protocols to be automatically connected when WinSetup starts up.

## Disable a protocol server

You may disable a protocol server at any time by using the **Disable** command.

### Procedure

1. In the WinSetup workspace, open the **Protocols** folder.
2. Click the right mouse button on the desired protocol server icon and select **Disable**.

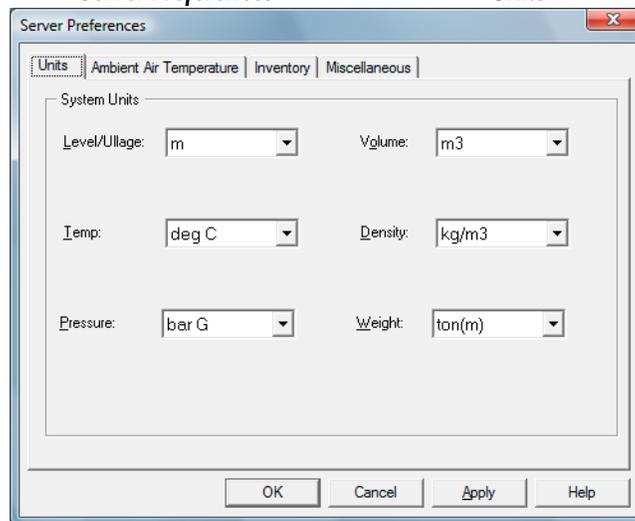
## 2.3 Preferences

### 2.3.1 Measurement units

Specify units for inventory calculations and measured variables such as level and temperature. To change measurement units do the following:

#### Procedure

1. Select the desired server (e.g. “This Workstation”) in the WinSetup workspace.
2. Click the right mouse button and select **Setup**, or from the **Service** menu select **Servers** → **Setup**.
3. In the **Server Preferences** window select the **Units** tab.



4. Select the desired measurement units for level/ullage, temperature, pressure, volume, density, and weight.
5. Click the **OK** button to save the current setting and close the window.

---

#### Note

Make sure that the desired measuring units are specified before installing new tanks and devices.

---

## Changing measurement units for existing tanks

Configuration of measurement units in the *Server Preferences* window only affect installation of new tanks. For tanks which are already installed in the WinSetup Workspace you will have to follow this procedure.

### Procedure

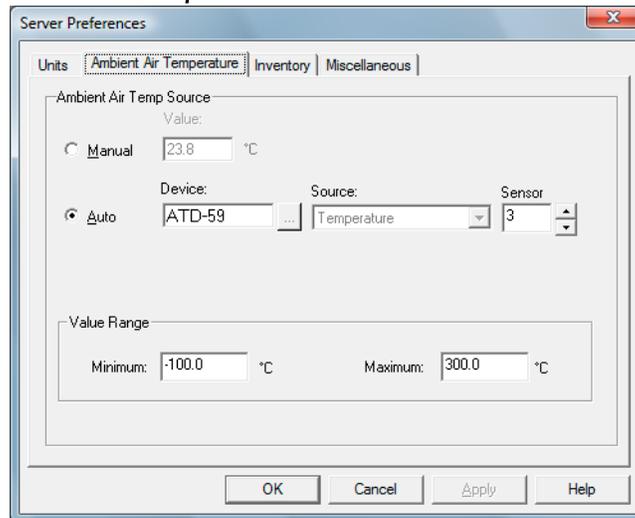
1. Uninstall the tank.
2. Change measurement units in the *Server Preferences/Units* window (or in the TankMaster WinOpi program choose menu option **Setup** → **System** and change units in the *System Setup* window).
3. Install the tank again.

## 2.3.2 Ambient Air Temperature

This section describes how to change the Ambient Air Temperature preferences.

### Procedure

1. Select the desired server (e.g. “This Workstation”) in the WinSetup workspace.
2. Click the right mouse button and select **Setup**, or from the Service menu select **Servers** → **Setup**.
3. In the *Server Preferences* window select the **Ambient Air Temperature** tab:



4. Choose **Auto** when there is a temperature sensor available that can be used for Ambient Air Temperature measurements. Otherwise, select the **Manual** option and type a value for the Ambient Air temperature.

**Device** Click the browse button and select the device to which a temperature sensor is connected.

**Source** Select temperature source associated with the selected device. In a Rosemount Tank Gauging system the associated temperature transmitter has to be configured in the tank database of the Rosemount 2410 Tank Hub.

**Sensor** Select a specific sensor to be used for Ambient Air Temperature.

**Value Range** Value Range defines the minimum and maximum values when Ambient Air Temperature is manually entered.

5. Click the **OK** button to save the current setting and close the window.

### Related information

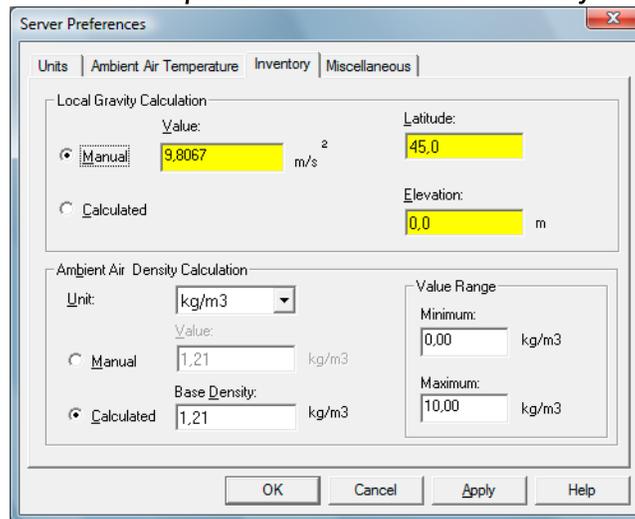
[Installing a Rosemount 2410 Tank Hub](#)

## 2.3.3 Inventory

Local Gravity and Ambient Air Density calculations are used for automatic density measurements. This is a description on how to change those Inventory settings.

### Procedure

1. Select the desired server (e.g. “This Workstation”) in the WinSetup workspace.
2. Click the right mouse button and select **Setup**, or from the Service menu select **Servers** → **Setup**.
3. In the *Server Preferences* window select the **Inventory** tab:



4. **Local Gravity** is used for density and weight calculations when an optional pressure transmitter is installed.
  - Select **Manual** if you want to use a specific value for the Local Gravity.
  - Select **Calculated** if you want local gravity to be calculated by TankMaster. In this case you need to enter **Latitude** and **Elevation** of the site.
5. **Ambient Air Density** is used for calculating **Observed Density** and **Weight in Air (WIA)**.
  - Select **Manual** if you want to use a specific value for Ambient Air Density.
  - Select **Calculated** if you want the **Ambient Air Density** to be calculated by TankMaster. The calculated value is based on the **Base Density** and the **Ambient Air Temperature**.

See the TankMaster WinOpi [Reference Manual](#) for more information on inventory parameters and calculations.

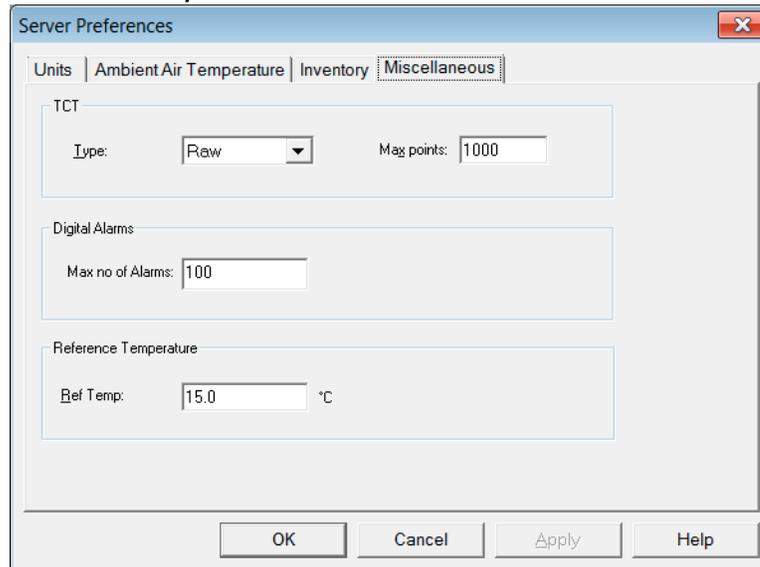
6. Click the **OK** button to save the current settings and close the window.

## 2.3.4 Miscellaneous

This is a description of how to change parameters such as type of Tank Capacity Table or Reference Temperature.

### Procedure

1. Select the desired server (e.g. “This Workstation”) in the WinSetup workspace.
2. Click the right mouse button and select **Setup**, or from the **Service** menu select **Servers** → **Setup**.
3. In the **Server Preferences** window select the **Miscellaneous** tab.



4. Choose the type of **Tank Capacity Table (TCT)** to be used as default setting when installing new tanks. The default TCT type will automatically be chosen when strapping tables are created for new tanks. However, the TCT type can be changed when the strapping table is specified in the **Tank Capacity Setup** window regardless of the settings in the **Server Preferences** window.

You can choose between TCT type Raw, International, and Northern<sup>(1)</sup>.

5. Specify the maximum number of **Digital Alarms** that will be used.
6. Specify the **Reference Temperature** to be used for inventory calculations. Normally, the standard value 15 °C is used.
7. Click the **OK** button to save the current settings and close the window.

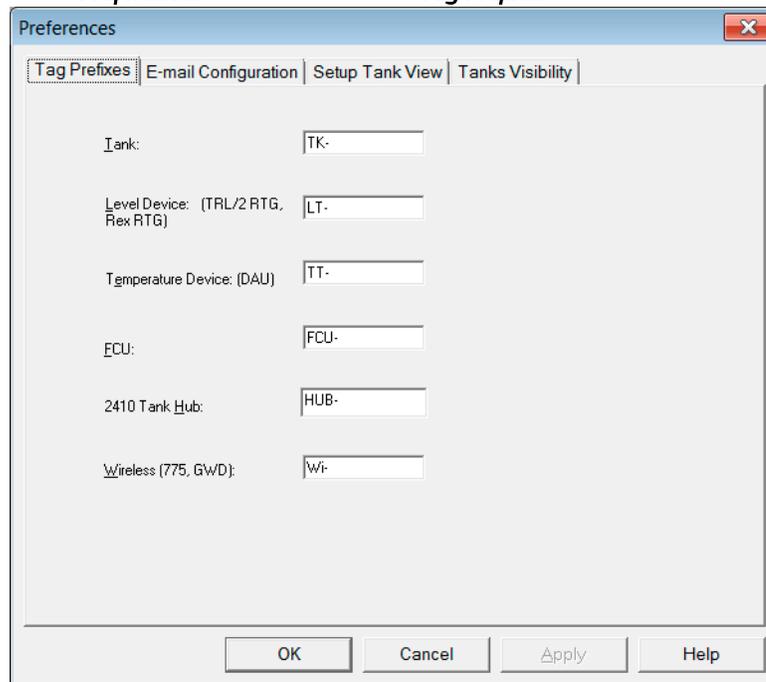
<sup>(1)</sup> See the TankMaster WinOpi [Reference Manual](#) for further information.

## 2.3.5 Setting the name tag prefixes

TankMaster WinSetup allows you to specify default name tag prefixes that will appear automatically when installing new tanks and devices. Note that Tank Tag must begin with a letter. These prefixes can be ignored if you want to use other prefixes instead.

### Procedure

1. From the **Service** menu select **Preferences**.
2. In the **Preferences** window select the **Tag Prefixes** tab.



3. Type the prefixes to be used for tank names and device names, and click the **OK** button.

You can change the prefixes later at any time.

---

### Note

Changing tag prefixes will not affect names of existing tanks and devices.

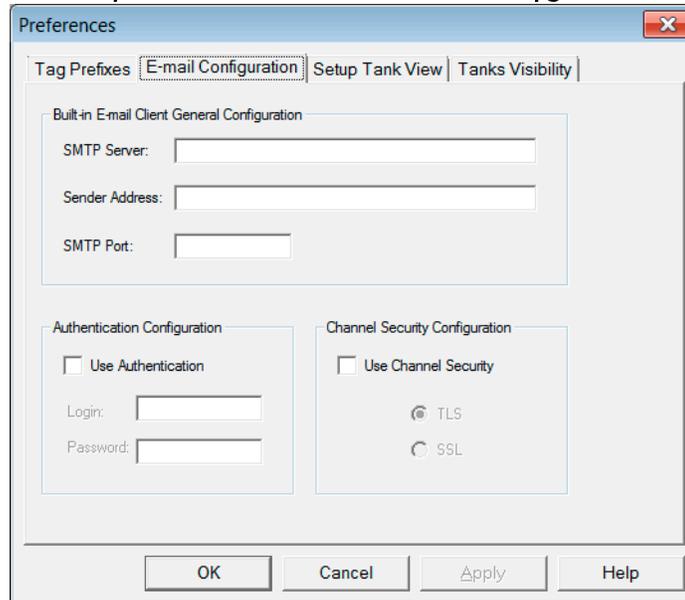
---

## 2.3.6 Email configuration

TankMaster WinSetup allows you to setup an e-mail client for alarm notifications and reports.

### Procedure

1. From the **Service** menu select **Preferences**.
2. In the **Preferences** window select the **E-mail Configuration** tab.



3. Enter the following information:

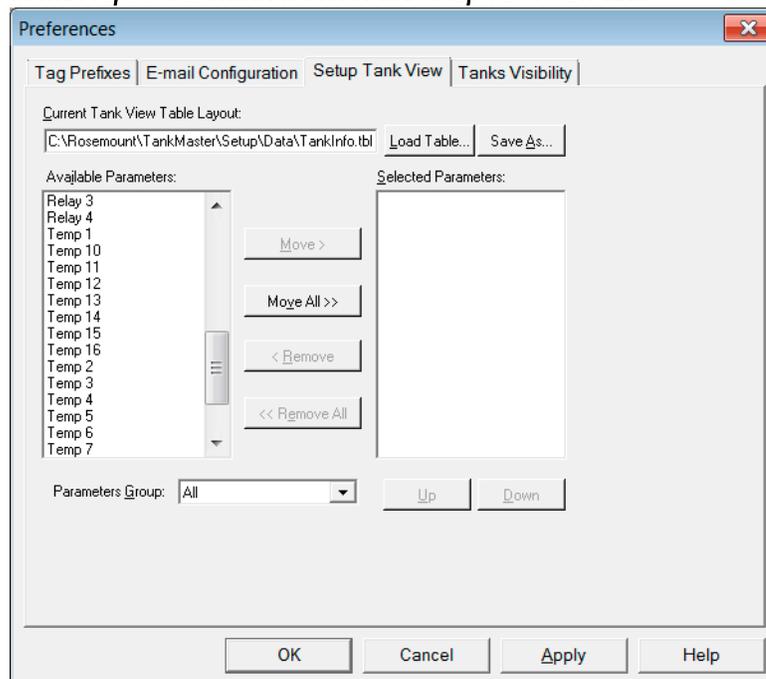
<b>SMTP Server</b>	Specify an SMTP server for outgoing messages. Contact your LAN administrator or Internet Service Provider (ISP) for details.
<b>Sender Address</b>	The e-mail account which will send e-mails from the current workstation must be located on the specified SMTP server.
<b>SMTP Port</b>	Contact your LAN administrator or ISP for details.
<b>Authentication Configuration</b>	Select this option and enter a <b>Login</b> name and <b>Password</b> if authentication is required on the mail server. Contact your LAN administrator or ISP for details.
<b>Channel Security Configuration</b>	Select this option if the e-mail client requires the use of channel security. Contact your LAN administrator or ISP for details.
<b>Subject</b>	Enter a title for an e-mail alarm notification. This subject is only used for Alarm notification and is optional. This subject will not be used for other e-mails sent from the built-in e-mail client.

## 2.3.7 Tank View layout

The **Setup Tank View** tab is used to specify variables to be presented in the **Tank View** window, see the [Rosemount TankMaster WinSetup Reference Manual](#) for more information. TankMaster WinSetup allows you to create a new tank view layout and store it on disk, or load an existing table layout from disk.

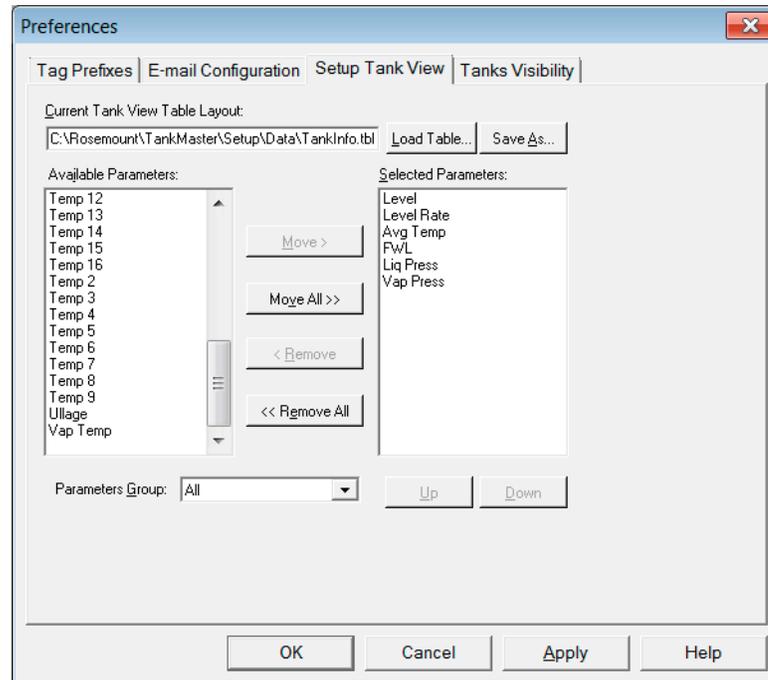
### Procedure

1. From the **Service** menu select **Preferences**.
2. In the **Preferences** window select the **Setup Tank View** tab.



3. Click the **Load Table** button if you wish to edit an existing Table Layout.
4. In the **Available Parameters** pane on the left-hand side of the **Preferences/Setup Tank View** window, select the parameter to be presented in the **Tank View** window.
5. Click the **Move** button to move it to the **Selected Parameters** pane on the right-hand side of the **Preferences/Setup Tank View** window.
6. Repeat this procedure for each parameter you wish to include. The **Move All** button allows you to move all variables at once to the **Selected Parameters** list box.

7. Ensure that all parameters to appear in the **Tank View** window are included in the **Selected Parameters** list box as illustrated below:



8. Click the **Save As** button if you wish to store the current tank view table for future use.
9. Click the **OK** button to save the current **Tank View** settings and close the window.

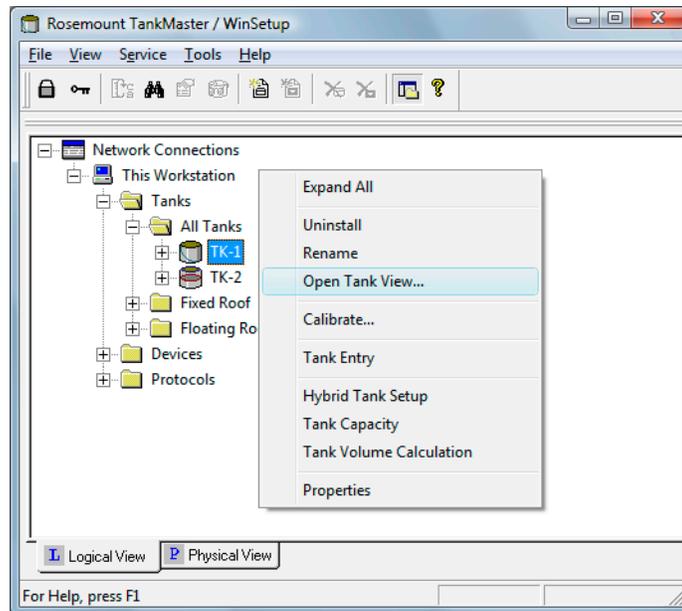
---

**Note**

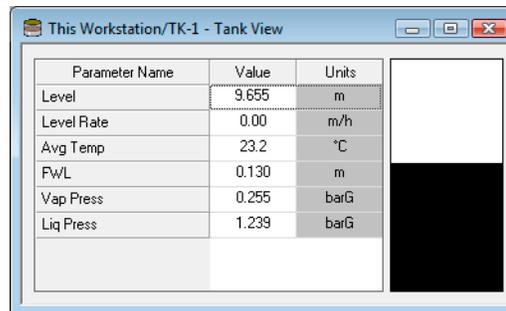
When clicking the **Apply** or the **OK** button, the parameter setup is stored in the table layout that is currently used by the **Tank View** window.

---

10. To view the specified tank parameters click the right mouse button and select **Open Tank View**:



The Tank View window shows the selected parameters as configured in the **Setup Tank View**.



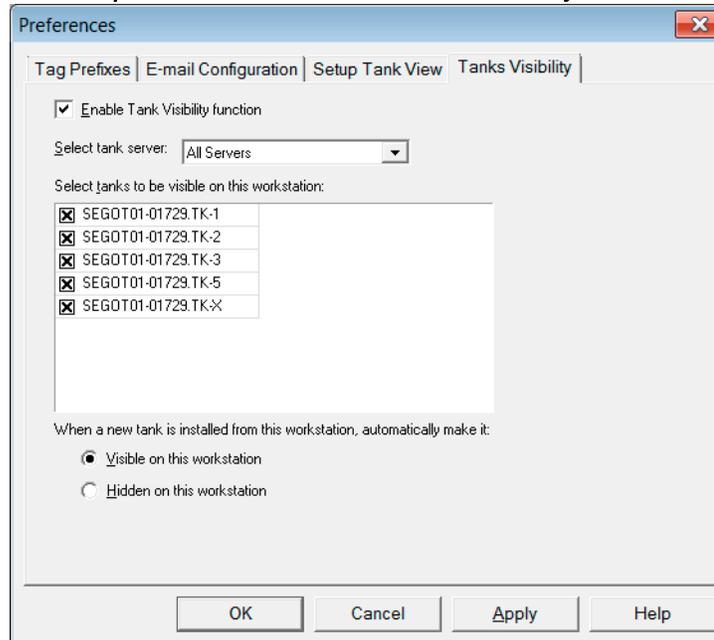
Parameter Name	Value	Units
Level	9.655	m
Level Rate	0.00	m/h
Avg Temp	23.2	°C
FWL	0.130	m
Vap Press	0.255	barG
Liq Press	1.239	barG

## 2.3.8 Tank visibility

The **Tanks Visibility** tab lets you configure tanks on a remote tank server to make them visible on the current TankMaster WinOpi client.

### Procedure

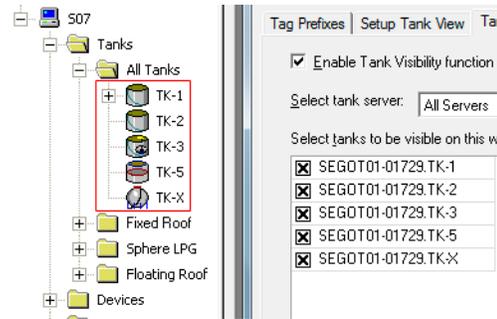
1. From the **Service** menu select **Preferences**.
2. In the **Preferences** window select the **Tanks Visibility** tab.



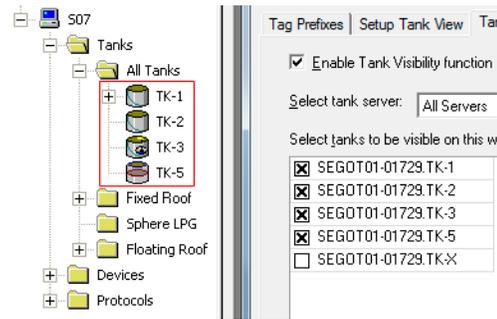
3. Select the **Enable Tank Visibility** function check box.
4. From the **Select tank server** drop-down list select the remote tank server on which the tanks are installed.
5. In the **Select tanks to be visible on this workstation** pane, check the tanks you wish to make visible on the current workstation.  
In the default setting all tanks are visible.
6. Select **Visible on this workstation** in case you would like to make tanks installed on a remote server automatically visible on the current workstation as well.

7. Click the **OK** button to store the current configuration and close the *Preferences* window.

**Figure 2-3: Tanks Visibility Enabled for All Tanks**



**Figure 2-4: One Tank Disabled from Visibility (TK-X)**



## 2.4 Field device installation overview

The Rosemount TankMaster software supports many field devices, for example:

- Rosemount 2460 System Hub
- Rosemount 2410 Tank Hub
- Rosemount 5900 Radar Level Gauge
- Rosemount 2240S Multi-input Temperature Transmitter
- Rosemount 2230 Graphical Field Display
- Rosemount 5408 Radar Level Transmitter
- Rosemount 5300 Guided Wave Radar
- Rosemount 3051/3051S Pressure Transmitter
- Rosemount 644 Temperature Transmitter

### 2.4.1 Configuration

A TankMaster installation includes configuration of the Rosemount Tank Gauging system for communication with the TankMaster work station and field devices as well as configuration of device specific parameters.

Configuration of radar level gauges includes:

- mapping to a specific tank
- communication parameters
- device specific parameters
- tank geometry
- tank environment parameters

Configuration of Auxiliary Tank Devices (ATDs) includes:

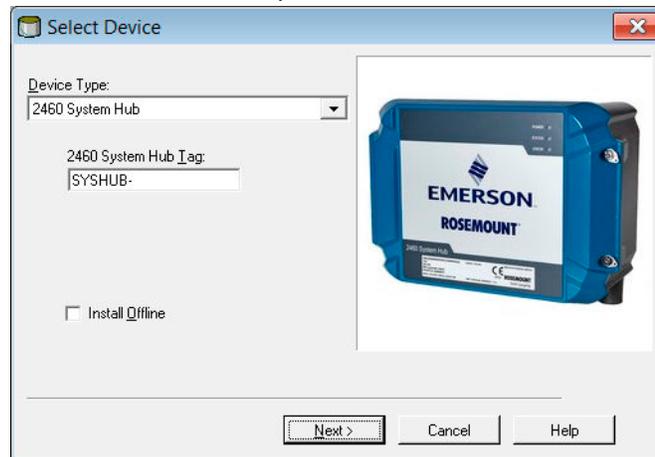
- communication address
- mapping of measurement variables to source devices
- Rosemount 2240S Multi-input Temperature Transmitter or other supported temperature transmitter
- temperature elements
- water level sensor
- Rosemount 2230 Graphical Field Display
- other supported field devices

## 2.5 Installing a Rosemount 2460 System Hub

This is a brief description of how to install and configure a Rosemount 2460 System Hub in a Rosemount Tank Gauging system.

### Procedure

1. Ensure that the Rosemount TankMaster WinSetup program is up and running.
2. Enable and configure a Protocol Channel to establish communication with the appropriate port on the TankMaster PC.
3. Start the installation wizard in TankMaster WinSetup:
  - a) Click the right mouse button on the **Devices** folder.
  - b) Select the **Install new** option.



4. Select device type 2460 System Hub.
5. Specify a name tag in the 2460 System Hub Tag input field. This tag will be used as an identifier of the Rosemount 2460 in various windows and dialogs.
6. Click the **Next** button to proceed with the installation wizard.
7. Verify that the Host and Field ports are properly configured. Host ports are used for communication with TankMaster work stations or other host systems. Field ports are used for communication with the Rosemount 2410 Tank Hub, the Rosemount 5900S Radar Level Gauge, and other field devices.
8. Configure the **Tank Database**. Ensure that the Modbus® Addresses of the connected devices are properly set. These addresses must correspond to the database settings of the Rosemount 2410 Tank Hub.

### Related information

[Rosemount 2460 Reference Manual](#)

## 2.6 Installing a Rosemount 2410 Tank Hub

The installation wizard covers basic configuration of a Rosemount 2410 Tank Hub. If further configuration of Primary Bus, Secondary Bus, Relay Output, and Hybrid Density Calculation is required this must be done separately via the 2410 Tank Hub **Properties** window.

### Related information

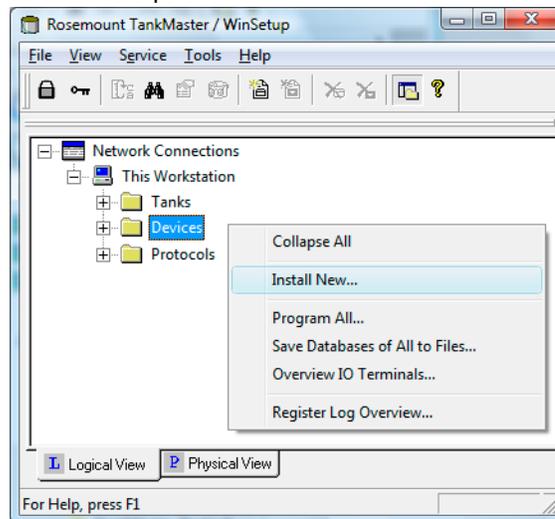
[Rosemount 2410 Reference Manual](#)

### 2.6.1 Installing a Rosemount 2410 using the wizard

It is very important that the Tank Database of the Rosemount 2460 System Hub is properly configured prior to configuring the Rosemount 2410 Tank Hub. This ensures that the system hub is able to collect data from the different field devices.

#### Procedure

1. In the Workspace window select the **Devices** folder.



2. Click the right mouse button and select **Install New**, or from the **Service** menu choose **Devices** → **Install New**.  
Now the **Select Device** window appears.

3. From the **Device Type** drop-down list, choose the **2410 Tank Hub** option.



4. Type a name in the 2410 HUB Tag input field. The tag will be used as an identifier for the Rosemount 2410 Tank Hub in various windows and dialogs.
5. Click the **Next** button to proceed with communication settings.

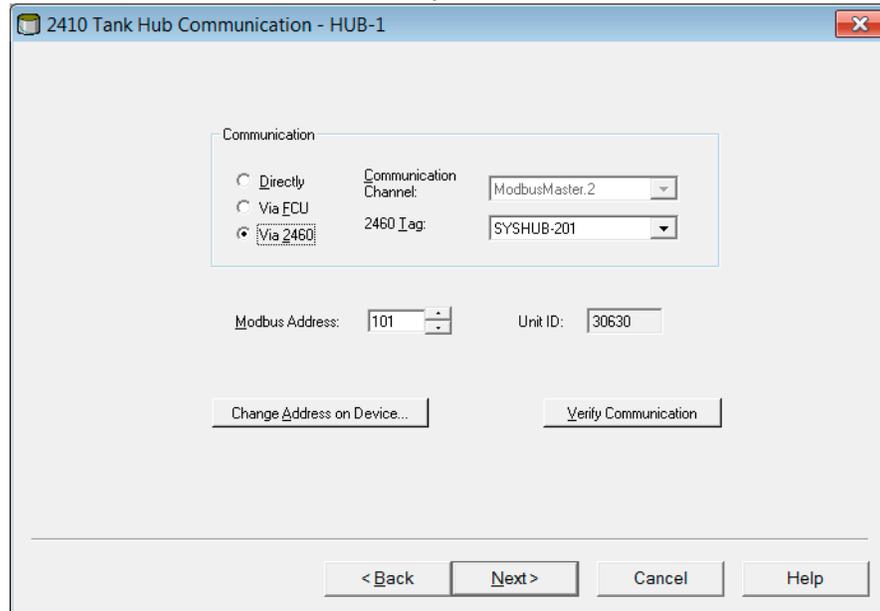
#### Related information

[Installing a Rosemount 2460 System Hub](#)

## Communication setup

### Procedure

1. Specify whether TankMaster communicates directly with the Rosemount 2410 Tank Hub, or via a Rosemount 2460 System Hub.



2. If the tank hub is connected to a system hub, select the appropriate system hub from the **2460 Tag** drop-down list.
3. If the tank hub is connected directly to a TankMaster PC and not via a system hub, specify the communication protocol channel which is associated with the communication port on the TankMaster workstation. To check which channels are enabled:
  - a) in the WinSetup workspace open the **Protocols** folder
  - b) click the right mouse button on the **ModbusMaster** protocol icon
  - c) choose the **Properties** option

To check which communication port that is associated with a certain channel:

- a) right-click the protocol channel icon
- b) open the **Communication** tab and check which communication port that is selected.

4. To verify communication with the tank hub, type the current Modbus address and click the **Verify Communication** button. The **Unit Id** will appear if the correct Modbus address was entered (the tank hub is shipped with the default Modbus address=247).

---

**Note**

In case several Rosemount 2410 Tank Hubs are connected using the same default address (247), you will have to change the addresses before the Verify command can be used.

---

5. In the **2410 Tank Hub Communication** window click the **Next** button to continue the installation procedure of the tank hub.

**Related information**

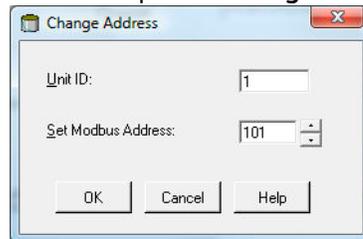
[Master protocol channel configuration](#)

[How to change the Modbus address of the Rosemount 2410](#)

**How to change the Modbus® address of the Rosemount 2410**

**Procedure**

1. In the **2410 Tank Hub Communication** window click the **Change Address on Device** button to open the **Change Address** window.



2. Enter the **Unit ID** and the new **Modbus Address**. When changing the device address, the Unit Id is used as a unique identifier of the device. The Unit Id can be found on a label mounted on the device.

---

**Tip**

If there is no other device connected that uses the same address as the current device, you can find the **Unit Id** by typing the current address into the **Address** field in the **2410 Tank Hub Communication** window and clicking the **Verify Communication** button.

---

3. Click the **OK** button to confirm the address settings and close the **Change Address** window.
4. In the **2410 Tank Hub Communication** window click the **Verify Communication** button to check that communication is established between the TankMaster workstation and the Rosemount 2410 Tank Hub. The Unit ID will appear when TankMaster finds the tank hub.

## Tank Database setup

Each tank is represented by a position in the Rosemount 2410 tank database. Each device connected to the Rosemount 2410 is mapped to a tank position. For each tank position, a name is assigned as an identifier of the tank. The tank database maps field devices to the various tanks, and identifies the devices whenever there is a request for measurement data from a Rosemount 2460 System Hub.

### Procedure

1. The **Device Type** column lists all devices that communicate on the Tankbus. Ensure that all devices connected to the Tankbus appear in the **Device Type** list to verify proper communication.
2. In the **Tank Position** column, map each device to a tank by selecting the appropriate number from the drop-down list in the tank database.

### Example

The example below illustrates a tank connected to a Rosemount 2410 Tank Hub. Note that tank positions which are mapped to devices are enabled for editing. You may change tank name and Modbus® address in the right-hand side of the **Tank Hub Tank Database** window.

The screenshot shows a software window titled "2410 Tank Hub Tank Database - HUB-1". It contains two main tables and a set of navigation buttons at the bottom.

**2410 Tank Positions:**

	Device Type	Device ID	Device connected to field bus	Tank Position
1	5900 RLG	51236	Yes	1
2	2240 MTT	1337	Yes	1
3	2230 GFD	1829	Yes	1
4	No Device		No	Not Configured
5	No Device		No	Not Configured
6	No Device		No	Not Configured
7	No Device		No	Not Configured
8	No Device		No	Not Configured
9	No Device		No	Not Configured
10	No Device		No	Not Configured
11	No Device		No	Not Configured
12	No Device		No	Not Configured
13	No Device		No	Not Configured
14	No Device		No	Not Configured
15	No Device		No	Not Configured
16	No Device		No	Not Configured

**2410 Tank Names and Addresses:**

Tank Position	Tank Name	Level Modbus Address	ATD Modbus Address
1	TK-1	1	101
2			
3			
4			
5			
6			
7			
8			
9			
10			

Enter tank name with max 10 characters.  
The name will be used in field displays.  
The name will also be used as base for the device tags in TankMaster.

Navigation buttons: < Back, Next >, Cancel, Help

- Optional: A multiple tanks version of the Rosemount 2410<sup>(2)</sup> allows you to connect several tanks to a single tank hub.

### Example

The example below illustrates three tanks connected to a tank hub for multiple tanks.

**2410 Tank Positions:**

	Device Type	Device ID	Device connected to field bus	Tank Position
1	5400 RLG	11880	Yes	1
2	2240 MTT	62679	Yes	1
3	2240 MTT	42878	Yes	3
4	5400 RLG	8528	Yes	2
5	5400 RLG	94238	Yes	3
6	2240 MTT	17178	Yes	2
7	No Device		No	Not Configured
8	No Device		No	Not Configured
9	No Device		No	Not Configured
10	No Device		No	Not Configured
11	No Device		No	Not Configured
12	No Device		No	Not Configured
13	No Device		No	Not Configured
14	No Device		No	Not Configured
15	No Device		No	Not Configured
16	No Device		No	Not Configured

**2410 Tank Names and Addresses:**

Tank Position	Tank Name	Level Modbus Address	ATD Modbus Address
1	TK-1	1	101
2	TK-2	2	102
3	TK-3	3	103
4			
5			
6			
7			
8			
9			
10			

Enter tank name with max 10 characters.  
The name will be used in field displays.  
The name will also be used as base for the device tags in TankMaster.

< Back    Next >    Cancel    Help

- Type the desired names in the Tank Name field. These tank names should also be used at a later stage when installing the tanks associated with the current Rosemount 2410 Tank Hub.
- For each tank, specify a Modbus address in the **Level Modbus Address** column to be associated with the level gauge. This must be the same Modbus address as configured in the tank database of the Rosemount 2460 System Hub. The **Level Modbus Address** is used to identify level gauges when distributing requests for measurement data from the system hub.

(2) Multiple tank version of the Rosemount 2410 Tank Hub requires model code option M. See the [Rosemount Tank Gauging System Data Sheet](#) for more information.

6. The various non-level devices on a tank are represented by a single ATD device in the Rosemount Tank Gauging system.
  - In tank position 1, the Rosemount Tank Gauging system uses the Modbus address of the Rosemount 2410 Tank Hub itself as the ATD Modbus address. In the example above, the tank hub has Modbus address 101. This address is automatically used as the ATD Modbus address as well.
  - For tank positions 2 to 10<sup>(2)</sup> you need to specify Modbus addresses in the ATD Modbus Address column to be associated with the different ATD devices.

---

**Important**

The ATD Modbus addresses must be the same as configured in the Rosemount 2460 System Hub's tank database.

---

- An empty ATD Modbus address field indicates that no ATD device is mapped to that particular tank position.
7. Click the **Next** button to continue the installation procedure.

**Related information**

[Installing a Rosemount 2460 System Hub](#)

[Rosemount 2460 Reference Manual](#)

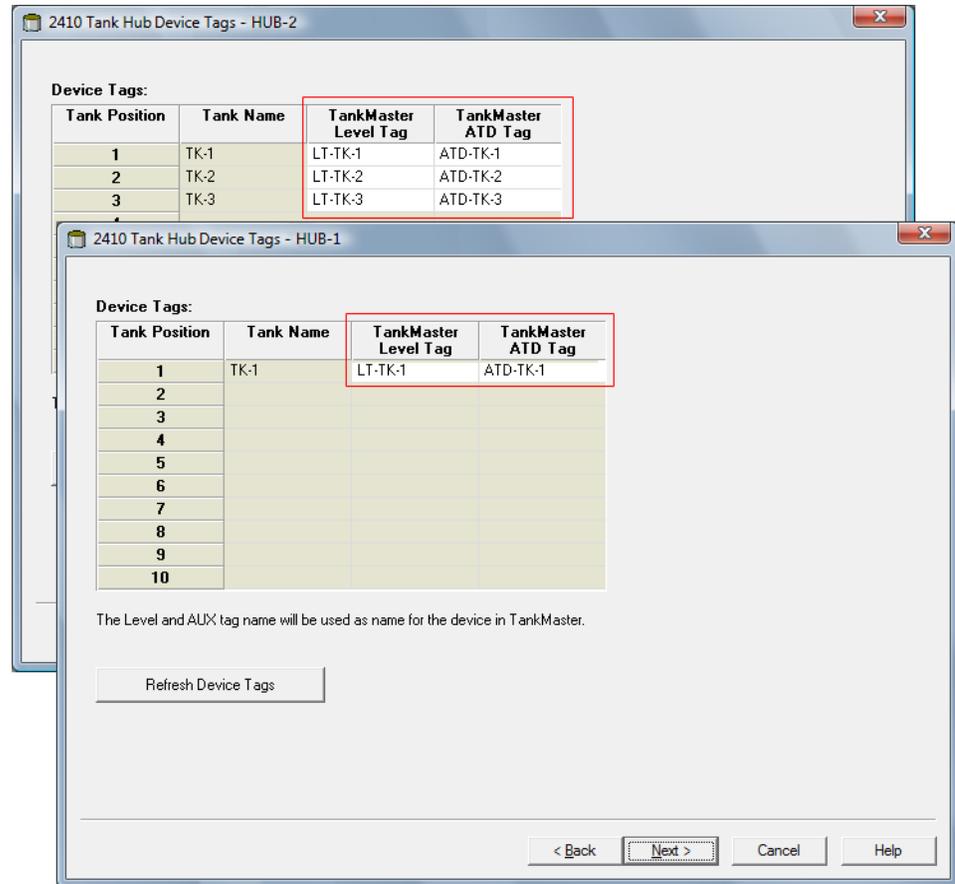
[Installing a tank](#)

## Device Tag setup

Level Tags and ATD Tags are configured automatically based on tank names in the **2410 Tank Hub Tank Database** window and the configuration of tag prefixes in the **Preferences/Tag Prefix** window. However, it is possible to edit the Level Tag and ATD Tag fields.

### Procedure

1. Verify that the **TankMaster Level Tag** is correct or type a new one.



2. Verify that the **TankMaster ATD Tag** is correct or type a new one. In case the ATD tag field is empty and disabled then no ATD device is associated with that tank position.
3. Click the **Next** button to continue the installation procedure.

### Related information

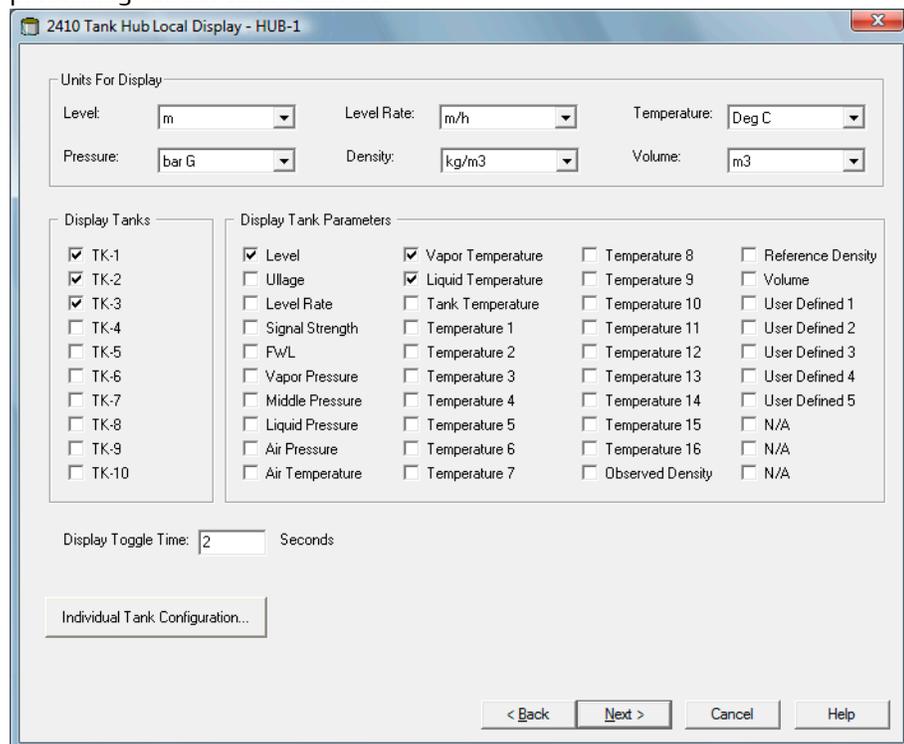
[Setting the name tag prefixes](#)

## Local display setup

Choose the parameters to be displayed on the integral display panel on the Rosemount 2410 Tank Hub. The display will alternate between the selected items at a rate given by the Display Toggle Time.

### Procedure

1. In the **Units for Display** pane, choose the desired measurement units from the drop-down lists. These measurement units will be used by the 2410 local display when presenting various tank variables.



2. In the **Display Tanks** pane, select check boxes for the tanks that you want to present in the Rosemount 2410 integral display.
3. In the **Display Tank Parameters** pane, choose the tank parameters to be displayed by checking the appropriate boxes. See [Table 2-2](#) for more information on available parameters:

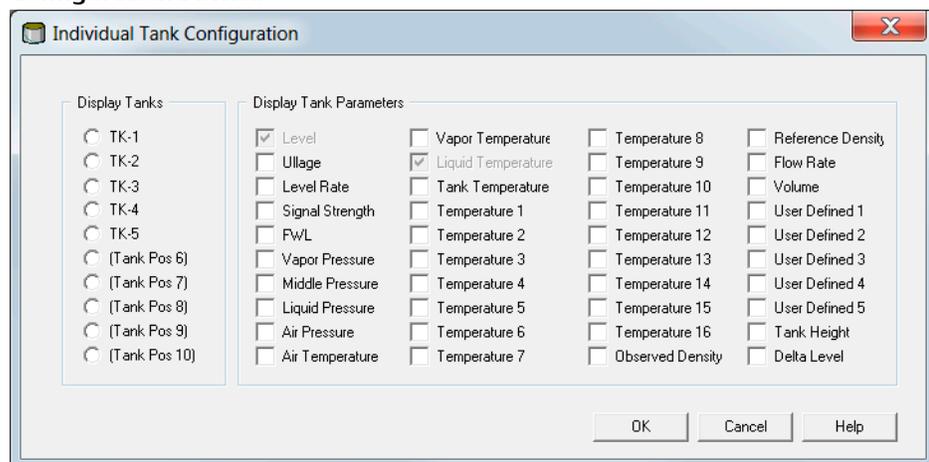
**Table 2-2: Various Tank Parameters can be Presented on the Local Display**

Tank Parameter	Description
Level	The current product level in the displayed tank.
Distance	Distance (ullage) is measured from the Tank Reference point to the product surface.
Level rate	The speed at which the product surface moves when emptying or filling the tank.
Signal strength	The signal strength of the radar level gauge measurement signal.

**Table 2-2: Various Tank Parameters can be Presented on the Local Display**  
(continued)

Tank Parameter	Description
Free water level	Water surface level at the bottom of the tank. Available when a water level sensor is installed in the tank.
Vapor pressure	Tank vapor pressure.
Liquid pressure	Product liquid pressure.
Air pressure	Ambient air pressure.
Air temperature	Ambient air temperature.
Vapor temperature	Tank vapor temperature.
Product temperature	Average temperature of the product.
Tank temperature	Average temperature of product and vapor in the tank.
Temperature 1, 2 ...	Temperature value measured by element 1, 2, etc.
Observed density	The actual product density at the current product temperature.
Reference density	Density at reference temperature (used for inventory calculations).
Volume	Total observed volume.
User defined 1 to 5	Variables for advanced configuration.

4. Enter the **Display Toggle Time**. Information on the local display alternates between the selected items at a rate given by the Display Toggle Time value.
5. The tank hub can be configured to show different parameters for each tank on the Tank Bus. In the 2410 Tank Hub Local Display window click the **Individual Tank Configuration** button:



6. The **Display Tanks** pane has a list of all tank positions in the tank database. Tank positions within brackets, for example (Tank Pos 6), are not configured in the Rosemount 2410's tank database.

7. Select the desired tank position and choose which parameters to show on the display. Repeat this procedure for each tank position.
8. Click the **OK** button to store the configuration and return to the **2410 Tank Hub** window.
9. Click the **Next** button to continue the installation procedure.

## Configuration summary

The **2410 Tank Hub Summary** window shows information about all devices included in the Rosemount 2410's tank database.

### Procedure

1. Verify that all Modbus® addresses, level tags and ATD tags presented in the **2410 Tank Hub Summary** window are correct. In case you would like to make any changes, click the **Back** button until the appropriate configuration window appears.

Please confirm:

2410 Tag: HUB-1  
Unit ID: 30630  
Communication: Via System Hub SYSHUB-201  
Modbus Address: 101

Tank Position	Tank Name	TankMaster Level Tag	Level Modbus Address	TankMaster ATD Tag	ATD Modbus Address
1	TK-1	LT-TK-1	1	ATD-TK-1	101
2					
3					
4					
5					
6					
7					
8					
9					
10					

Install Level and AUX devices offline in TankMaster.

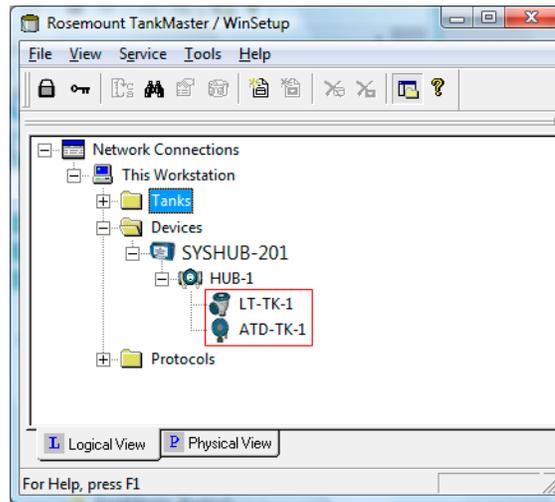
< Back Finish Cancel Help

2. By selecting the **Install Level and AUX devices** check box, field devices connected to the tank hub will automatically be installed in the TankMaster workspace. The check box is selected by default and this is the recommended setting.

Once installed, the devices need to be configured via the **Properties** window. The installation procedure will be facilitated by using the **Install Level and AUX devices** check box. However, the field devices (level gauge and ATD) can be installed at a later stage by using the device installation wizard for the respective device.

3. Click the **Finish** button to confirm the installation. The installed devices will appear in the Workspace window.  
The installed devices will appear in the *Workspace* window.

**Figure 2-5: Devices Appear in the WinSetup Workspace Window**



### Postrequisites

Make sure that devices are properly configured.

### Related information

- [Installing a Rosemount 5900 Radar Level Gauge](#)
- [Installing Auxiliary Tank Devices](#)
- [Using the device installation wizard](#)

## Advanced configuration

The installation wizard does not include all configuration options available for a Rosemount 2410 Tank Hub. Further configuration can be done via the 2410 Tank Hub Configuration window:

- host communication parameters for the Primary Bus
- host communication and emulation parameters for the Secondary Bus
- virtual relays
- hybrid density calculation

See the Rosemount 2410 Tank Hub Reference Manual (00809-0100-2410) for more information on how to configure a Rosemount 2410 Tank Hub.

### Related information

[Rosemount 2410 Reference Manual](#)

## 2.7 Installing a Rosemount 5900 Radar Level Gauge

This is a description of how to setup a Rosemount 5900 Radar Level Gauge by using the TankMaster WinSetup configuration software. It applies to the Rosemount 5900S as well as the Rosemount 5900C. Pictures in the examples below will show the Rosemount 5900S in most cases, but the functionality is the same for the Rosemount 5900C if not otherwise stated.

The Rosemount 5900 Radar Level Gauge is typically installed in TankMaster WinSetup as part of the Rosemount 2410 Tank Hub installation procedure. Once installed, the Rosemount 5900 is configured via the **5900 RLG Properties** window. The 5900 RLG Properties window includes tabs for basic and advanced configuration.

When connecting a Rosemount 5900 Radar Level Gauge to a Rosemount 2410 Tank Hub in an existing Rosemount Tank Gauging system, the level gauge needs to be mapped to the appropriate tank in the tank hub's database. Configuration is performed via the 5900 RLG Properties window.

A Rosemount 5900 is most conveniently installed by utilizing the integrated option included as part of the Rosemount 2410 Tank Hub installation procedure.

It can also be installed and configured by using the WinSetup installation Wizard. This method should only be used in special cases when, for example, the 5900 is connected to the Tankbus at a later stage and not available when installing the Rosemount 2410 Tank Hub.

The following configuration steps are included in the Rosemount 5900 Radar Level Gauge basic configuration:

- communication parameters
- antenna type
- tank geometry

Configuration of a Rosemount may also include:

- Tank Scan
- Empty Tank Handling

Due to the properties of the product, the tank shape, or other circumstances, further configuration may be needed in addition to the basic configuration. Disturbing objects and turbulent conditions in the tank may require that advanced measures are taken. Advanced configuration options include:

- Tank Environment
- Tank Shape
- Surface Echo Tracking
- Filter Settings

### Related information

[Installing a Rosemount 5900 using the installation wizard](#)

[Advanced configuration](#)

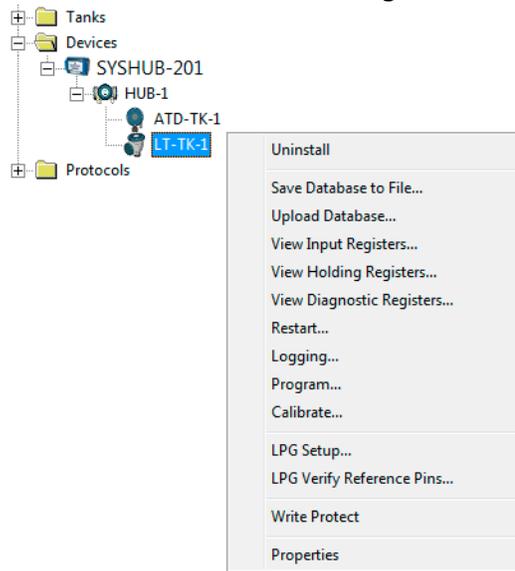
[Adding a tank](#)

## 2.7.1 Configuration via the Properties window

The basic configuration procedure of a Rosemount 5900 Radar Level Gauge is straightforward and easy to perform. All configuration options are available in the **Rosemount 5900 RLG Properties** window. For a basic configuration of the Rosemount 5900 do the following:

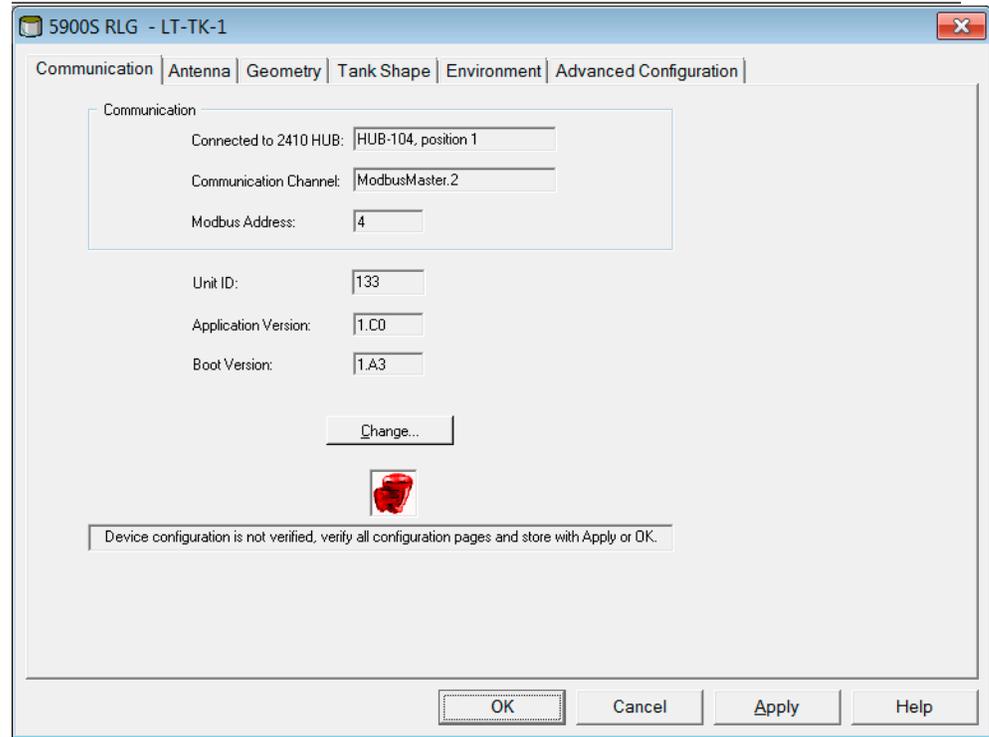
### Procedure

1. In the WinSetup **Workspace** window, open the **Devices** folder and select the Rosemount 5900S Radar Level Gauge icon.



2. Click the right mouse button and select **Properties**, or from the **Service** menu select **Devices** → **Properties**.

The **Communication**, **Antenna**, and **Geometry** tabs cover basic configuration of the Rosemount 5900.



3. Select the **Communication** tab. Note that a red gauge icon means that the device needs to be configured.
4. Verify the tank position.

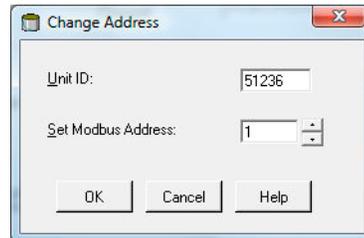
The **Connected to 2410 HUB** field shows the name of the Rosemount 2410 Tank Hub and the tank position that the device is mapped to in the tank hub's database. The tank position indicates which tank the device is associated with.

In most cases, the Rosemount 2410 single tank version is used for level gauges. In those cases, only one tank position will be used in the tank hub's database.

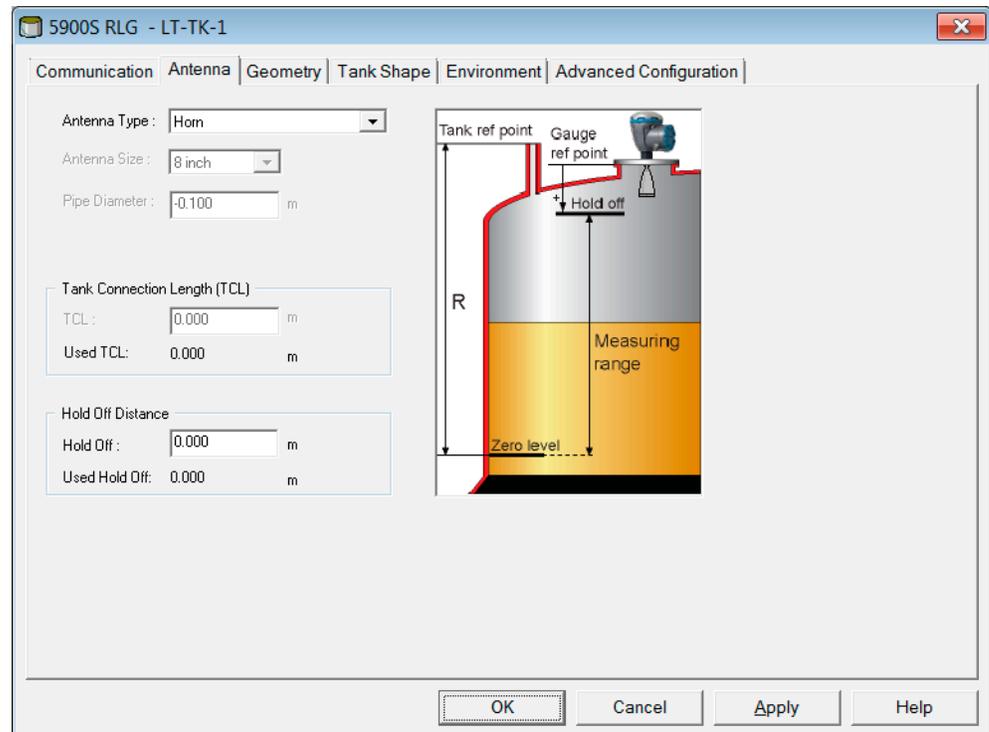
In case the multiple tank version of the Rosemount 2410 is used to connect several tanks, the level gauge can be mapped to another tank through the 2410 Tank Hub **Properties/Tank Database** window:

- a) in the WinSetup workspace click the right mouse button on the Rosemount 2410 icon.
- b) select **Properties** and open the **Tank Database** tab.
- c) select the desired tank position.

5. Verify that the Modbus® address is correct. To change the address:
  - a) Click the **Change** button to open the **Communication** window.
  - b) Click the **Change Address on Device** button to open the **Change Address** window:



- c) Enter the Unit ID. When changing the device address, the Unit Id is used as a unique identifier of the device. The Unit Id can be found on the main label.
  - d) Set the desired Modbus address.
  - e) Click **OK** to confirm the settings and close the **Change Address** window.
  - f) Click **OK** to close the **Communication** window.
6. In the **5900 RLG Properties/Communication** window click the **Apply** button to store the Modbus address in the 5900 holding register.
7. Select the **Antenna** tab:

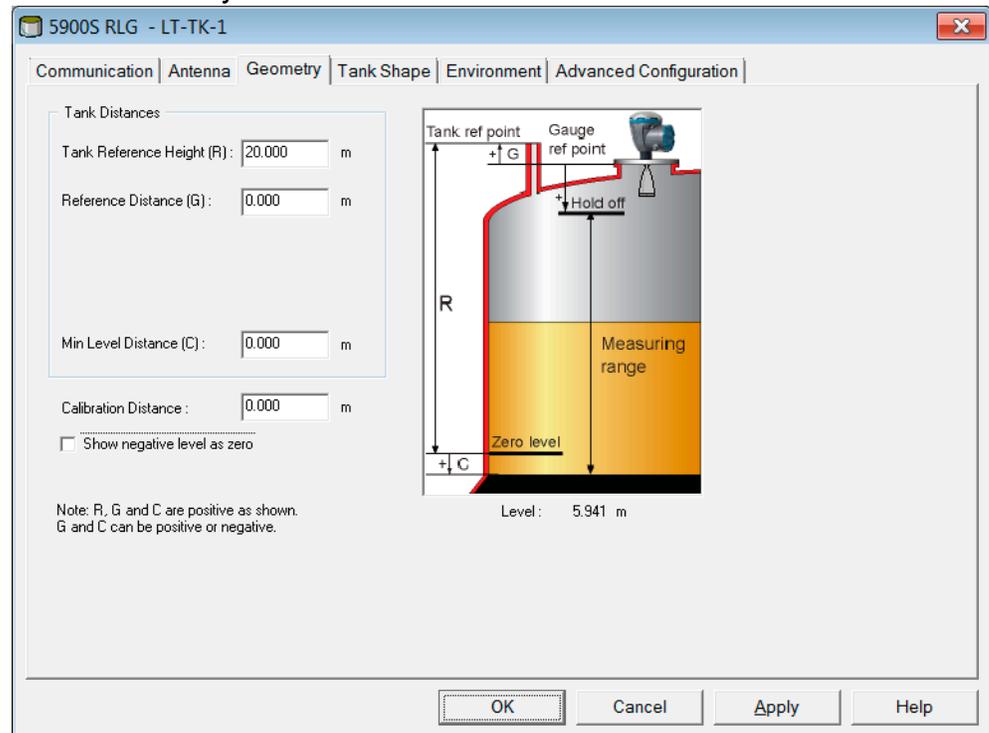


8. Select one of the predefined **Antenna Types** to match the antenna attached to the level gauge. For predefined antennas, a number of parameters are configured automatically in order to optimize measurement performance.

In case there are disturbances close to the nozzle you may need to adjust the **Hold Off Distance**. By increasing the Hold Off distance, the measurement range is reduced in the upper part of the tank.

For non-standard antennas you may choose one of the User Defined antennas. However, it is recommended that you contact Emerson Automation Solutions/ Rosemount Tank Gauging for advice before using this advanced option.

9. Click the **Apply** button to save the configuration.
10. Select the **Geometry** tab:



11. Enter the tank geometry parameters:
  - a) **Tank Reference Height**. This is the distance from the hand dip nozzle (Tank Reference Point) to the Zero Level (Datum Plate) close to the bottom of the tank.
  - b) **Reference Distance (G)**. This is the distance from the Gauge Reference Point to the Tank Reference Point, which is located at the side of the flange that meets the tank nozzle. G is positive if the Tank Reference Point is located above the Gauge Reference Point, otherwise G is negative (see [Figure 2-6](#)).

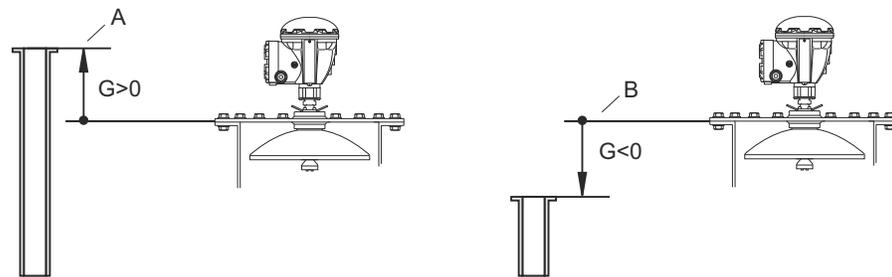
When using a Rosemount 5900 with Still-pipe Array antenna and hinged hatch, the Tank Reference Point is located at the hand-dip plate inside the hatch. The hand-dip plate is also used as the Gauge Reference Point for this antenna type, which means that  $G=0$ .

- c) **Minimum Level Distance (C)**. This is defined as the distance between the **Zero Level** (Dipping Datum Point) and the minimum level for the product surface. By specifying a C-distance the measuring range can be extended to the bottom of the tank.

**C>0**: the level gauge presents negative level values when the product surface is below the Zero Level. The **Show negative level values as zero** check box lets you present product levels below the Zero Level (Datum plate) as equal to zero.

**C=0**: measurements below the Zero Level will not be approved, i.e. the RLG will report “invalid level” if the product level is below the Datum Plate.

**Figure 2-6: Reference Distance (G)**



- A. Tank Reference Point  
B. Gauge Reference Point

12. Enter the **Calibration Distance**. Use this parameter to calibrate the level gauge so that measured product levels match hand dipped levels. A minor adjustment may be necessary when the gauge is installed. For example, a minor deviation between the actual tank height and the value stored in the device database may occur if tank dimensions according to drawings are not quite up to date with actual dimensions. For still-pipe applications the **Calibrate** function in the TankMaster WinSetup program is a useful tool to configure the **Calibration Distance** and the **Correction Factor**.
13. Optional: Select the **Show negative level as zero** check box in case you don't want the transmitter to show negative level values.
14. Click the **OK** button to save the configuration and close the configuration window.

### Postrequisites

In addition to the configuration steps described above, a basic configuration of the Rosemount 5900 may include using the **Tank Scan** function to verify that there are no disturbing objects in the tank that may interfere with the level measurements. Also, the **Empty Tank Handling** function may be used to optimize measurement performance near the tank bottom.

### Related information

[Antenna configuration](#)  
[Tank Database setup](#)

[Advanced configuration](#)  
[Calibrating the level gauge](#)  
[Rosemount 5900S Reference Manual](#)  
[Rosemount 5900C Reference Manual](#)

## Antenna configuration

In the **5900 Properties/Antenna** window several antenna types are available. For some of them additional configuration is required, such as antenna size and pipe diameter.

Antenna types:

- Horn
- Parabolic
- Still-Pipe Array Fixed
- Still-Pipe Array Hatch
- LPG/LNG
- Cone (5900C)
- Cone Pipe (5900C)

For the LPG/LNG antenna you need to select the appropriate option:

- LPG/LNG 150 PSI + Valve
- LPG/LNG 150 PSI
- LPG/LNG 300 PSI + Valve
- LPG/LNG 300 PSI
- LPG/LNG 600 PSI + Valve
- LPG/LNG 600 PSI

For the Cone antenna the following options are available:

- Cone 4" PTFE
- Cone 4" Quartz
- Cone 6" PTFE
- Cone 6" Quartz
- Cone 8" PTFE
- Cone 8" Quartz

For the Cone Pipe antenna the following options are available:

- Cone Pipe PTFE
- Cone Pipe Quartz

## Pipe diameter

For Still-pipe Array, LPG, and Cone Pipe<sup>(3)</sup> antennas you need to specify Pipe Diameter. Pipe Diameter parameter compensates for the lower microwave propagation speed inside a still-pipe. See also "Using the Calibrate function" on page 138 for information on how to calibrate the 5900 for still-pipe installations.

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(3) Rosemount 5900C only

For pipe antennas it is very important that the accurate pipe diameter is input to WinSetup in order to avoid scale factor deviations which may result in inaccurate level readings.

For Cone Pipe antennas supplied by factory the following nominal values are recommended as input in TankMaster WinSetup:

Antenna	Nominal Pipe Diameter
Cone Pipe 1 inch	30 mm
Cone Pipe 2 inch	56 mm

### Related information

[Using the Calibrate function](#)

### Antenna size

For Still-pipe Array antennas, various antenna size options are available:

- 5 inch
- 6 inch
- 8 inch
- 10 inch
- 12 inch

### User Defined antenna

The **User Defined** option should only be used for special applications when using non-standard antennas.

### Procedure

1. Choose the appropriate antenna type:
  - User Defined Free Propagation
  - User Defined Still-Pipe
  - User Defined Still-Pipe Array
2. Enter the **Tank Connection Length** in the TCL input field.
3. For still pipe applications, type the inner diameter of the still pipe in the **Pipe Diameter** input field.
4. In case there are disturbances close to the nozzle you may need to adjust the **Hold Off Distance**. By increasing the Hold Off distance, the measurement range is reduced in the upper part of the tank.
5. Select **Apply** to save the configuration.

## 2.7.2 Advanced configuration

In addition to the basic configuration, there are advanced configuration options available for the Rosemount 5900 Radar Level Gauge. These may be used to optimize measurement performance for certain applications.

### Related information

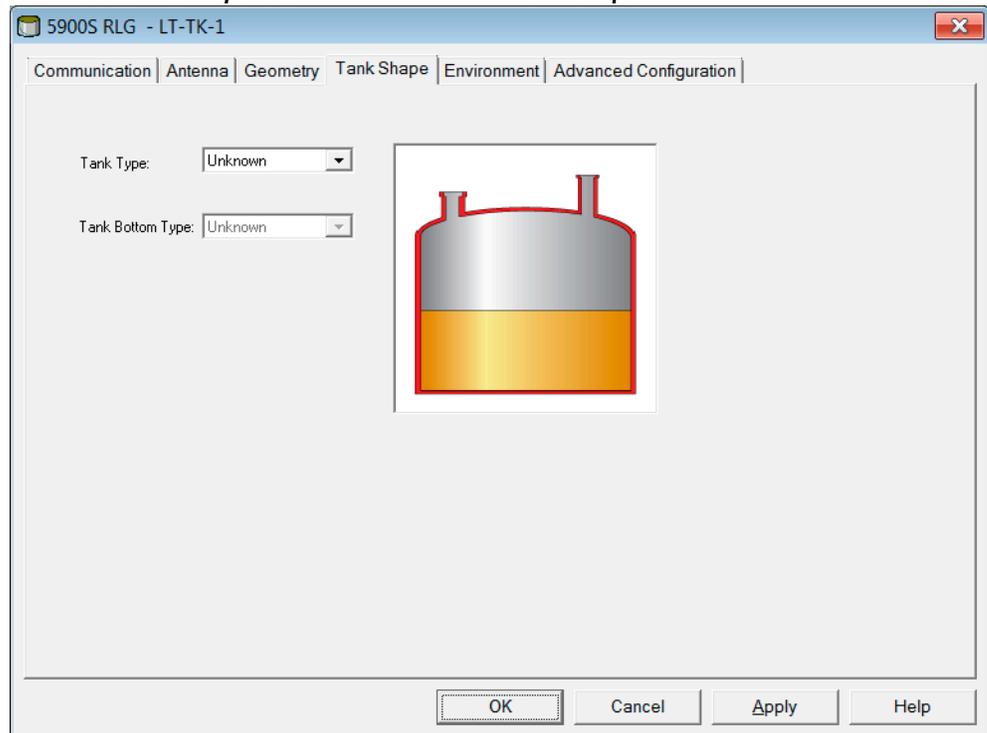
[Installing a Rosemount 5900 Radar Level Gauge](#)

## Tank Shape

The Tank Type and Tank Bottom Type parameters optimize the Rosemount 5900 for various tank geometries and for measurements close to the tank bottom.

### Procedure

1. In the *5900 RLG Properties* window select the *Tank Shape* tab:



2. Select a **Tank Type** option that is similar to the actual tank. Choose **Unknown** if there is no applicable option.
3. Select **Tank Bottom Type** that matches the actual tank. Choose **Unknown** if there is no applicable option.
4. Click the **OK** button to save the configuration and close the window.

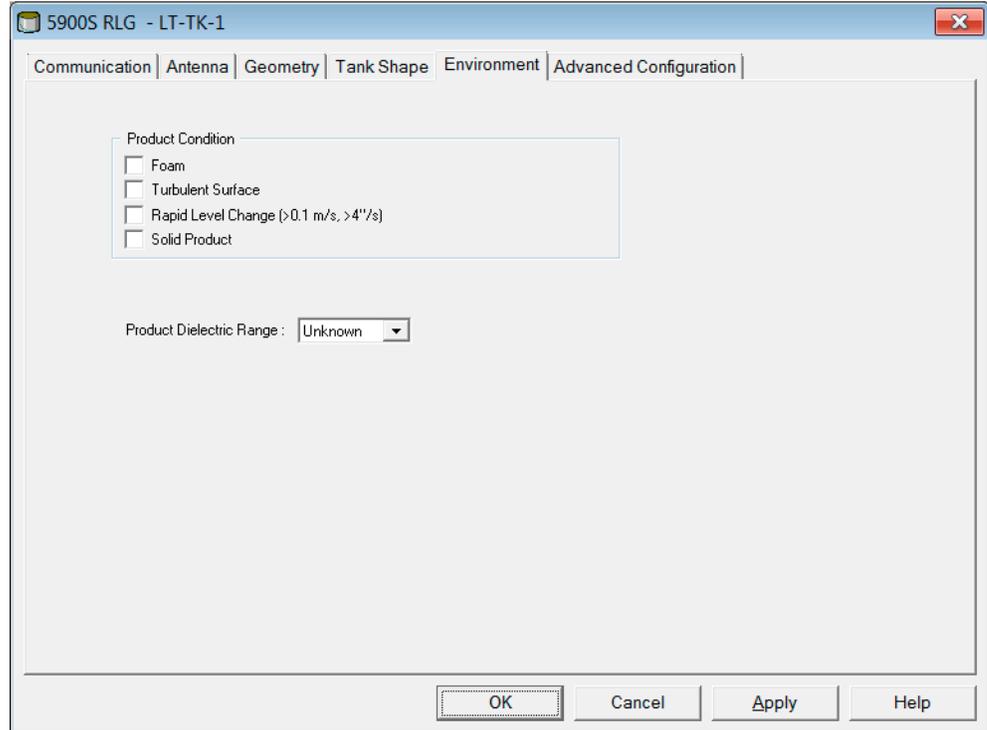
## Tank Environment

Certain tank conditions may require additional configuration of the Rosemount 5900 Radar Level Gauge in order to optimize measurement performance. By considering

environmental conditions in the tank, the Rosemount 5900 can compensate for conditions such as rapid level changes, weak echo signals, or varying surface echo amplitudes.

### Procedure

1. In the **5900 RLG Properties** window select the **Environment** tab:



2. Select the check boxes that correspond to the conditions in the tank. Use as few options as possible. It is recommended that no more than two options are used simultaneously.
3. Select **Product Dielectric Range** from the drop-down list. Select the Unknown option if the correct value range is unknown or if the contents of the tank is changing on a regular basis.
4. Click the **OK** button to save the configuration and close the window.

### Related information

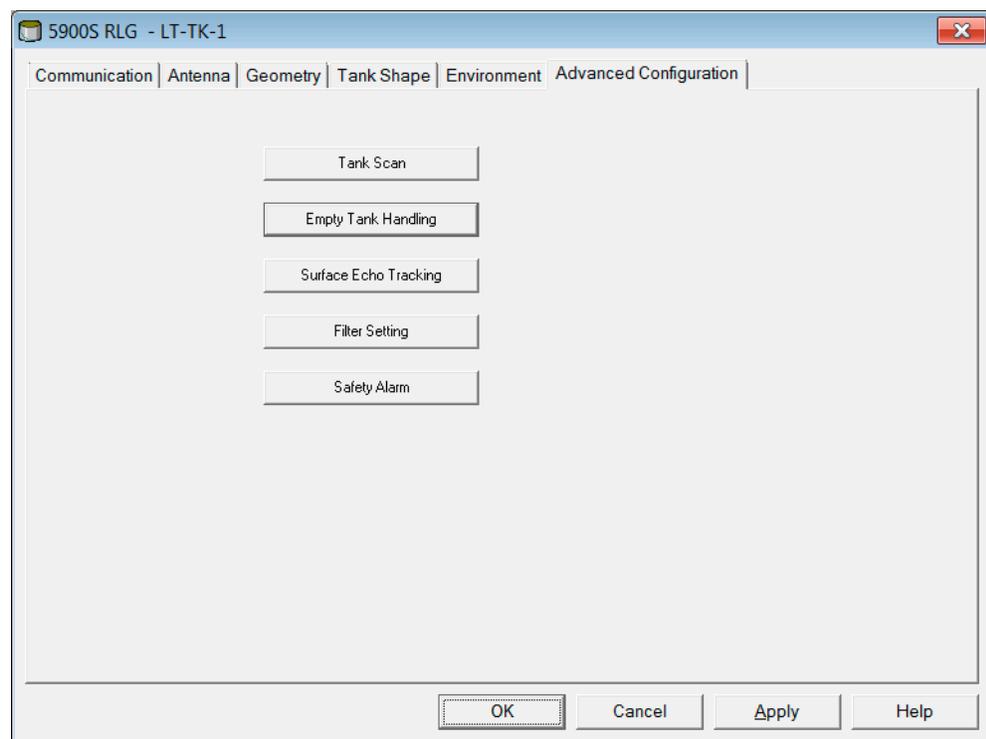
[Rosemount 5900S Reference Manual](#)  
[Rosemount 5900C Reference Manual](#)

## Advanced Configuration window

The *Advanced Configuration* window provides further configuration options. The following options are available:

- Tank Scan<sup>(4)</sup>
- Empty Tank Handling<sup>(4)</sup>
- Surface Echo Tracking
- Safety Alarm (only used for SIL safety systems)

**Figure 2-7: The 5900S RLG Properties/Advanced Configuration window**



### Related information

[Rosemount 5900S Reference Manual](#)  
[Rosemount 5900C Reference Manual](#)

<sup>(4)</sup> May also be used in Basic configuration

## 2.7.3 Installing a Rosemount 5900 using the installation wizard

The installation wizard in TankMaster WinSetup is a tool that may be used to install and configure various devices in a Rosemount Tank Gauging system.

Field devices are typically installed as part of the installation procedure for a Rosemount 2410 Tank Hub. However, the installation wizard lets you install devices in TankMaster separately from the tank hub installation.

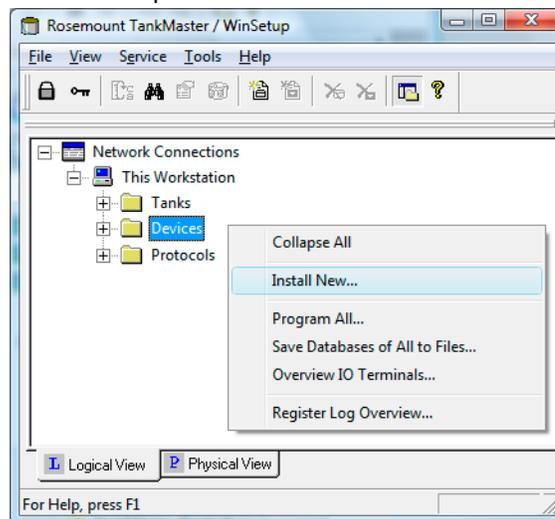
### Prerequisites

Ensure that the tank databases of the Rosemount 2460 System Hub and the Rosemount 2410 Tank Hub are properly configured for the new Rosemount 5900.

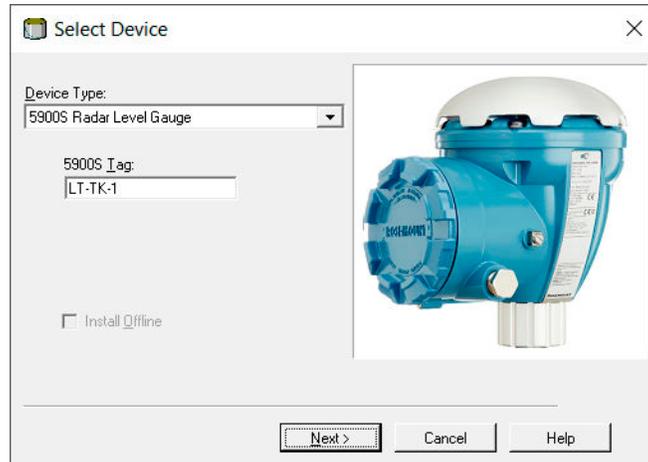
Ensure that the correct Modbus® address is configured for the new device.

### Procedure

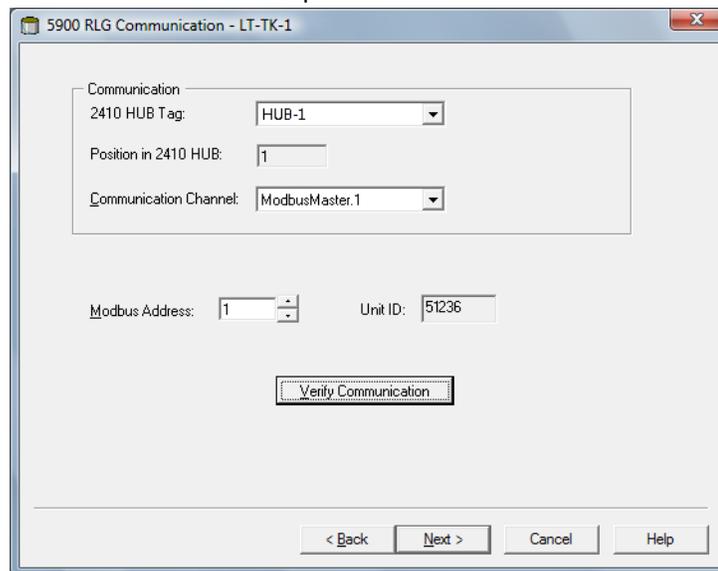
1. In the Workspace window select the **Devices** folder.



- Click the right mouse button and select **Install New**, or from the **Service** menu select **Devices** → **Install New**.



- Select Device Type **5900S Radar Level Gauge** from the drop-down list.
- Enter the desired tag for identifying the device.
- Click the **Next** button to open the **5900 RLG Communication** window:

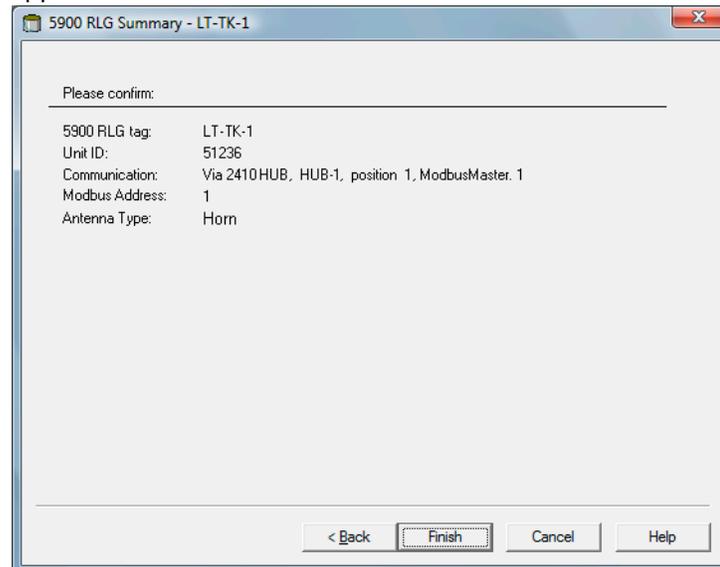


- In the 2410 HUB Tag drop-down list, select the tank hub that the Rosemount 5900 Radar Level Gauge is connected to. Normally, there is one tank hub for each tank.
- Enter the **Modbus address**. This address must be available in the tank databases of the Rosemount 2460 System Hub and the Rosemount 2410 Tank Hub.
- Click the **Verify Communication** button to confirm that the TankMaster PC communicates with the device. The Unit ID will appear when contact is established.

9. Check the **Position in 2410 HUB** field to verify that the device is mapped to the correct tank position in the Rosemount 2410 tank database. The tank position indicates which tank the device is associated with. Normally, the single tank version of the Rosemount 2410 Tank Hub is used for level gauges. In those cases the **Position in 2410 HUB** field will be equal to 1 since there is only one tank position that is used in the tank hub's database.

In case the multiple tank version of the Rosemount 2410 Tank Hub is used for several tanks, the level gauge can be mapped to the desired tank via the **2410 Tank Hub Properties/Tank Database** window:

- a) In the WinSetup workspace, click the right mouse button on the tank hub icon.
  - b) Select the **Properties** option.
  - c) Select the **Tank Database** tab and map the device to the desired tank position.
10. Click the **Next** button to proceed with the Rosemount 5900 configuration.
  11. In the 5900 RLG **Summary** window, click the **Finish** button to verify the configuration and finish the installation wizard. In case some part of the configuration needs to be changed, click the **Back** button until the desired window appears.



### Postrequisites

Verify that the device communicates with the Rosemount 2410 Tank Hub. Use for example the tank hub's **Device Live List** function to see all devices connected to the tank hub. The live list is available by right clicking the tank hub's device icon.

Further configuration options are available in the **5900 RLG Properties** window.

### Related information

[Installing a Rosemount 5900 Radar Level Gauge](#)

[Configuration via the Properties window](#)  
[Advanced configuration](#)  
[Installing a Rosemount 2460 System Hub](#)  
[Installing a Rosemount 2410 Tank Hub](#)  
[Tank Database setup](#)  
[Rosemount 5900S Reference Manual](#)  
[Rosemount 5900C Reference Manual](#)

## 2.8 Installing the Rosemount 5900S 2-in-1 version

Installing a 2-in-1 Rosemount 5900S Radar Level Gauge is in most parts similar to installing a standard 5900S. A significant difference though, is that in the TankMaster operator's interface the Rosemount 5900S 2-in-1 version will be configured as two separate gauges, and each gauge will be associated with its own tank.

### 2.8.1 Overview

To install and configure a 2-in-1 version of the Rosemount 5900S level gauge:

#### Procedure

1. In Rosemount TankMaster WinSetup, configure the Rosemount 2460 System Hub's tank database by adding two Rosemount 5900S gauges.
2. In Rosemount TankMaster WinSetup, install the Rosemount 2410 Tank Hub.
3. Configure the new tank hub's tank database:
  - a) map the two Rosemount 5900S gauges to two different tank positions, i.e. configure the Primary and Secondary gauges as if they are installed on two different tanks
  - b) assign a Level Modbus® address for each Rosemount 5900S
4. Assign tags for the Rosemount 5900S Radar Level Devices and the Auxiliary Tank Device<sup>(5)</sup> (ATD). The ATD includes various non-level devices such as temperature transmitters, displays, and pressure transmitters.
5. Install the devices in the TankMaster workspace. This is done automatically by the installation wizard for the Rosemount 2410 in case the **Install Level and AUX devices** check box is selected in the **Rosemount 2410 Tank Hub Summary** window.
6. Configure the level gauges and ATD devices (right-click the device icon and select **Properties**).
7. Install two new tanks to be associated with the primary and secondary Rosemount 5900S radar level gauges.
8. Assign a Rosemount 5900S and an ATD for the primary tank.
9. Assign a Rosemount 5900S for the secondary tank. Note that the primary and secondary tanks in TankMaster workspace represent one tank in real life.
10. Configure the tanks.
11. Open the TankMaster workspace to verify correct installation of tanks and devices.

#### Related information

[Installing a Rosemount 2410 Tank Hub](#)

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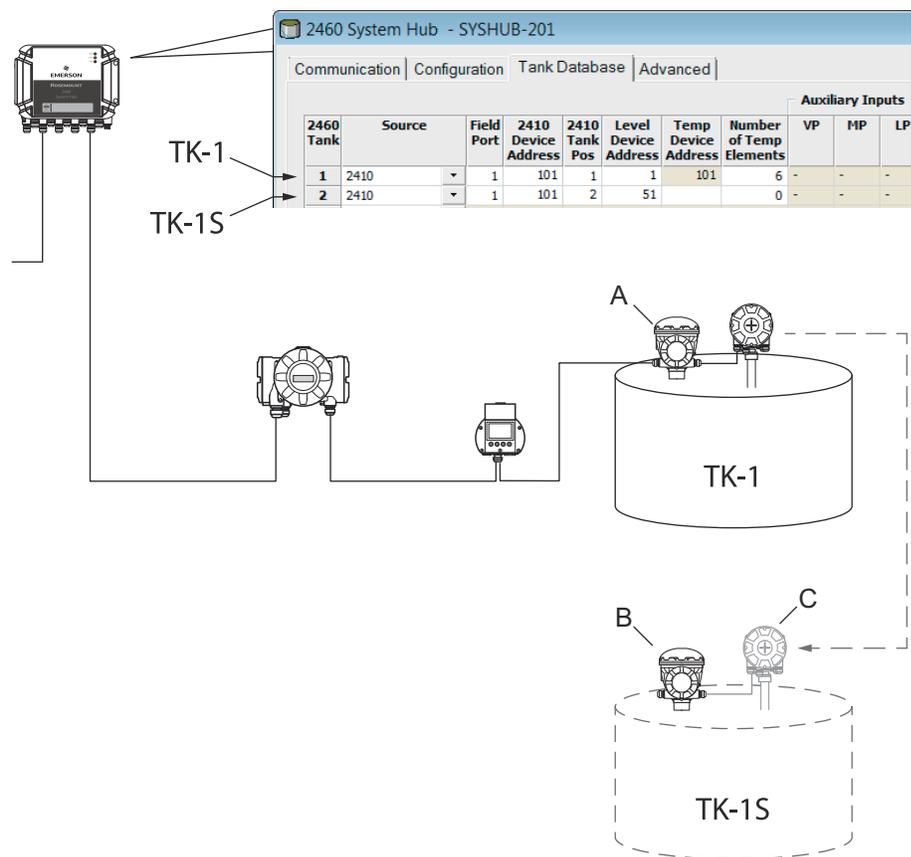
(5) Auxiliary Tank Device (ATD) is used in the Tank Database of the Rosemount 2410 Tank Hub to designate various devices such as temperature and pressure transmitters, displays and other non-level devices.

## Configuration example of Rosemount 5900S 2-in-1

The Rosemount 5900S 2-in-1 version is installed and configured in TankMaster as a tank gauging system with two tanks. Various configuration options are possible:

1. Primary tank with 5900S and ATD (2240S, 2230 ...). Secondary tank with 5900S.
2. Primary tank with 5900S and ATD (2240S, 2230 ...). Secondary tank with 5900S. ATD on Primary tank mapped to secondary tank (see [Figure 2-8](#)).
3. Primary tank with 5900S and ATD (2240S, 2230...). Secondary tank with 5900S and redundant ATD.

**Figure 2-8: Example of a Rosemount 5900S 2-in-1 System**



- A. Rosemount 5900S 2-in-1 on Primary tank
- B. Rosemount 5900S 2-in-1 on Secondary tank
- C. Rosemount 2240S: mapped from primary tank

## 2.8.2 Installation and configuration

To install and configure the 2-in-1 version of the Rosemount 5900S, follow these steps:

### Procedure

1. Start the TankMaster WinSetup program.
2. Configure the Rosemount 2460 System Hub's tank database. Since the Rosemount 5900S 2-in-1 version includes two separate gauges, you will have to add two Level Device addresses in the Tank Database.
3. Assign Modbus® addresses for the Rosemount 5900S 2-in-1 level devices.

2460 System Hub - SYSHUB-201								Auxiliary In	
2460 Tank	Source	Field Port	2410 Device Address	2410 Tank Pos	Level Device Address	Temp Device Address	Number of Temp Elements	VP	MP
A	2410	1	101	1	1	101	6	-	-
B	2410	1	101	2	51		0	-	-
3	(none)								
4	(none)								

- A. Primary tank  
B. Secondary tank

### Example

Primary tank TK-1: address=1

### Example

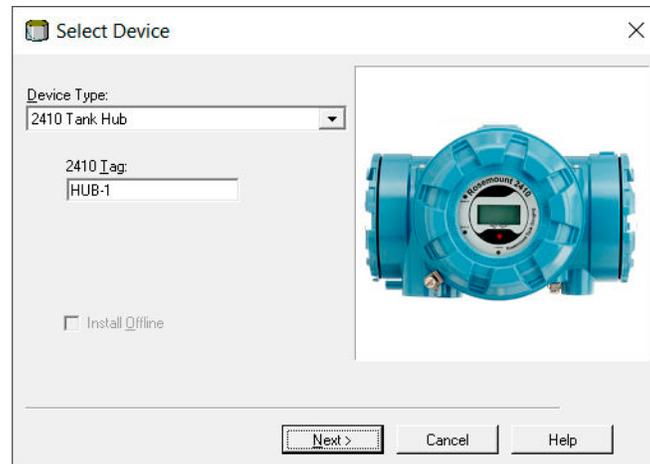
Secondary tank TK-1S: address=51

- It is recommended that Modbus address 50 + “X” is used for the secondary level device, where “X” is the address of the primary level device.
- For the Primary tank the temperature device will automatically be assigned the same Modbus address as the Rosemount 2410 Tank Hub.
- For the Secondary tank you will not need to enter a “Temp Device Address”.
- Do not configure any temperature elements (Number of Temp Elements=0) for the Secondary temperature device.

In case two temperature transmitters are installed on the tank, one to be associated with the Primary and the other to the Secondary tank, you will need to configure Temp Device Address as well as Number of Temp Elements for both tanks. This configuration is like a standard configuration with one Rosemount 2410 connected to two separate tanks.

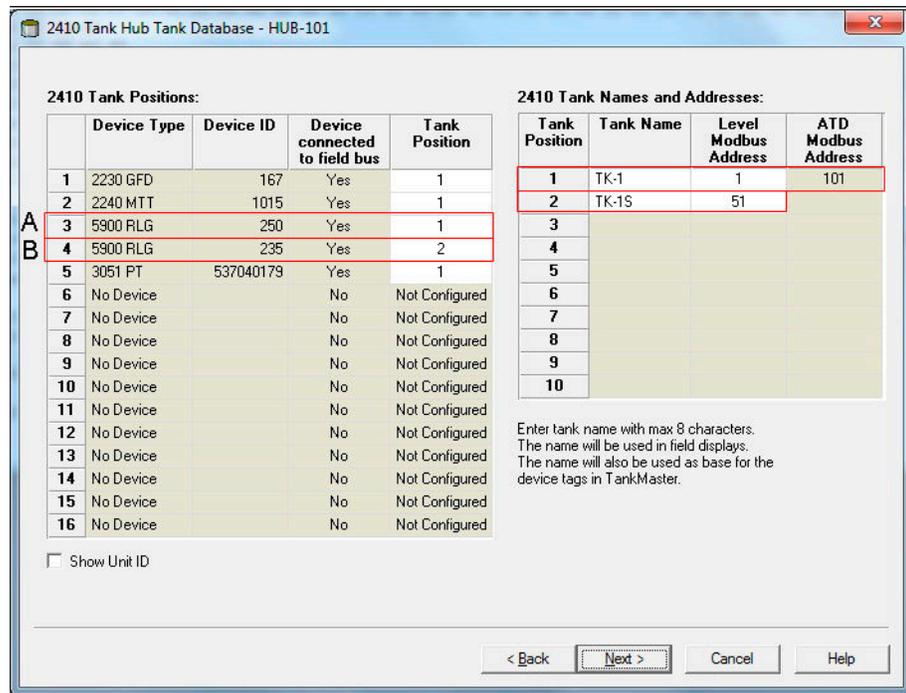
2460 Tank	Source	Field Port	2410 Device Address	2410 Tank Pos	Level Device Address	Temp Device Address	Number of Temp Elements	Auxiliary Inputs		
								VP	MP	LP
1	2410	1	101	1	1	101	6	-	-	-
2	2410	1	101	2	51	102	6	-	-	-

- Proceed with installing a Rosemount 2410 Tank Hub. In the WinSetup workspace, select the **Devices** folder, click the right mouse button and select **File** → **Install New**:



- In the **Select Device** window, select Device Type 2410 Tank Hub and assign a 2410 Tag.
- Click the **Next** button to proceed to the **Tank Database** configuration window.

7. Configure the tank hub's tank database:



- A. Primary level gauge on TK-1
- B. Secondary level gauge on TK-1S

In the tank database, the Rosemount 5900S 2-in-1 will appear as two separate level gauges. The two gauges are mapped to different tank positions and will be associated with different tanks in the WinSetup workspace.

**Example**

Assign the same name on the two tanks. Add “S” to the secondary tank name, for example:

primary tank: TK-1

secondary tank: TK-1S

Assign Level Modbus Addresses to the gauges. Example:

TK-1: 1

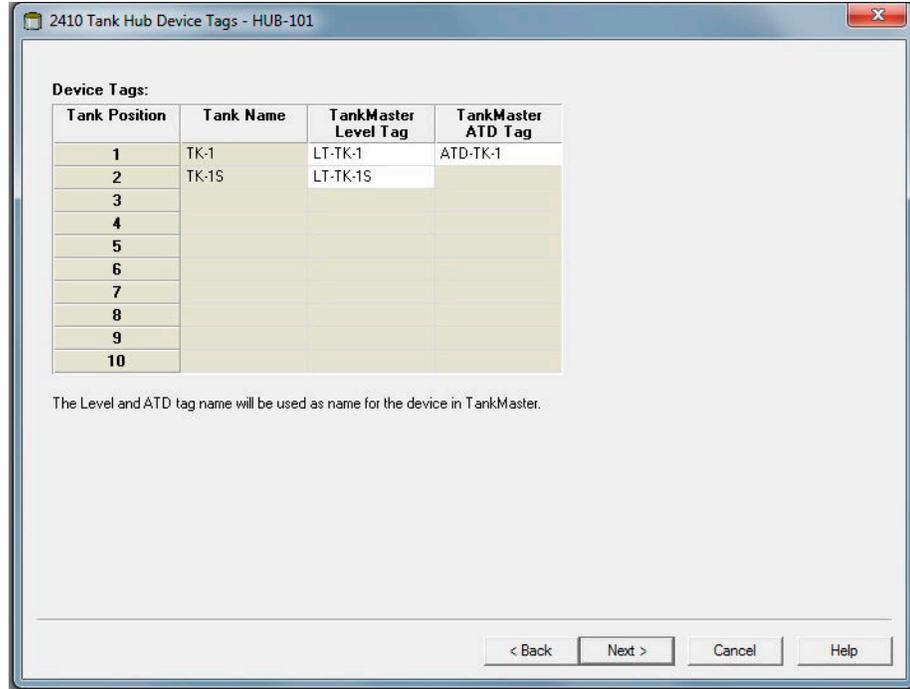
TK-1S: 51

It is recommended that Modbus address 50 + “X” is used for the secondary device, where “X” is the address of the primary radar level gauge.

Ensure that the same addresses are configured in the tank databases for the Rosemount 2460 System Hub and the Rosemount 2410 Tank Hub, respectively.

8. Click **Next** to proceed to the *Device Tags* window.

9. Verify **Level Tags** for the primary and secondary Rosemount 5900S gauges, and **ATD Tags** for the other devices (temperature transmitter, field display, pressure transmitter). The tags can be changed later if needed.

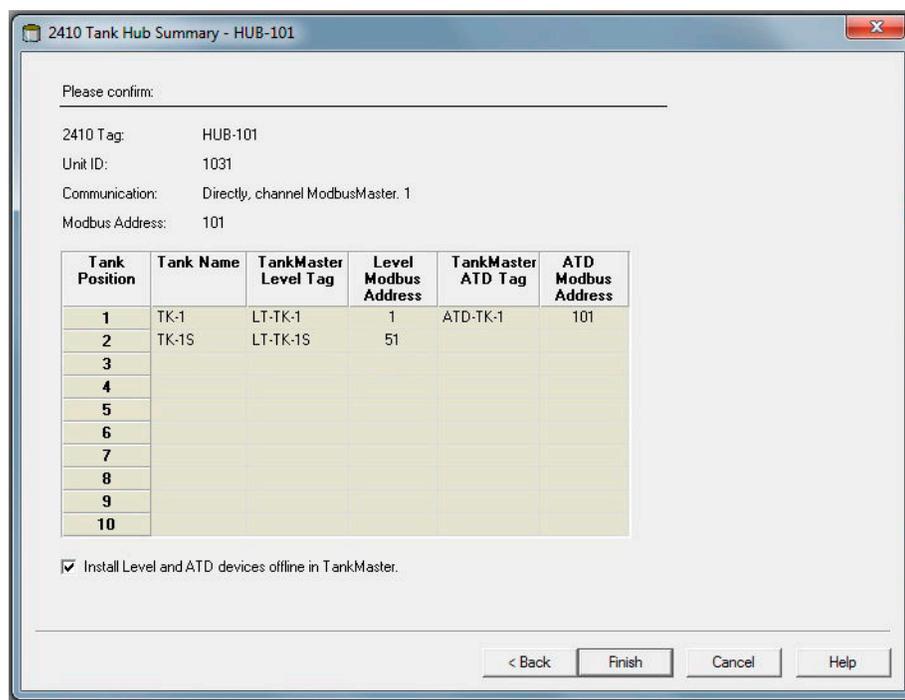


10. In the final step of the Rosemount 2410 installation wizard, check that all device tags and Modbus addresses are correct. Note that if a Rosemount 2460 System Hub is used, the Modbus addresses in the Rosemount 2410's tank database must match the addresses configured in the Rosemount 2460's tank database.

Ensure that the **Install Level and ATD devices...** check box is selected in case you like to enable automatic installation of devices in the TankMaster workspace. This is the recommended setting.

**Note**

If new devices are added to an existing Rosemount 2410 Tank Hub, the Install Level and ATD devices check box may not be active. Then you will have to add the new devices manually.

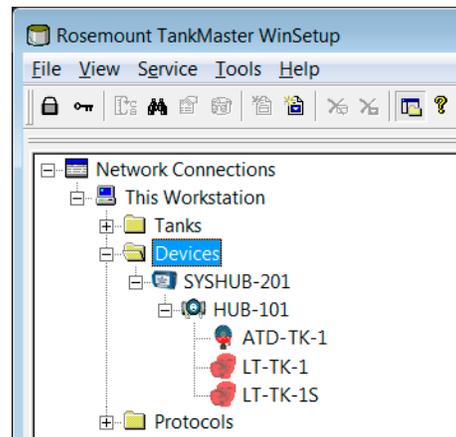


11. Verify that the devices appear in the WinSetup workspace. The Rosemount 2410 Tank Hub, the two Rosemount 5900S RLGs, and the ATD are automatically installed in the TankMaster WinSetup workspace if the check box is marked in the **2410 Tank Hub Summary** window.

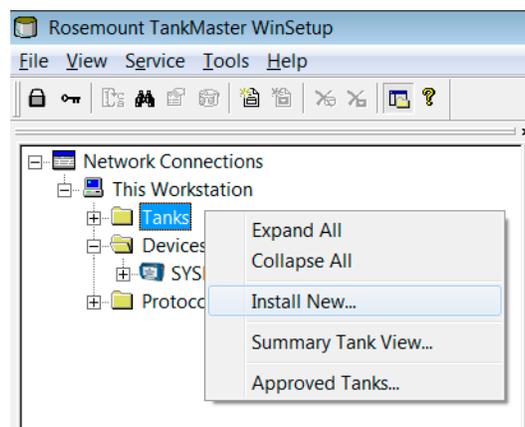
**Note**

The new device icons are red indicating that these devices need to be configured.

Once the tank hub and associated level and ATD devices are installed in TankMaster you will have to configure each device.



12. Configure the level gauges and ATD devices (right-click the device icon and select Properties).
13. Finally, when devices are installed and configured you will have to install and configure the two tanks to be associated with the 2-in-1 Rosemount 5900S. In the following description one tank will be associated with the **primary** level gauge (LT-TK-1 in this example), and the other tank will be associated with the **secondary** level gauge (LT-TK-1S).
  - a) Select the **Tanks** folder.
  - b) Click the right mouse button and select the **Install New** option.



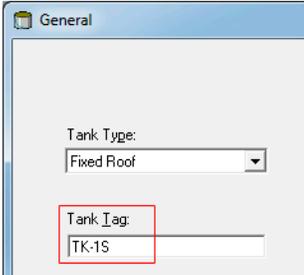
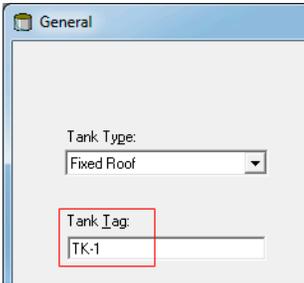
- c) Install and configure the primary tank first and then the secondary tank.

14. For each tank, select **Tank Type** and assign a **Tank Tag**. It is recommended that you use the same tank name as specified in the tank database of the Rosemount 2410 Tank Hub.

**2410 Tank Names and Addresses:**

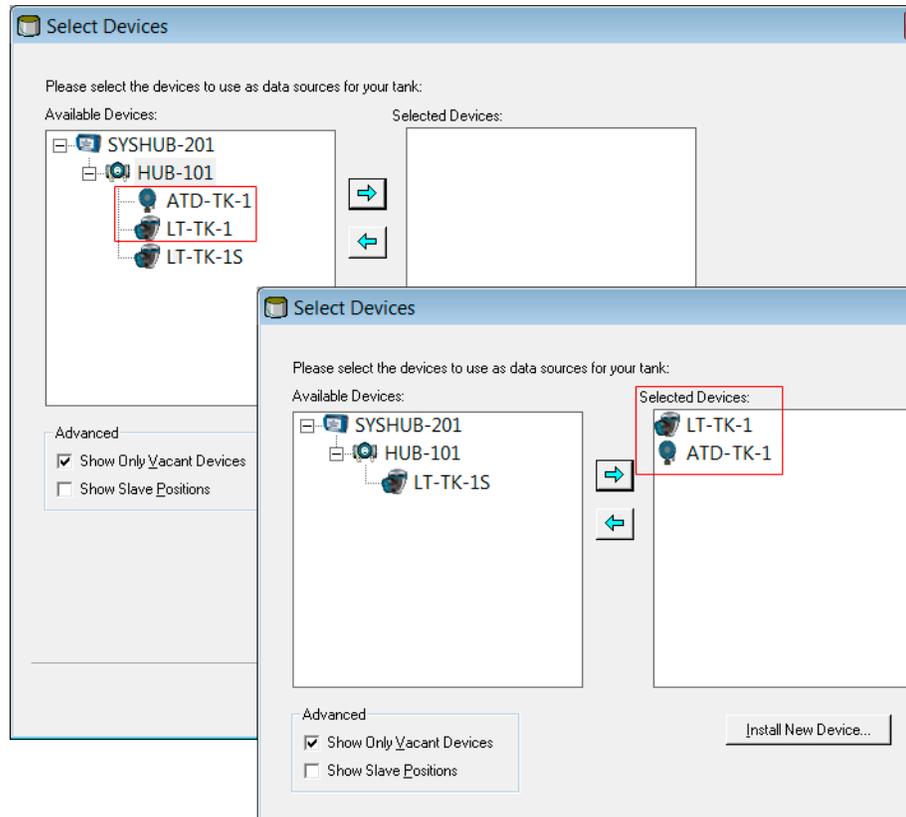
Tank Position	Tank Name	Level Modbus Address	ATD Modbus Address
1	TK-1	1	101
2	TK-1S	51	
3			
4			
5			
6			
7			
8			
9			
10			

Enter tank name with max 8 characters.  
The name will be used in field displays.  
The name will also be used as base for the device tags in TankMaster.

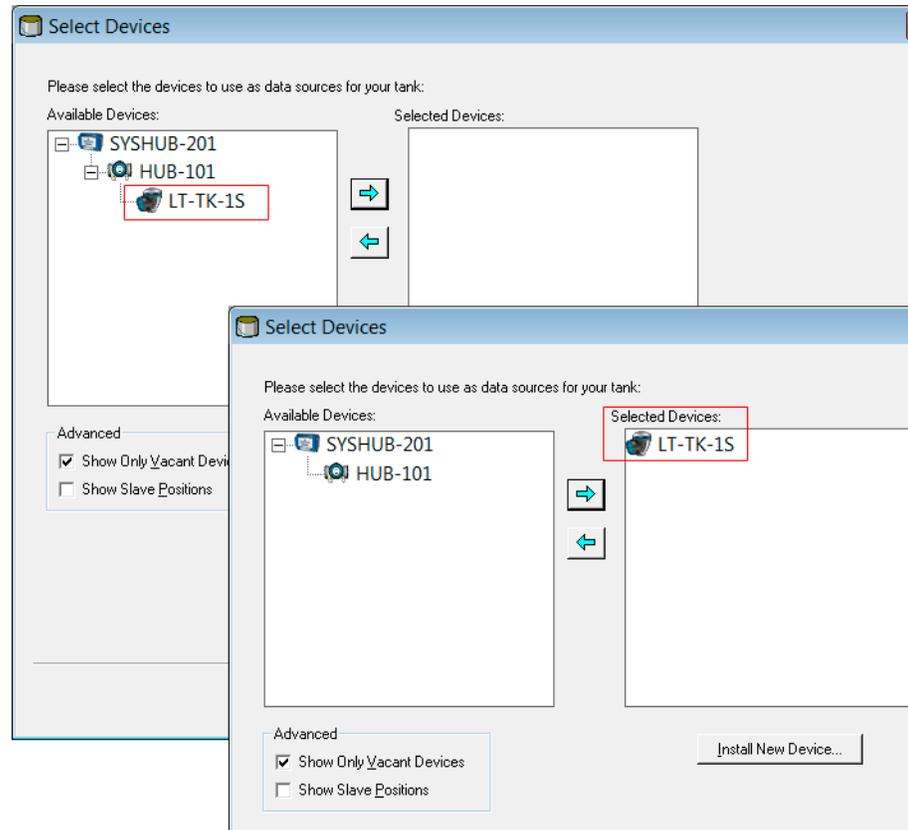


15. Assign devices to the primary tank TK-1:
- Primary Rosemount 5900S level gauge (LT-TK-1)
  - ATD device (ATD-TK-1) in case the tank is equipped with non-level devices such as a Rosemount 2240S Temperature Transmitter, a Rosemount 2230

Graphical Field Display, Water Level Sensor, or a Rosemount 3051S Pressure Transmitter.



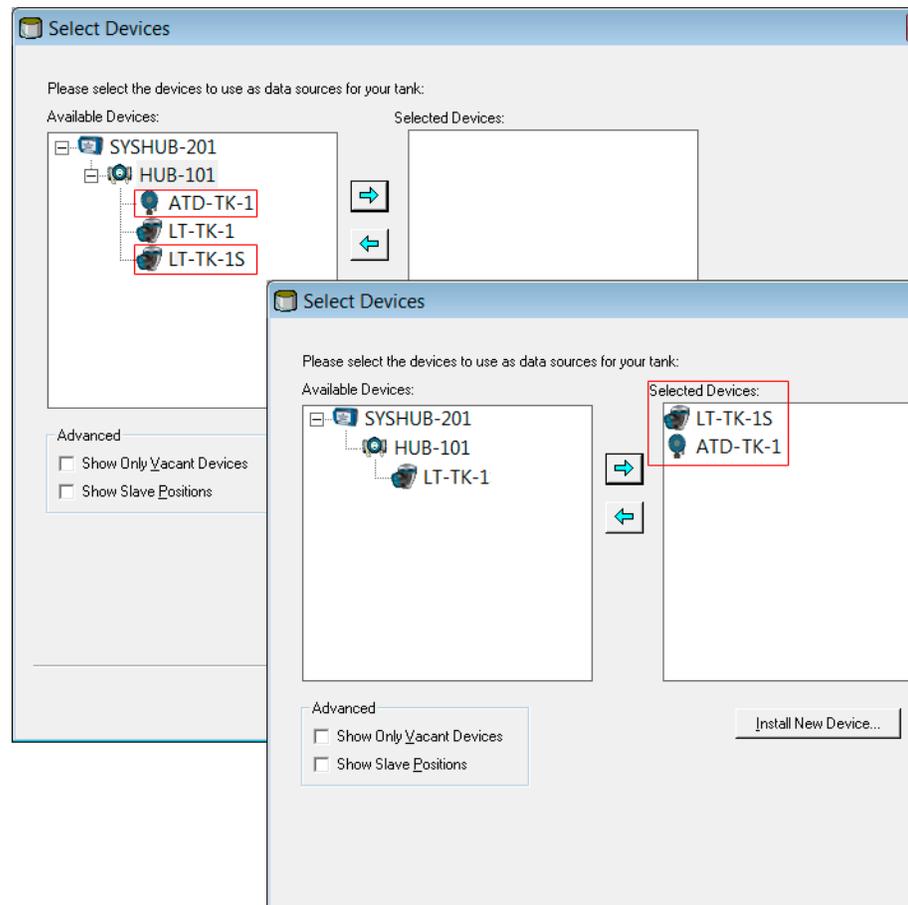
16. For the secondary tank TK-1S assign the secondary 5900S level gauge (LT-TK-1S) as shown below:



- Optional: You may map the ATD device on the primary tank to the secondary tank TK-1S as shown below. This allows you to view temperature data, such as Average Temperature, for the secondary tank as well.

**Note**

You need to ensure that **Show Only Vacant Devices** is not selected in order to view all devices.

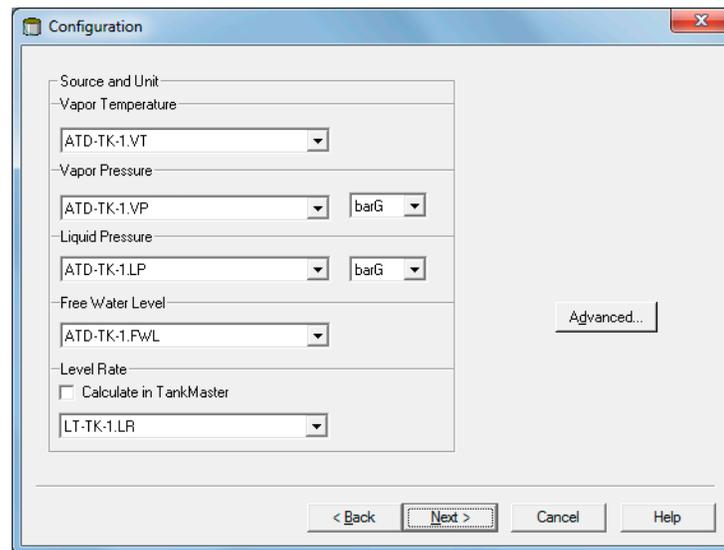


18. Choose the desired tank measurement variables. For the primary tank, variables associated with the ATD device automatically appears in the **Configuration** window.

**Note**

The available source variables may vary depending on the actual devices connected to the Rosemount 2410 Tank Hub.

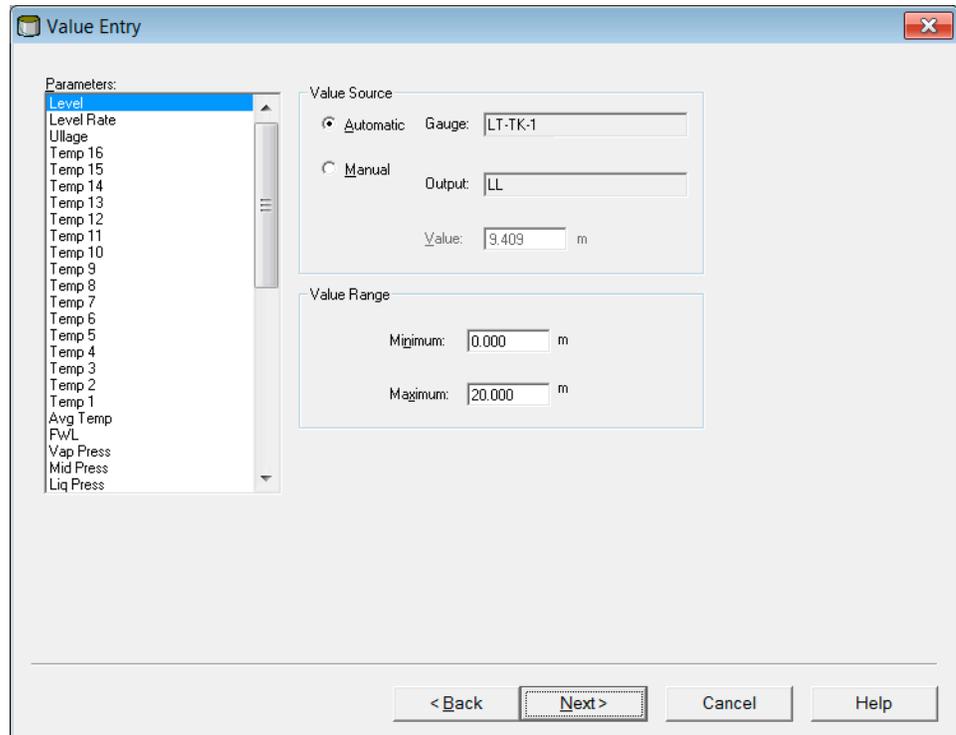
For the secondary tank, “none” is automatically selected for temperature and pressure variables as well as for free water level. In case the ATD device on the primary tank is mapped to the secondary tank as well, those variables will appear in the **Configuration** window for the secondary tank.



- Specify parameter **Value Range** (Minimum, Maximum) to be used in various windows for presentation of measurement data.

**Note**

Calculation of the Average Temperature (AVG Temp) requires a valid Level value. In case the Level value is not available, the Average Temperature (AVG Temp) will also be missing.



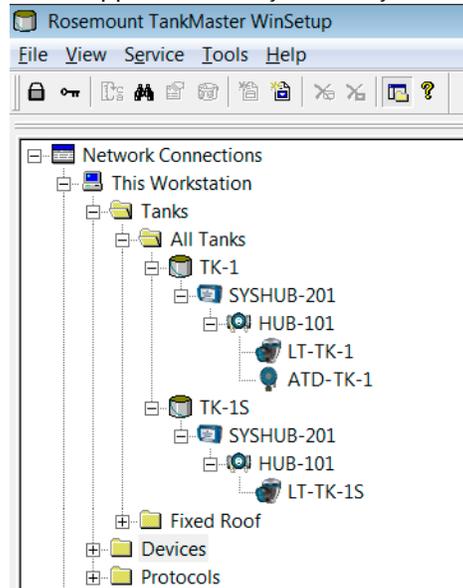
- Configure whether to use measurement values (**Automatic**) from the available instruments or **Manual** values.

21. In the TankMaster WinSetup workspace verify that the tanks and devices are properly installed. Check that the two Rosemount 5900S gauges and the ATD are associated with the right tanks. Two options are shown below:

- ATD (temperature transmitter, etc.) is associated with the primary tank only
- ATD on primary tank is mapped to both the primary and secondary tanks

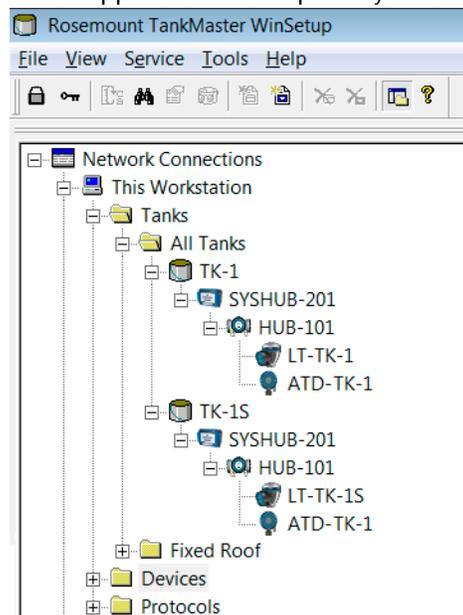
### Example

ATD mapped to Primary tank only



### Example

ATD mapped to both the primary and secondary tank



**Related information**

[Installing a Rosemount 5900 Radar Level Gauge](#)  
[Installing Auxiliary Tank Devices](#)

## 2.9 Installing Auxiliary Tank Devices

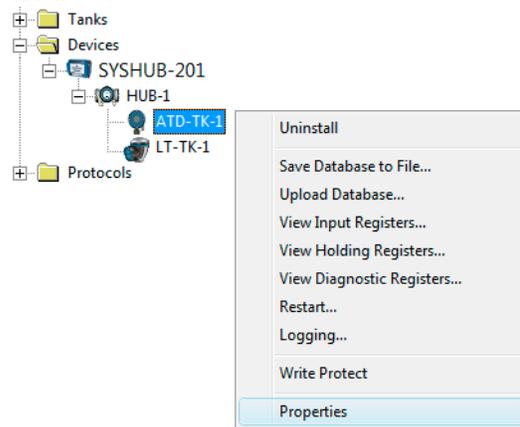
Auxiliary Tank Devices (ATDs) such as the Rosemount 2240S Multi-input Temperature Transmitter and the Rosemount 2230 Graphical Field Display, are typically installed as part of the installation procedure of the Rosemount 2410 Tank Hub.

ATD devices appear in the TankMaster workspace and are configured via the 22XX ATD window. The **22XX ATD** window includes tabs for configuration of temperature sensors, graphical field displays, and water level sensors. It also includes configuration options for mapping outputs of measurement instruments to variables such as Free Water Level and Liquid Pressure. Before starting the ATD installation, read the reference manuals for the various ATD devices, such as the Rosemount 2240S and the Rosemount 2230, to learn more about how to configure these devices.

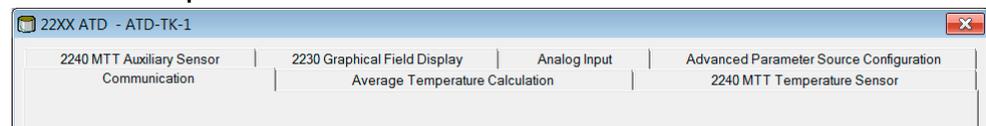
### 2.9.1 Opening the Properties window

#### Procedure

1. In the WinSetup Workspace window, open the **Devices** folder and select the ATD icon.



2. Click the right mouse button and select **Properties**, or from the **Service** menu select **Devices** → **Properties**.



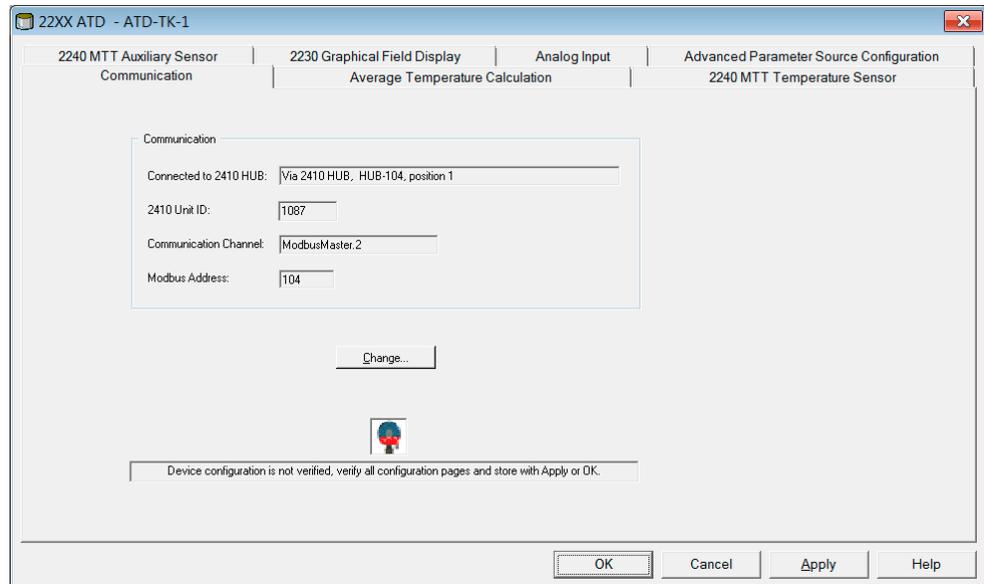
3. The **22XX ATD** window has a number of configuration tabs for the Rosemount 2240S and the Rosemount 2230.
4. Open the appropriate tabs to configure the ATD devices.
5. Finish the ATD configuration by clicking the **Apply** or **OK** button.

## 2.9.2 Communication parameter setup

The **Communication** tab lets you verify the device communication settings. A red icon means that the current ATD needs to be configured.

### Procedure

1. In the **22xx ATD** window select the **Communication** tab.



2. In the **Connected to HUB** field, verify that the ATD device is:

- connected to the correct Rosemount 2410 Tank Hub
- mapped to the correct position in the tank hub's tank database

For example, "position 1" means that the ATD device is mapped to tank database position 1 in the tank hub's database, "position 2" to tank database position 2 etc. You can check the tank database of the current tank hub by opening the **2410 HUB Properties/Tank Database** window.

3. The **Change** button lets you change the Modbus® address of the current ATD device in case it is connected to a multiple tank version of the tank hub. Note that the Modbus address can only be changed for ATD devices in tank database position 2 and higher. An ATD device mapped to position 1 in the tank hub's database uses the same Modbus address as the tank hub itself.
4. Click the **Apply** button to store the configuration, or click the **OK** button to store the configuration and close the window.

### Related information

[Installing a Rosemount 2410 Tank Hub](#)

## 2.9.3 Temperature sensor configuration

The **2240S MTT Temperature Sensor** tab lets you configure a sensor connected to the Rosemount™ 2240S Multi-input Temperature Transmitter. The 2240S MTT Temperature Sensor tab input fields are disabled in case no Rosemount 2240S is connected to the Tankbus.

### Procedure

1. In the **22xx ATD** window, select the **2240S MTT Temperature Sensor** tab.

The screenshot shows the configuration window for a Rosemount 2240S MTT Temperature Sensor. The window title is "22XX ATD - ATD-TK-1". It has four tabs: "2240 MTT Auxiliary Sensor Communication", "2230 Graphical Field Display Average Temperature Calculation", "Analog Input", and "2240 MTT Temperature Sensor". The "2240 MTT Temperature Sensor" tab is selected. The window contains several sections: "Device Information" with fields for Unit ID (133), Application SW Version (1.A5), Boot SW Version (1.A5), and Status (OK); a checked "Use Auto Sensor Configuration" checkbox; "Conversion Method" with a dropdown set to "PT100" and three buttons for user-defined configurations; "Used Sensor Configuration" with fields for Method (PT100), Connection (3 wires spot with common return), Supported Elements (16), Min Temperature (-200.0 °C), and Max Temperature (250.0 °C); "Connection" with a dropdown set to "3 wires spot with common return"; and "Temperature Range" with fields for Min Value (-200.0 °C) and Max Value (250.0 °C). At the bottom are buttons for "OK", "Cancel", "Apply", and "Help".

2. The Rosemount 2240S is equipped with a DIP switch for automatic configuration of temperature element and wiring. By selecting the **Use Auto Sensor Configuration** check box, the transmitter is automatically configured according to the DIP switch settings.

In case a temperature element type is used that does not match the Auto Sensor Configuration, the Rosemount 2240S transmitter can be manually configured.

### Related information

[Temperature sensor manual configuration](#)  
[Rosemount 2240S Reference Manual](#)

## Temperature sensor manual configuration

### Procedure

1. Ensure that the **Use Auto Sensor Configuration** check box is unchecked.
2. In the **Method** input field, select the desired user defined conversion method.

### Note

For spot temperature elements, use the Pt100 sensor option to ensure correct average temperature calculation.

3. In the **Connection** drop-down list, choose the type of sensor connection that is used for the spot sensors.
4. Specify the measurement range of the current temperature element in the **Min Value** and **Max Value** input fields.

The screenshot shows a configuration window for a temperature sensor. At the top left, there is a checkbox labeled "Use Auto Sensor Configuration" which is unchecked. Below this, there are two main sections. The left section is titled "Conversion Method" and contains a "Method:" dropdown menu set to "PT100". Below the dropdown are three buttons: "Configure User Defined Linearization Table", "Configure User Defined Formula", and "Configure User Defined Individual Formula". The right section is titled "Used Sensor Configuration" and contains four input fields: "Method:" (PT100), "Connection:" (3 wires spot with common return), "Supported Elements:" (16), "Min Temperature:" (-200.0 °C), and "Max Temperature:" (250.0 °C). Below these sections, there is a "Connection:" dropdown menu with a list of options: "3 wires spot with common return", "3 wires independent spot", "4 wires independent spot", and "3 wires spot with common return" (which is highlighted in blue). Below the connection dropdown are "Temperature:" (Reserved), "Min Value:" (200.0 °C), and "Max Value:" (250.0 °C) input fields.

5. For user defined temperature conversion, such as User defined table, User defined formula, and User defined individual formula, click the configuration button that corresponds to the selected conversion method and configure the temperature sensors.
6. Click the **Apply** button to store the configuration, or click the **OK** button to store the configuration and close the window.

### Related information

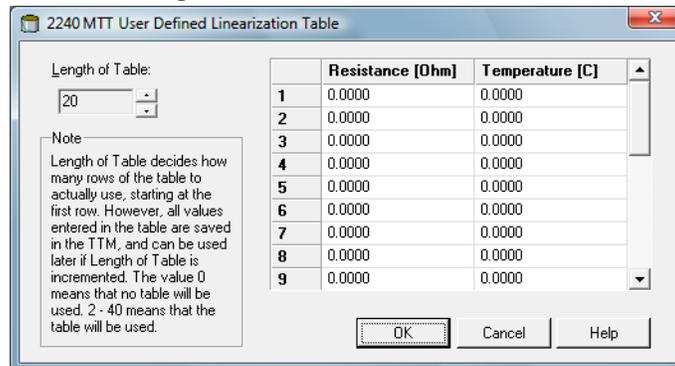
[Rosemount 2240S Reference Manual](#)  
[User defined linearization table](#)  
[User defined formula](#)  
[User defined individual formula](#)

## User defined linearization table

When using a resistance temperature sensor, the electrical resistance values can be converted to temperature values by using a table of resistance and temperature values.

### Procedure

1. In the *2240S MTT Temperature Sensor* window, select conversion method **User Defined Linearization Table**.
2. Click the **Configure User Defined Linearization Table** button:



3. Specify the number of conversion points in the Length of Table input field.
4. Type resistance and temperatures values into the Resistance [Ohm] and Temperature [C] columns.
5. Click the OK button to store the linearization table in the temperature transmitter's database registers.

## User defined formula

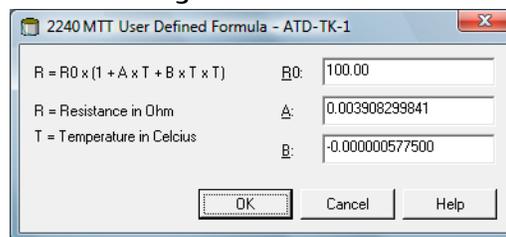
For a resistance temperature sensor, the relation between temperature and resistance can be specified by a mathematical formula:

$$R=R_0*(1+A*T+B*T^2),$$

where **R** is the resistance at temperature **T**, **R<sub>0</sub>** is the electrical resistance at zero degrees Celsius, and **A** and **B** are constants.

### Procedure

1. In the *2240S MTT Temperature Sensor* window, choose conversion method **User Defined Formula**.
2. Click the **Configure User Defined Formula** button:



3. Enter the parameters **R<sub>0</sub>**, **A** and **B** in the corresponding input fields.
4. Click the **OK** button to store the **R<sub>0</sub>**, **A** and **B** parameters in the temperature transmitter's database registers.

## User defined individual formula

When using User Defined Individual Formula, a mathematical formula is used for each individual temperature element:

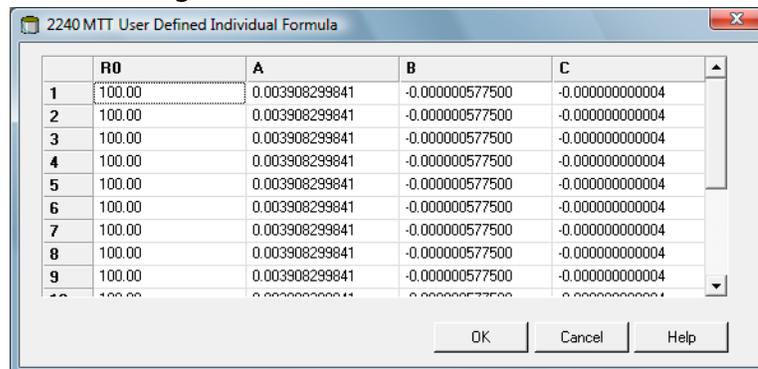
$$R=R_0*(1+A_N*T+B_N*T^2+C_N*T^3),$$

where

- R is the resistance at temperature T
- R<sub>0</sub> is the resistance at zero degrees Celsius
- A, B, and C are individual constants for each element
- N is the number of temperature sensors

### Procedure

1. In the *2240S MTT Temperature Sensor* window, choose conversion method **User Defined Individual Formula**.
2. Click the **Configure User Defined Individual Formula** button:



3. Enter parameters R<sub>0</sub>, A, B, and C for each individual temperature element.
4. Click the **OK** button to store the formula in the temperature transmitter's database registers.

## 2.9.4 Average Temperature calculation

This section gives a brief description of how to configure average temperature calculations for a temperature sensor connected to the Rosemount 2240S Multi-input Temperature Transmitter.

### Procedure

1. In the **22xx ATD** window, select the **Average Temperature Calculation** tab.

	Position	Exclude	Weight Factor	Temp
No of Elements: 3				
Sensor Type: Spot				
Insert Distance: 0.000 m				
16	-1000.000 m	<input type="checkbox"/>	1.0	-300.0 °C
15	-1000.000 m	<input type="checkbox"/>	1.0	-300.0 °C
14	-1000.000 m	<input type="checkbox"/>	1.0	-300.0 °C
13	-1000.000 m	<input type="checkbox"/>	1.0	-300.0 °C
12	-1000.000 m	<input type="checkbox"/>	1.0	-300.0 °C
11	-1000.000 m	<input type="checkbox"/>	1.0	-300.0 °C
10	-1000.000 m	<input type="checkbox"/>	1.0	-300.0 °C
9	-1000.000 m	<input type="checkbox"/>	1.0	-300.0 °C
8	-1000.000 m	<input type="checkbox"/>	1.0	-300.0 °C
7	-1000.000 m	<input type="checkbox"/>	1.0	-300.0 °C
6	-1000.000 m	<input type="checkbox"/>	1.0	-300.0 °C
5	-1000.000 m	<input type="checkbox"/>	1.0	-300.0 °C
4	-1000.000 m	<input type="checkbox"/>	1.0	-300.0 °C
3	12.000 m	<input type="checkbox"/>	1.0	-22.1 °C
2	1.500 m	<input type="checkbox"/>	1.0	-6.5 °C
1	1.000 m	<input type="checkbox"/>	1.0	38.7 °C

Note 1: The insert distance is the distance that the element must be below the surface to be included in the average calculation.

Note 2: The position distance is the distance from the datum plate to the temperature element. If the datum plate is located below position 1 then all distances shall be positive.

Vapor Temperature: -22.1 °C  
Liquid Temperature: 16.1 °C

2. **No of Elements:** select the number of temperature elements used. Verify that the input fields for element positions are enabled.
3. **Sensor Type:** select the type of sensor that is used; Spot or Average.
4. **Insert Distance:** specify the minimum distance between a temperature sensor and the product surface for temperature sensors included in average temperature calculation.
5. **Position:** enter the distance from **Zero Level** to the spot temperature element. If average temperature elements are used, enter the position where the average element ends.
6. You may exclude a temperature element from average temperature calculation by selecting the **Exclude** check box in the column next to the **Position** field. This option may be useful in case you would like to exclude a malfunctioning temperature element.
7. Click the **Apply** button to store the configuration, or click the **OK** button to store the configuration and close the window.

### Related information

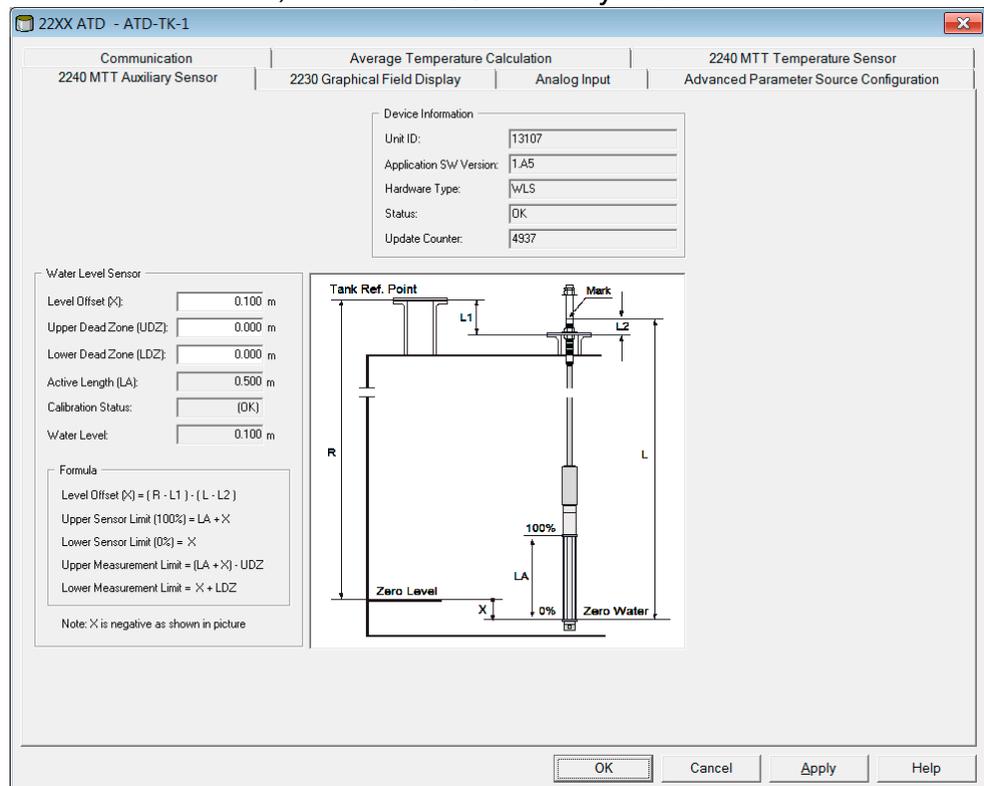
[Rosemount 2240S Reference Manual](#)

## 2.9.5 Auxiliary sensor configuration

The **2240S MTT Auxiliary Sensor** tab lets you configure a water level sensor connected to a Rosemount 2240S Multi-input Temperature Transmitter.

### Procedure

1. In the **22xx ATD** window, select the **2240 MTT Auxiliary Sensor** tab.



2. Calculate the **Level Offset (X)** according to the formula  $X=(R-L1)-(L-L2)$ .
3. Enter the resulting level offset value in the **Level Offset (X)** input field.
4. Enter the **Upper Dead Zone (UDZ)** and the **Lower Dead Zone (LDZ)** if needed.
5. Click the **Apply** button to store the configuration, or click the **OK** button to store the configuration and close the window.

### Related information

[Rosemount 2240S Reference Manual](#)

## 2.9.6 Advanced parameter source configuration

The **Advanced Parameter Source Configuration** tab lets you map the output of various measurement instruments (source devices) to tank measurement variables such as Liquid Pressure and Vapor Pressure. This makes the measurement variables available for configuration in the **Tank Configuration** window

For tank measurement variables such as Level, Vapor Temperature, and Free Water Level, source devices are automatically mapped and do not need to be configured in the Advanced Parameter Source Configuration tab.

The Rosemount 2410 Tank Hub supports 60 source parameter mappings. Six mappings are reserved for each one of the ten tank database positions.

### Note

A warning message will appear in case a certain parameter/source mapping is already used for another tank.

For a source device to be available in the **Advanced Parameter Source Configuration** tab, it must be mapped to the current tank in the tank hub's database.

### Procedure

1. In the **22xxATD** window select the **Advanced Parameter Source Configuration** tab.

2. In the **Parameter Mapping** column select a tank measurement parameter.
3. In the **Source Device Type/ID/No** column, choose a measurement device such as a pressure transmitter or any other type of instrument.

The default setting lists only devices mapped to the current tank position in the tank hub's database. By using this option you will avoid mapping to a device on the wrong tank by mistake. By selecting the appropriate radio button you can choose to show all available devices, or only the devices mapped to tank position 1 in the 2410 tank database.

4. In the **Source Parameter** column, select the transmitter variable to be mapped to the tank measurement variable in the first column.

5. In case **User Defined** is selected, you may type a description in the Description of User Def parameter box.
6. Click the **Apply** button to store the configuration, or click the **OK** button to store the configuration and close the window.

**Related information**

[Installing a Rosemount 2410 Tank Hub](#)

[Installing a tank](#)

## Using a Rosemount 644 Temperature Transmitter

The Rosemount Tank Gauging system automatically handles source parameter mapping for Rosemount 2240S transmitters to provide correct input for calculation of tank measurement variables such as Vapor Temperature and Average Temperature.

For Rosemount 644 temperature transmitters, tank variables have to be mapped manually to the appropriate source devices. The output from each Rosemount 644 transmitter on the tank is mapped to a temperature tank variable as shown in the following example with three Rosemount 644 transmitters on the tank.

### Procedure

1. In the **22xx ATD** window select the **Advanced Parameter Source Configuration** tab.

Parameter Mapping	Unit	Source Device Type / ID / No	Source Parameter
<input checked="" type="checkbox"/> Vapor Pressure	barG	3051 PT / 268441203 / (No 3)	Pressure 1
<input checked="" type="checkbox"/> Temperature 1	C	644 / 45 / (No 3)	Temperature 1
<input checked="" type="checkbox"/> Temperature 2	C	644 / 54 / (No 4)	Temperature 1
<input checked="" type="checkbox"/> Temperature 3	C	644 / 56 / (No 5)	Temperature 1
<input type="checkbox"/> Level	m	Not Configured	Level
<input type="checkbox"/> Level	m	Not Configured	Level

Show only devices configured for tank position: 1  
 Show all devices.

2. In the **Parameter Mapping** list select **Temperature 1** for the first 644 temperature transmitter. This temperature parameter is mapped to the temperature element at position 1 in the tank.

For the second and third 644 transmitters, select **Temperature 2** and **Temperature 3** in the **Parameter Mapping** list. These parameters are mapped to the temperature elements at position 2 and 3, respectively.

3. In the **Source Device Type** field, for each temperature parameter (Temperature 1, 2, 3) select the actual **644 transmitter** to be used as source device.
4. In the **Source Parameter** list, select **Temperature 1**. This is the source parameter designation of the temperature output from a Rosemount 644 temperature transmitter.

### Note

The **Vapor Temperature** and **Average Temperature** variables are not mapped to the source devices.

5. Click the **Apply** button to store the configuration, or click the **OK** button to store the configuration and close the window.

## 2.9.7 Rosemount 2230 Graphical Field Display

This section gives a brief description of how to configure a Rosemount 2230 Graphical Field Display.

All fields in the **2230 Graphical Field Display** tab are disabled if no graphical field display is connected to the Tankbus, or if the display is not mapped to the current tank database position of the Rosemount 2410 Tank Hub. The **Configure Tank Display 2** and **Configure Tank Display 3** buttons are disabled when only one Rosemount 2230 is mapped to the current tank database position.

### Procedure

1. In the **22xx ATD** window select the **2230 Graphical Field Display** tab.

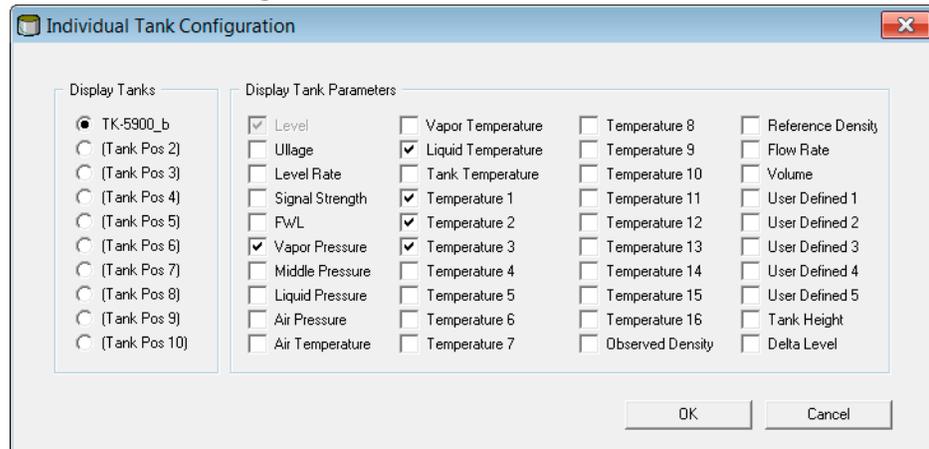
2. From the drop-down lists in the **Units for Display** pane, select the desired measurement units to be displayed for the various tank measurement variables.

### Note

The Rosemount 2230 converts the unit specified in the **Server Preferences** window.

3. In the **Common Tank Configuration** pane, select tanks and tank parameters to be presented by the Rosemount 2230 display by selecting the appropriate check boxes.

4. In the **Display Toggle Time** input field, enter toggle time for the displayed tank parameters. The selected parameters will be displayed for one tank at a time starting with Tank 1.
5. If a second graphical field display is used, click the **Configure Tank Display No 2** button and repeat the configuration procedure.
6. If a third graphical field display is used, click the **Configure Tank Display No 3** button and repeat the configuration procedure.
7. The Rosemount 2230 can be configured to show different set of parameters for each tank on the Tank Bus. In the 2230 Graphical Field Display tab click the **Individual Tank Configuration** button:



8. Select the desired tank and parameters to show on the Rosemount 2230 display. Repeat this procedure for each tank.
9. Click the **OK** button to store the configuration and return to the 22xx ATD window.
10. Click the **Apply** button to store the configuration, or click the **OK** button to store the configuration and close the window.

### Related information

[Measurement units](#)

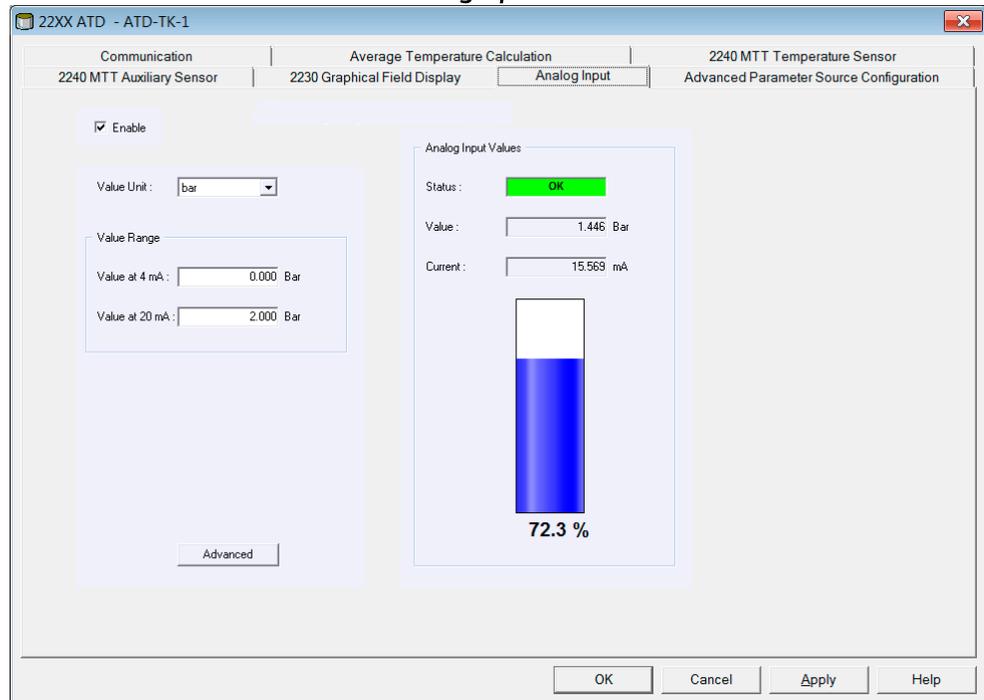
[Rosemount 2230 Reference Manual](#)

## 2.9.8 Analog input

The Rosemount™ 2410 Tank Hub can be equipped with an analog input which lets you connect instruments for 4- 20 mA/HART communication.

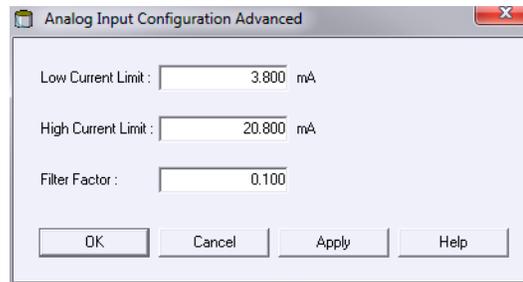
### Procedure

1. In the **22xx ATD** window select the **Analog Input** tab.



2. Ensure that the **Enable** check box is selected.
3. In the **Value Unit** field select a suitable unit to match the input source.
4. In the **Value Range** pane, enter the parameter values that correspond to the analog input values 4 mA and 20 mA, respectively. You may specify any value as long as the 20 mA value is higher the 4mA value. For measurement values outside the range values, the analog input enters alarm mode.

5. Use the **Advanced** button in case you would like to configure **Filter Factor** and **Current Limits**.



- Filter Factor** Lets you suppress spurious fluctuations in the analog input signal. A value between 0 and 1 can be used. The default value is 0.1. A higher value means less filtering.
- Filtering means that the presented Analog Input value is calculated as the average value of the <n> latest measurements. A filter factor equal to 0.1 is the average of the 10 latest measurements, a filter factor equal to 0.5 is the average of the 2 latest measurements and so on.
- Current Limits** Define the lower and upper limits of the input currents. An error will be indicated outside this range. The current limits should correspond to the error limits of connected instruments. If for example an instrument sets the output current in alarm mode to 3.8 mA, you should set the lower error limit to 3.8 or higher.

6. In the **Analog Input Values** pane, verify that Status is OK and that the expected measurement results appear in the **Value** and **Current** fields.

### Related information

[Rosemount 2410 Reference Manual](#)

## Analog input tank parameter setup

This is a description of the steps to perform for a complete configuration of the Rosemount 2410 Tank Hub's analog input.

### Procedure

1. Configure the tank hub's tank database; associate the Analog Input with the tank on which the device is installed.
2. In the *Rosemount 2410 Properties* window, select the Device Tags tab and install the analog input device in TankMaster. Verify that it is installed as an ATD device.
3. In the *ATD Properties/Analog Input* window, configure value range and units.
4. In the *ATD Properties/Advanced Parameter Source Configuration* window, ensure that the analog input device is mapped to the desired tank parameter, source device, and source parameter.
5. Install a tank in TankMaster WinSetup and make sure that the ATD device that includes the analog input device is mapped as source device for the tank.

### Postrequisites

See the Rosemount 2410 [Reference Manual](#) for more information on how to set up the analog input.

## 2.10 Installing a Rosemount 5408

The Rosemount 5408 Radar Level Transmitter is most conveniently installed in TankMaster WinSetup, by utilizing the integrated option included as part of the Rosemount 2410 Tank Hub installation procedure. Once installed, the Rosemount 5408 is configured via the **5408 RLT** window which includes tabs for basic and advanced configuration.

When connecting a Rosemount 5408 to a Rosemount 2410 Tank Hub in an existing Rosemount Tank Gauging system, the Rosemount 5408 has to be mapped to the appropriate tank in the Rosemount 2410 tank database. Configuration is performed via the **5408 RLT** window.

A Rosemount 5408 can also be installed and configured by using the WinSetup installation Wizard. This method should only be used when, for example, the transmitter is connected to the Tankbus at a later stage and not available when installing the Rosemount 2410 Tank Hub.

The following configuration steps are included in the Rosemount 5408 radar level transmitter basic configuration:

- communication parameters
- antenna type
- tank geometry

Due to properties of the product, tank shape, or other circumstances, further configuration may be needed in addition to the basic configuration. Disturbing objects and turbulent conditions in the tank may also require advanced measures to be taken. The TankMaster WinSetup configuration tool includes advanced options for the 5408 such as:

- tank environmental conditions
- tank shape

### Related information

[Configuration via Properties window](#)

[Install a Rosemount 5408 using the installation wizard](#)

[Rosemount 5408 Reference Manual FF](#)

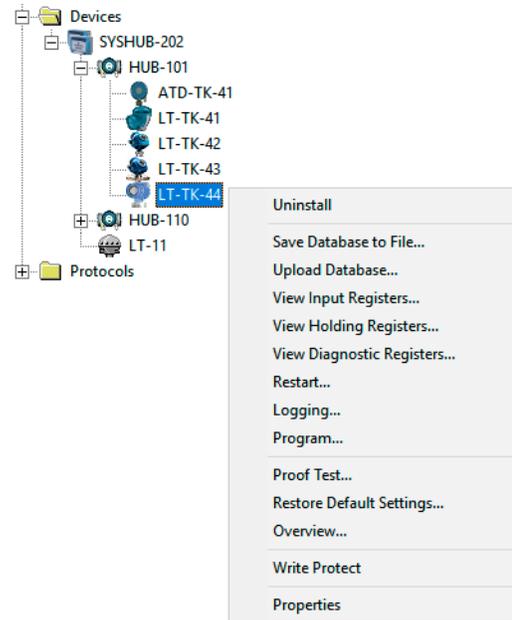
[Rosemount 5408 Reference Manual HART](#)

## 2.10.1 Configuration via Properties window

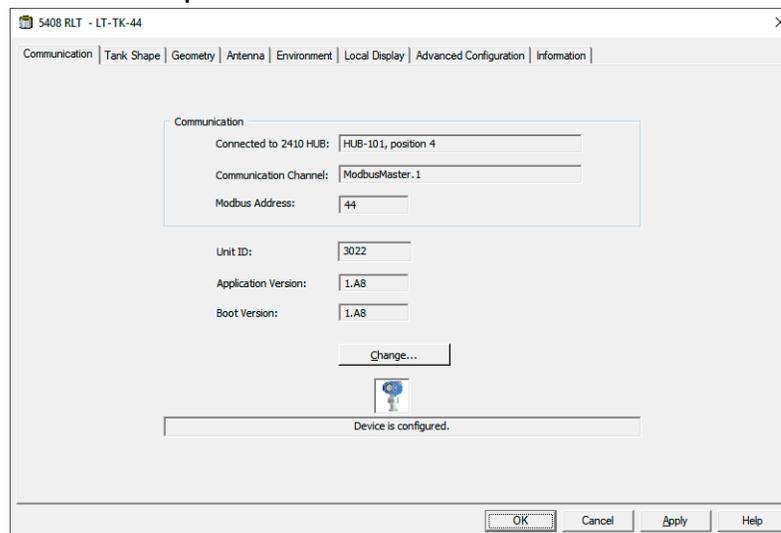
This section describes the basic configuration procedure for a Rosemount 5408 Radar Level Transmitter by using the **5408 RLT** window.

### Procedure

1. In the WinSetup Workspace window, open the **Devices** folder and select the Rosemount 5408 transmitter icon.



2. Click the right mouse button and select **Properties**, or from the **Service** menu select **Devices** → **Properties**.



3. Select the **Communication** tab. Note that a red gauge icon means that the device needs to be configured.

4. Verify the tank position.

The **Connected to 2410 HUB** field shows the name of the Rosemount 2410 Tank Hub and the tank position that the device is mapped to in the tank hub's database. The tank position indicates which tank the device is associated with.

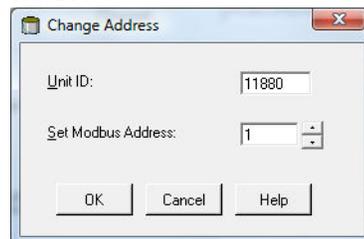
In most cases, the Rosemount 2410 single tank version is used for level gauges. In those cases, only one tank position will be used in the tank hub's database.

In case the multiple tank version of the Rosemount 2410 is used to connect several tanks, the level gauge can be mapped to another tank through the 2410 Tank Hub **Properties/Tank Database** window:

- a) in the WinSetup workspace click the right mouse button on the Rosemount 2410 icon.
- b) select **Properties** and open the **Tank Database** tab.
- c) select the desired tank position.

5. Verify that the Modbus® address is correct. To change the address:

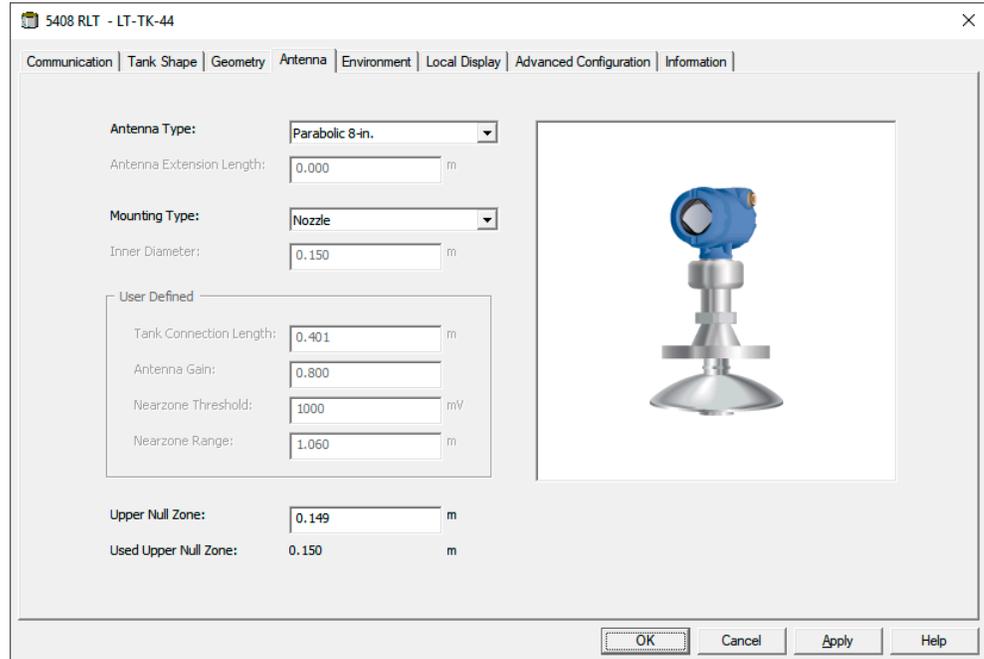
- a) Click the **Change** button to open the **Communication** window.
- b) Click the **Change Address on Device** button to open the **Change Address** window:



- c) Enter the **Unit ID**. When changing the device address, the Unit Id is used as a unique identifier of the device. The Unit Id can be found on the main label.
- d) Set the desired **Modbus address**.
- e) Click **OK** to confirm the settings and close the **Change Address** window.
- f) Click **OK** to close the **Communication** window.

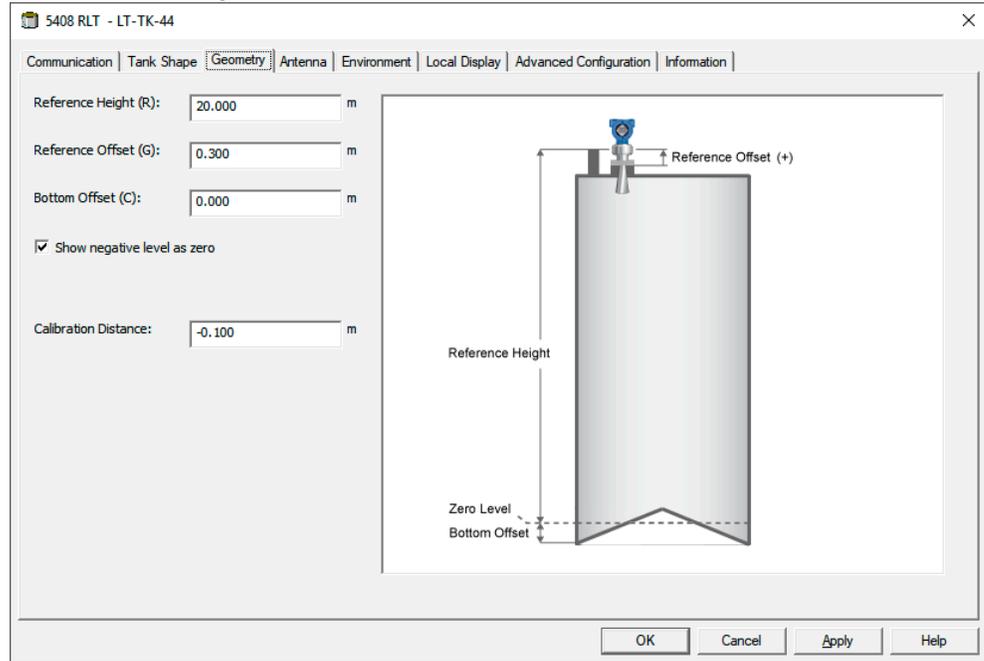
6. In the **5408 RLT Communication** window click the **Apply** button to store the address.

7. Select the **Antenna** tab:



8. Select **Antenna Type** and mounting type if applicable. You may choose between **predefined** antenna types or **user defined** for non-standard antennas. For predefined antennas a number of transmitter parameters are automatically specified in order to optimize measurement performance. For user defined antenna the database settings must be entered manually.  
  
Enter **Antenna Extension Length** in case the antenna is equipped with an extension.
9. In case there are disturbances close to the nozzle you may adjust the **Upper Null Zone**. By increasing the Upper Null Zone, the measurement range is reduced in the upper part of the tank.
10. For still pipe applications enter the **Inner Diameter**.
11. Click the **Apply** button to save the configuration.

12. Select the **Geometry** tab:



13. Enter the tank geometry parameters.

- |                                  |  |
|----------------------------------|--|
| <b>Tank Reference Height (R)</b> | Distance from the <b>Tank Reference Point</b> to the <b>Zero Level</b> .   |
| <b>Reference Offset (G)</b>      | Distance between the Tank Reference Point and the Gauge Reference Point, which is located at the surface of the nozzle flange on which the gauge is mounted.   |
| <b>Bottom Offset (C)</b>         | Distance between the <b>Zero Level</b> (Dipping Datum Point) and the minimum level for the product surface (tank bottom). By specifying a C-distance, the measuring range can be extended to the bottom of the tank.<br><b>C&gt;0</b> : the transmitter presents negative level values when the product surface is below the <b>Zero Level</b> (Datum plate). You can use the <b>Show negative level values as zero</b> check box to present product levels below the Zero Level as equal to zero.<br><b>C=0</b> : measurements below the <b>Zero Level</b> will not be approved, i.e. the transmitter will report “invalid level” if the product level is below the <b>Zero Level</b> . |

14. Enter **Calibration Distance** if needed. This variable lets you adjust the tank height so that measured product levels correspond to hand dipped levels. Normally a minor adjustment is necessary when the transmitter is installed. For example, a minor deviation between the actual tank height and the value stored in the transmitter database may occur if tank dimensions according to drawings are not quite up to date with actual dimensions.

15. Optional: Select the **Show negative level as zero** check box in case you don't want the transmitter to show negative level values.
16. Click the **Apply** button to store the configuration, or click the **OK** button to store the configuration and close the window.

**Related information**

[Installing a Rosemount 5408](#)

[Advanced configuration](#)

[Tank Database setup](#)

[Rosemount 5408 Reference Manual FF](#)

[Rosemount 5408 Reference Manual HART](#)

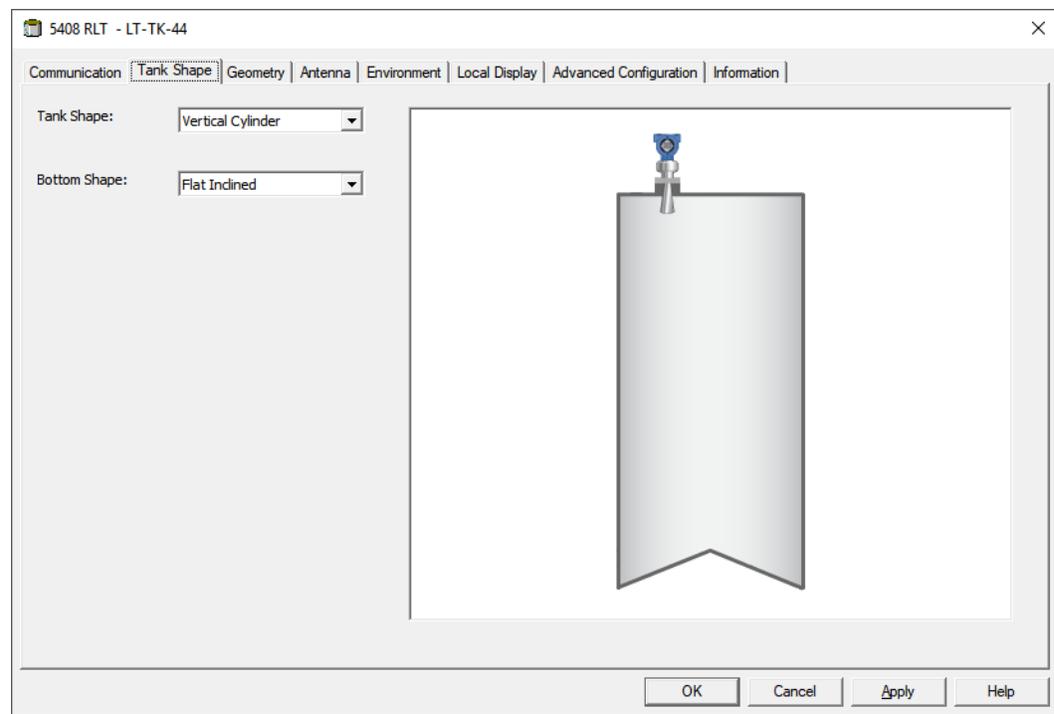
## 2.10.2 Advanced configuration

In addition to the basic configuration there are advanced configuration options available for the Rosemount 5408 transmitter. This section provides a brief description of a couple of these options. For more information on advanced configuration see the Rosemount 5408 Series [Reference Manual](#).

### Tank shape

The **Tank Shape** and **Bottom Shape** parameters optimize the Rosemount 5408 for various tank geometries and for measurements close to the tank bottom. These parameters are configured in the *Tank Shape* window:

**Figure 2-9: Tank Shape Window**

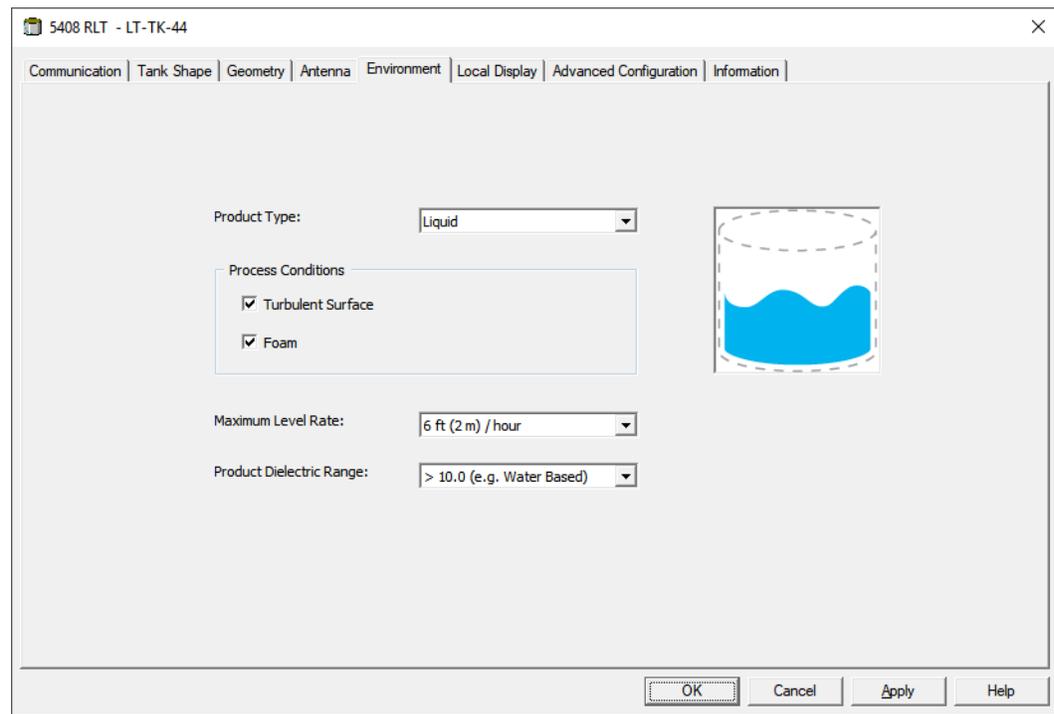


### Tank environment

Certain product conditions in the tank may require special configuration options to be used in order to optimize measurement performance of the 5408 Radar Level Transmitter. By configuring the environmental conditions in the tank, the transmitter can compensate for conditions such as rapid level change, weak echo signals, varying surface echo amplitudes, or other similar sources of inaccurate measurement.

The **Environment** window is used to optimize the transmitter for special tank conditions. For **Process Conditions** it is recommended to select as few options as possible.

**Figure 2-10: Environment Window**



### Related information

- [Installing a Rosemount 5408](#)
- [Rosemount 5408 Reference Manual FF](#)
- [Rosemount 5408 Reference Manual HART](#)

## 2.10.3 Install a Rosemount 5408 using the installation wizard

The installation wizard in TankMaster WinSetup is a tool that may be used to install and configure various devices in a Rosemount Tank Gauging system.

### Prerequisites

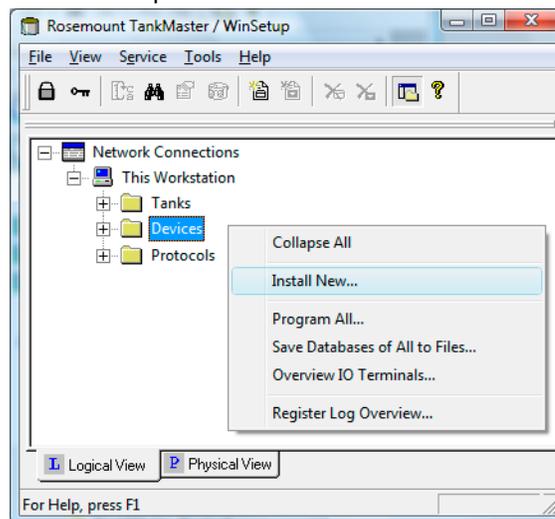
Ensure that the tank databases of the Rosemount 2460 System Hub and the Rosemount 2410 Tank Hub are properly configured and include the new device.

Ensure that the correct Modbus® address is used.

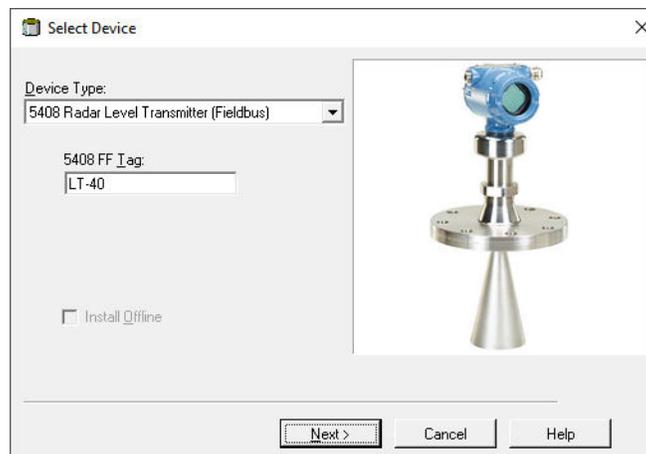
Field devices are typically installed as part of the installation procedure for a Rosemount 2410 Tank Hub. However, the installation wizard lets you install devices in TankMaster separately from the tank hub installation.

### Procedure

1. In the Workspace window select the **Devices** folder.



2. Click the right mouse button and select **Install New**, or from the **Service** menu select **Devices** → **Install New**.



3. Select Device Type **5408 Radar Level Transmitter** from the drop-down list.
4. Enter the desired tag for identifying the device.
5. Click the **Next** button to open the **5408 RLT Communication** window:

5408 RLT Communication - LT-40

Communication

2410 HUB Tag: HUB-110

Position in 2410 HUB:

Communication Channel: ModbusMaster.1

Modbus Address: 1 Unit ID:

Verify Communication

< Back Next > Cancel Help

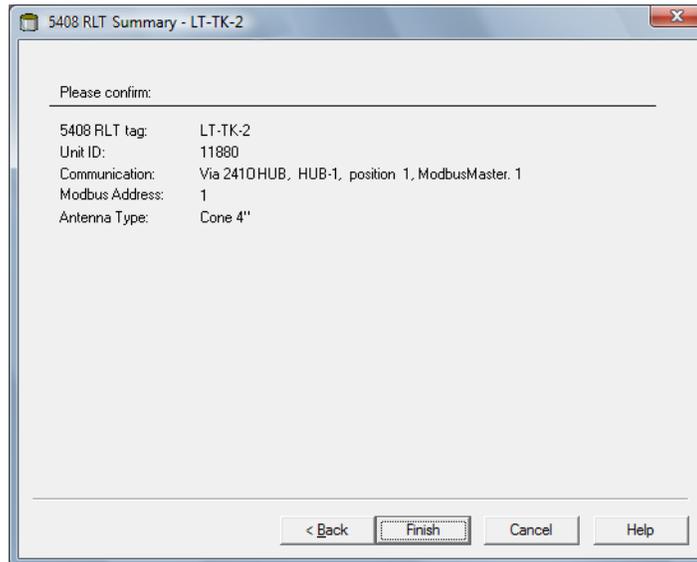
6. In the **2410 HUB Tag** drop-down list, select the tank hub that the Rosemount 5408 Radar Level Transmitter is connected to. Normally, there is one tank hub for each tank.
7. Enter the **Modbus address**. This address must be available in the tank databases of the Rosemount 2460 System Hub and the Rosemount 2410 Tank Hub.
8. Click the **Verify Communication** button to verify that the TankMaster PC communicates with the device. The Unit ID will appear when contact is established.
9. Check the **Position in 2410 HUB** field to verify that the device is mapped to the correct tank position in the Rosemount 2410 tank database. The tank position indicates which tank the device is associated with. Normally, the single tank version of the Rosemount 2410 Tank Hub is used for level gauges. In those cases the **Position in 2410 HUB** field will be equal to 1 since there is only one tank position that is used in the tank hub's database.

In case the multiple tank version of the Rosemount 2410 Tank Hub is used for several tanks, the level gauge can be mapped to the desired tank via the **2410 Tank Hub Properties/Tank Database** window:

- a) In the WinSetup workspace, click the right mouse button on the tank hub icon.
  - b) Select the **Properties** option.
  - c) Select the **Tank Database** tab and map the device to the desired tank position.
10. Click the **Next** button to proceed with the Rosemount 5408 configuration.

For more information refer to the appropriate parts in chapter [Configuration via Properties window](#).

11. In the 5408 RLT **Summary** window, click the **Finish** button to verify the configuration and finish the installation wizard. In case some part of the configuration needs to be changed, click the **Back** button until the desired window appears.



12. Verify that the device communicates with the Rosemount 2410 Tank Hub. Use for example the tank hub's **Device Live List** function to see all devices connected to the tank hub. The live list is available by right clicking the tank hub's device icon.

### Postrequisites

Further configuration options are available in the **5408 RLT Properties** window.

### Related information

[Configuration via Properties window](#)

[Advanced configuration](#)

[Installing a Rosemount 5408](#)

[Tank Database setup](#)

[Rosemount 5408 Reference Manual FF](#)

[Rosemount 5408 Reference Manual HART](#)

## 2.11 Installing a Rosemount 5300

The Rosemount 5300 Radar Level Transmitter is most conveniently installed in TankMaster WinSetup, by utilizing the integrated option included as part of the Rosemount 2410 Tank Hub installation procedure. Once installed, the Rosemount 5300 is configured via the **5300 RLT** window which includes tabs for basic and advanced configuration.

When connecting a Rosemount 5300 to a Rosemount 2410 Tank Hub in an existing Rosemount Tank Gauging system, it has to be mapped to the appropriate tank in the Rosemount 2410 tank database. Configuration is performed via the **5300 RLT** window.

A Rosemount 5300 can also be installed and configured by using the WinSetup installation Wizard. This method should only be used when, for example, the transmitter is connected to the Tankbus at a later stage and not available when installing the Rosemount 2410 Tank Hub.

The following configuration steps are included in the Rosemount 5300 radar level transmitter basic configuration:

- communication parameters
- probe type
- tank geometry

Due to properties of the product, tank shape, or other circumstances, further configuration may be needed in addition to the basic configuration. Disturbing objects and turbulent conditions in the tank may also require advanced measures to be taken. The TankMaster WinSetup configuration tool includes advanced options for the 5300 such as:

- tank environmental conditions

### Related information

[Configuration via Properties window](#)

[Install a Rosemount 5300 using the installation wizard](#)

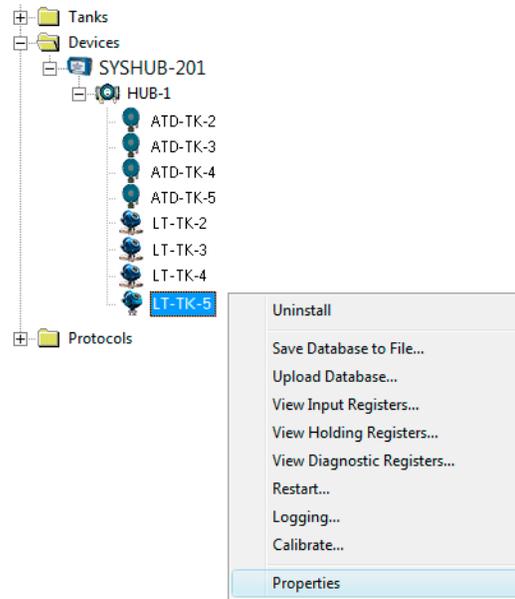
[Rosemount 5300 Reference Manual](#)

### 2.11.1 Configuration via Properties window

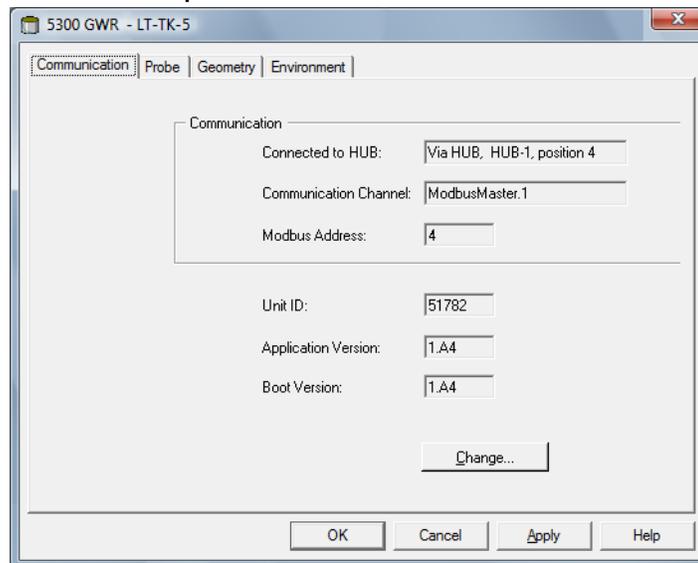
This section describes the basic configuration procedure for a Rosemount 5300 Guided Wave Radar by using the **5300 GWR** window.

#### Procedure

1. In the WinSetup Workspace window, open the **Devices** folder and select the Rosemount 5300 transmitter icon.



2. Click the right mouse button and select **Properties**, or from the **Service** menu select **Devices** → **Properties**.



3. Select the **Communication** tab. Note that a red gauge icon means that the device needs to be configured.

4. Verify the tank position.

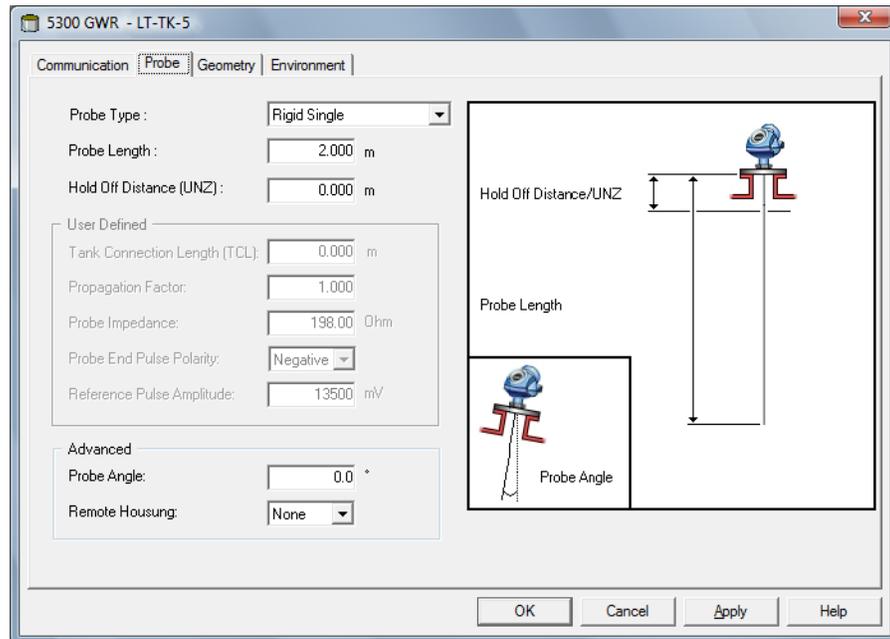
The **Connected to 2410 HUB** field shows the name of the Rosemount 2410 Tank Hub and the tank position that the device is mapped to in the tank hub's database. The tank position indicates which tank the device is associated with.

In most cases, the Rosemount 2410 single tank version is used for level gauges. In those cases, only one tank position will be used in the tank hub's database.

In case the multiple tank version of the Rosemount 2410 is used to connect several tanks, the level gauge can be mapped to another tank through the 2410 Tank Hub **Properties/Tank Database** window:

- a) in the WinSetup workspace click the right mouse button on the Rosemount 2410 icon.
  - b) select **Properties** and open the **Tank Database** tab.
  - c) select the desired tank position.
5. Verify that the Modbus<sup>®</sup> address is correct. To change the address:
- a) Click the **Change** button to open the **Communication** window.
  - b) Click the **Change Address on Device** button to open the **Change Address** window.
  - c) Enter the **Unit ID**. When changing the device address, the Unit Id is used as a unique identifier of the device. The Unit Id can be found on the main label.
  - d) Set the desired **Modbus address**.
  - e) Click **OK** to confirm the settings and close the **Change Address** window.
  - f) Click **OK** to close the **Communication** window.
6. In the **Communication** window click the **Apply** button to store the address.

7. Select the **Probe** tab:



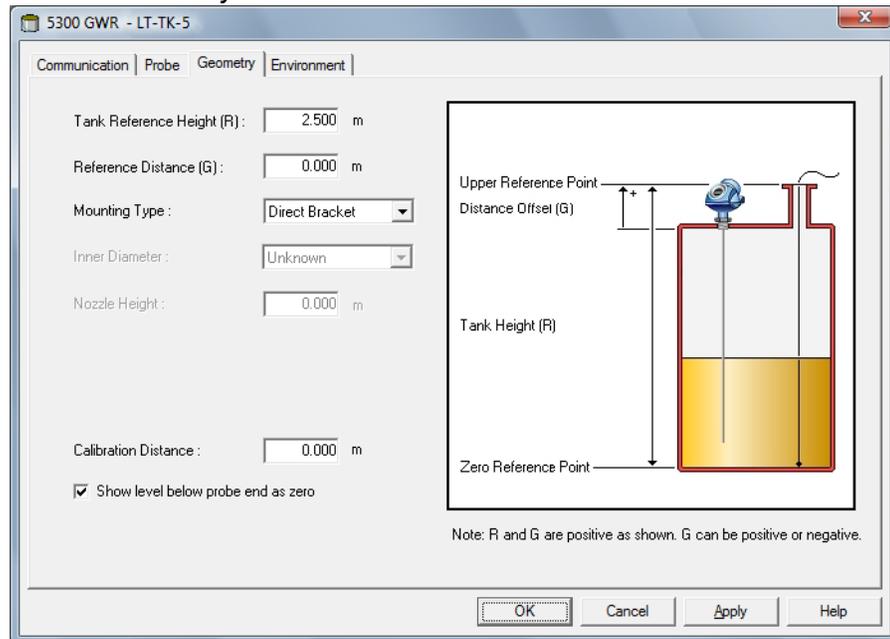
8. Select a **Probe Type** that corresponds to the actual probe that is used on the transmitter. You may select a predefined (standard) probe, or User Defined for non-standard probes. For predefined probe types, measurement performance is optimized by automatically specifying various device parameters. For a User Defined probe the database settings must be configured manually.

The following predefined (standard) **Probe Types** are available:

- Flexible Twin
- Flexible Single
- Coaxial

9. **Probe Length** is measured from the **Upper Reference Point** to the end of the probe. If a weight is used at the end of the probe it shall not be included.
10. Adjust the **Hold Off Distance (UNZ)** if there are disturbances in the upper part of the tank. Such problems may occur if there are disturbing objects, such as a narrow nozzle with rough walls, close to the probe. By increasing the Hold Off distance, the measuring range is reduced.
11. Click the **Apply** button to save the configuration.

12. Select the **Geometry** tab:



13. **Tank Reference Height (R)** is defined as the distance from the Upper Reference Point to the Zero Reference Point.
14. **Reference Distance (G)** is the distance between the Upper Reference Point and the flange.
15. Use the **Calibration Distance** parameter to adjust the tank height so that measured product levels match the hand dipped level values. Typically a minor adjustment is necessary when the device is installed. For example, a minor deviation between the actual tank height and the value stored in the device database may occur if tank dimensions according to drawings are not quite up to date with actual dimensions.
16. Select the appropriate **Mounting Type**; **Pipe Chamber**, **Direct Bracket**, or **Nozzle**. Select Unknown if none of these is appropriate. Depending on mounting type you may also need to specify other parameters such as **Inner Diameter** and **Nozzle Height**.
17. Optional: Select the **Show level below probe end as zero** check box if you want the transmitter to present zero instead of negative product levels.
18. Click the **Apply** button to store the configuration, or click the **OK** button to store the configuration and close the window.

**Related information**

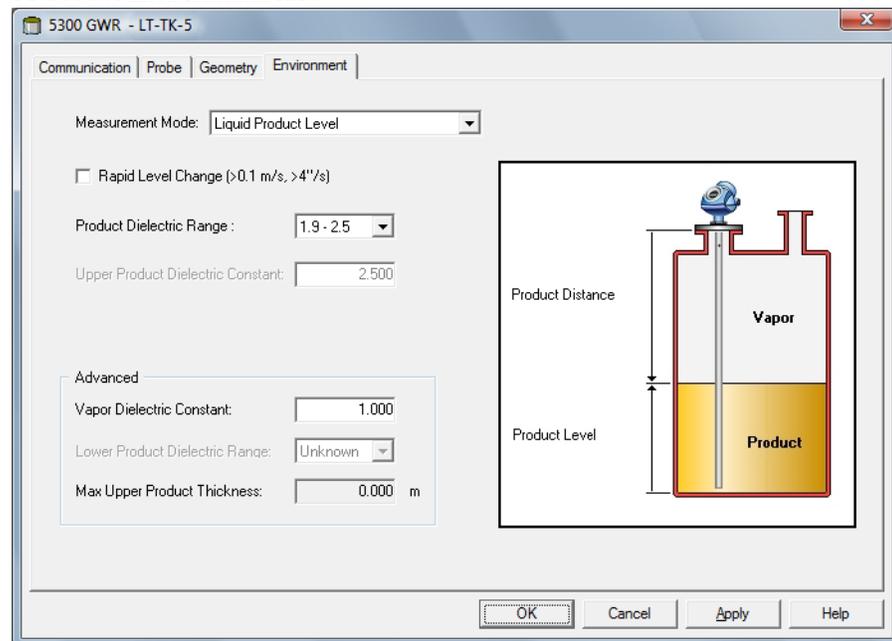
- [Installing a Rosemount 5300](#)
- [Advanced configuration](#)
- [Tank Database setup](#)
- [Rosemount 5300 Reference Manual](#)

## 2.11.2 Advanced configuration

In addition to the basic configuration there are advanced configuration options available for the Rosemount 5300 Guided Wave Radar. Environment conditions such as rapid level changes and dielectric constants of products as well as vapor dielectric constant can be configured. The **5300 GWR/Environment** window can be used to optimize the Rosemount 5300 for special tank conditions.

### Procedure

1. In the **WinSetup Workspace** window, open the **Devices** folder and select the Rosemount 5300 transmitter icon.
2. Click the right mouse button and select **Properties**, or from the **Service** menu select **Devices** → **Properties**.
3. Select the **Environment** tab.



4. Configure the appropriate options.

### Related information

[Installing a Rosemount 5300](#)  
[Rosemount 5300 Reference Manual](#)

## Measurement mode

The Rosemount 5300 is preconfigured according to the specified model and normally the measurement mode does not need to be changed.

## Rapid level change

Select the **Rapid Level Change** check box if the surface is moving quickly up or down at rates over 0.1 m/s (4 inch/s).

## Dielectric constant and dielectric range

The Product Dielectric Range is used for setting the appropriate signal amplitude thresholds in order to filter out noise from the measurement signal.

The Product Dielectric Range is used for setting the appropriate signal amplitude thresholds in order to filter out noise from the measurement signal.

In interface level measurements, dielectric constants can be configured for both the upper and the lower products. For the Product Dielectric Range choose option Unknown if the correct value range is not known or if the contents of the tank is changing on a regular basis.

For measurement mode **Liquid Product Level** enter the Product Dielectric Range. In some applications there is heavy vapor above the product surface having a significant influence on the level measurement. This may for example be the case of saturated water vapor under high pressure. In such cases the **Vapor Dielectric Constant** can be changed to compensate for this effect. Normally this value does not have to be changed since the effect on measurement performance is very small for most vapors. The default value is equal to 1 which corresponds to the dielectric constant of vacuum.

For measurement mode **Product Level and Interface Level** enter the **Upper Product Dielectric Constant**. If the dielectric constant of the lower product is significantly smaller than the dielectric constant of water you may need to adjust the **Lower Product Dielectric Range** as well.

## 2.11.3 Install a Rosemount 5300 using the installation wizard

The installation wizard in TankMaster WinSetup is a tool that may be used to install and configure various devices in a Rosemount Tank Gauging system.

### Prerequisites

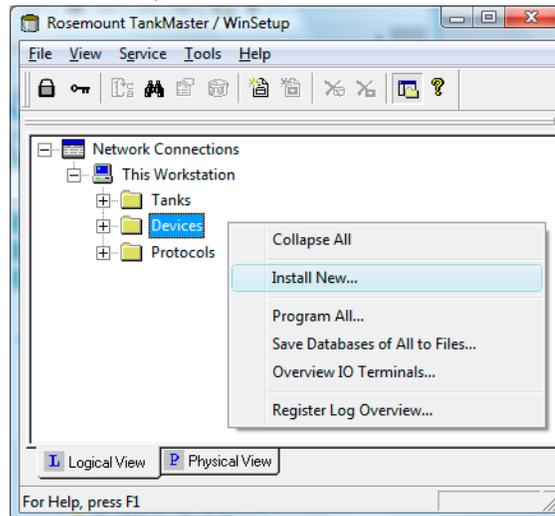
Ensure that the tank databases of the Rosemount 2460 System Hub and the Rosemount 2410 Tank Hub are properly configured and include the new device.

Ensure that the correct Modbus® address is used.

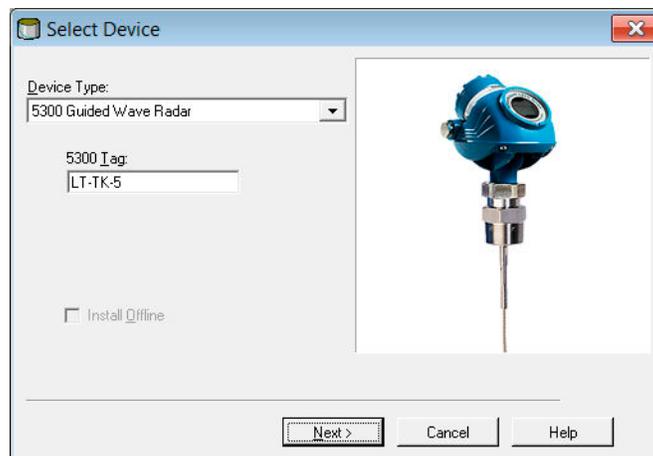
Field devices are typically installed as part of the installation procedure for a Rosemount 2410 Tank Hub. However, the installation wizard lets you install devices in TankMaster separately from the tank hub installation.

### Procedure

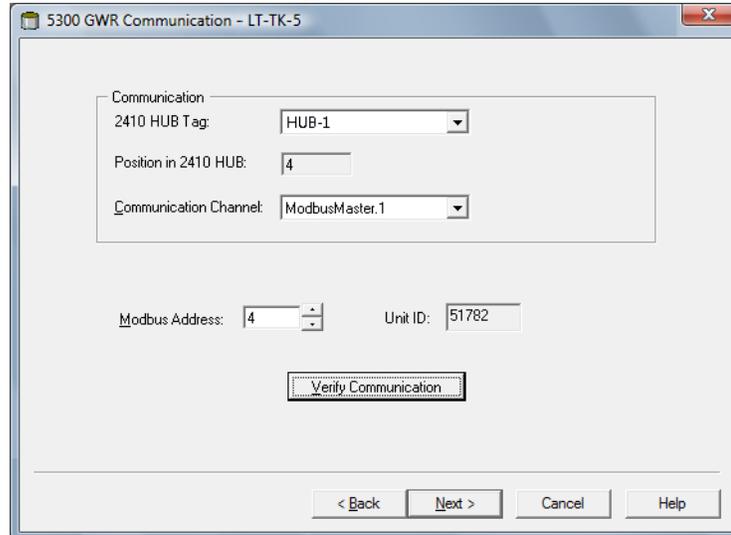
1. In the Workspace window select the **Devices** folder.



2. Click the right mouse button and select **Install New**, or from the **Service** menu select **Devices** → **Install New**.



3. Select Device Type **5300 Guided Wave Radar** from the drop-down list.
4. Enter the desired tag for identifying the device.
5. Click the **Next** button to open the **5300 GWR Communication** window:

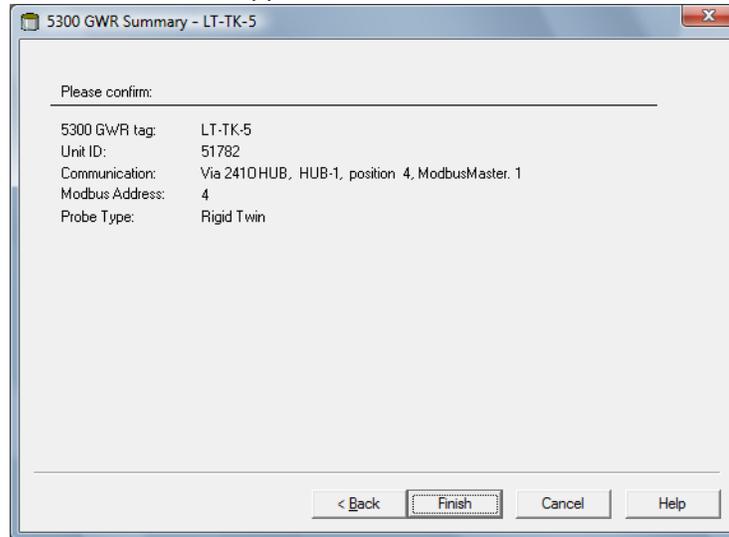


6. In the 2410 HUB Tag drop-down list, choose the tank hub that the Rosemount 5300 Radar Level Transmitter is connected to. Normally, there is one tank hub for each tank.
7. Enter the **Modbus address**. This address must be available in the tank databases of the Rosemount 2460 System Hub and the Rosemount 2410 Tank Hub.
8. Click the **Verify Communication** button to verify that the TankMaster PC communicates with the device. The Unit ID will appear when contact is established.
9. Check the **Position in 2410 HUB** field to verify that the device is mapped to the correct tank position in the Rosemount 2410 tank database. The tank position indicates which tank the device is associated with. Normally, the single tank version of the Rosemount 2410 Tank Hub is used for level gauges. In those cases the **Position in 2410 HUB** field will be equal to 1 since there is only one tank position that is used in the tank hub's database.

In case the multiple tank version of the Rosemount 2410 Tank Hub is used for several tanks, the level gauge can be mapped to the desired tank via the **2410 Tank Hub Properties/Tank Database** window:

- a) In the WinSetup workspace, click the right mouse button on the tank hub icon.
  - b) Select the **Properties** option.
  - c) Select the **Tank Database** tab and map the device to the desired tank position.
10. Click the **Next** button to proceed with the configuration.

11. Verify the configuration and click the **Finish** button to finish the installation wizard. In case part of the configuration needs to be changed, click the **Back** button until the desired window appears.



12. Verify that the device communicates with the Rosemount 2410 Tank Hub. Use for example the tank hub's **Device Live List** function to see all devices connected to the tank hub. The live list is available by right clicking the tank hub's device icon.

### Postrequisites

Further configuration options are available in the *5300 GWR Properties* window.

### Related information

- [Configuration via Properties window](#)
- [Advanced configuration](#)
- [Installing a Rosemount 5300](#)
- [Tank Database setup](#)
- [Rosemount 5300 Reference Manual](#)



## 3 Tank installation

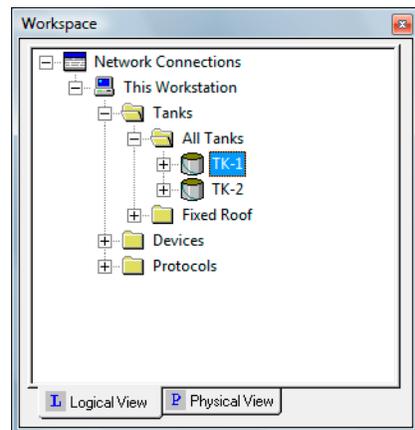
This section describes how to install and configure tanks in a Rosemount Tank Gauging system by using the Rosemount TankMaster WinSetup configuration program.

### 3.1 Installing a tank

#### 3.1.1 Overview

Basically the purpose of the tank installation procedure is to associate various devices to the right tanks. It also includes mapping variables such as Free Water Level and Vapor Pressure to specific instrument outputs.

**Figure 3-1: Tanks folder in WinSetup workspace**



Installing a new tank is a simple and straightforward procedure when using the tank installation wizard.

#### Note

Make sure that measurement units are specified before installing a new tank.

Specified measurement units only affect installation of new tanks. Changing measurement units has no effect on tanks which are already installed in WinSetup. This means that if you want to change measurement units for an installed tank, it has to be uninstalled first, and then installed again after changing the measurement units in the *Server Preferences/Units* window.

### Steps to install a tank

1. Specify tank type: Fixed Roof, Floating Roof, Sphere, Horizontal etc.
2. Select which devices to associate with the tank.
3. Configure the tank. For inventory calculations you will need to specify source signals for Free Water Level (FWL), Vapor Temperature, Vapor Pressure and Liquid Pressure.
4. Specify input for the different tank variables: automatic (measured by a field device) or manual values.

### Related information

[Measurement units](#)

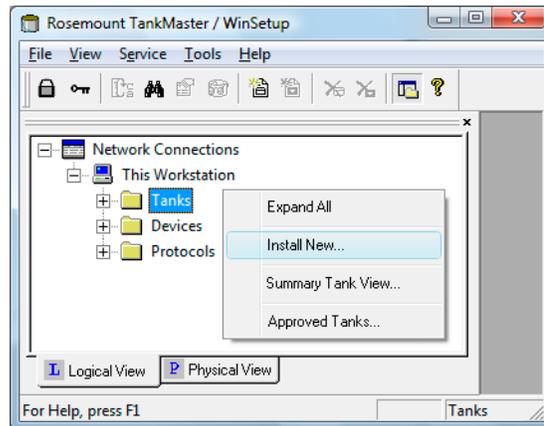
[Advanced parameter source configuration](#)

## 3.1.2 Installing a new tank

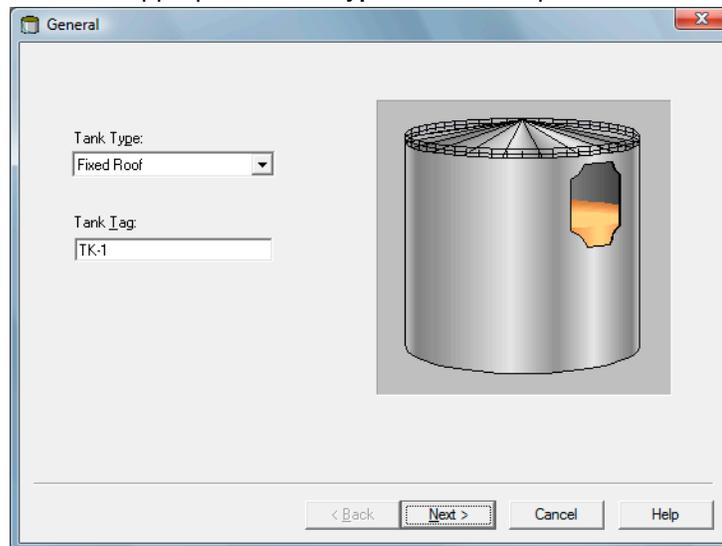
To install and configure a tank by using the WinSetup installation wizard:

### Procedure

1. Start the TankMaster WinSetup program.
2. In the Workspace window select the **Tanks** folder.
3. Click the right mouse button and select **Install New**, or from the **Service** menu select **Tanks** → **Install New**.



4. Select the appropriate **Tank Type** from the drop-down list.

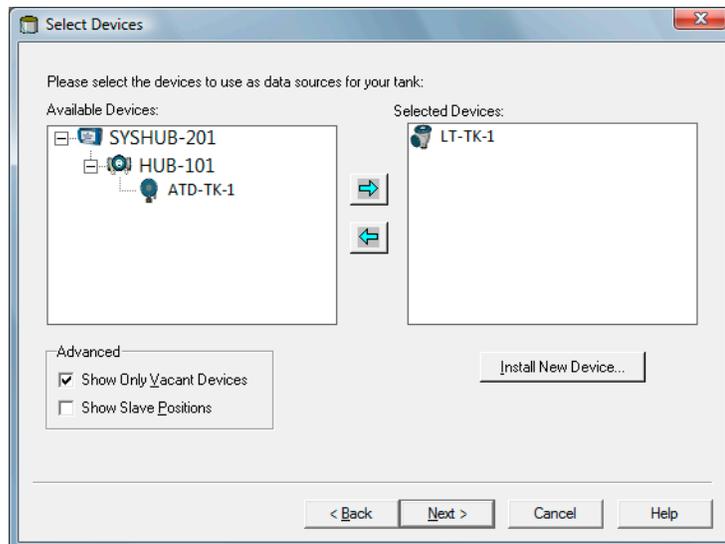


5. Enter the desired **Tank Tag** for identification of the tank. A prefix appears automatically if you have defined one in the **Tag Prefixes** window. It is recommended that the same name is used as in the tank database of the Rosemount 2410 Tank Hub.

6. Click **Next** to proceed with assigning field devices to the current tank:
  - a) From the **Available Devices** pane, select a device that is installed on the current tank and click the arrow button to move it to the **Selected Devices** pane.
  - b) Repeat this procedure for each device to be associated with the tank.

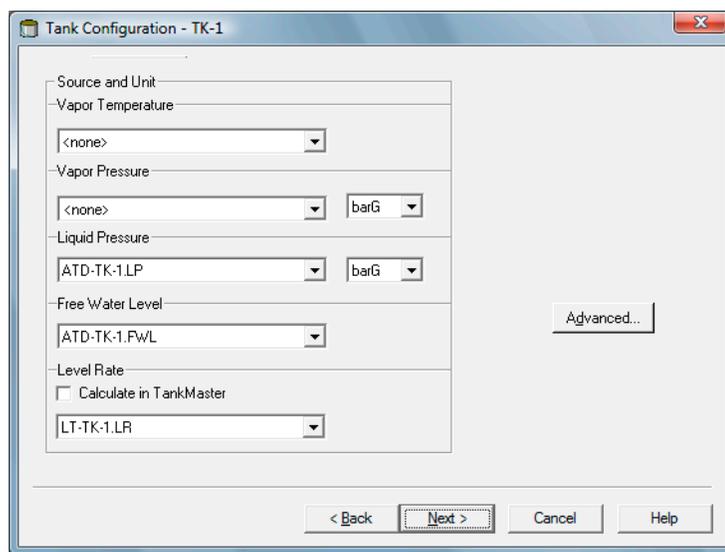
**Note**

It is recommended that devices are installed prior to installing tanks.



7. Click the **Next** button to proceed with tank configuration.

The **Tank Configuration** window lets you enable tank measurement variables such as **Vapor Temperature**, **Vapor Pressure**, **Liquid Pressure**, and **Free Water Level (FWL)** for calculating **Observed Density** and other inventory parameters.



The **Calculate in TankMaster** check box may be used for devices without internal calculation of **Level Rate**. By selecting this check box the Level Rate is calculated by the TankMaster program

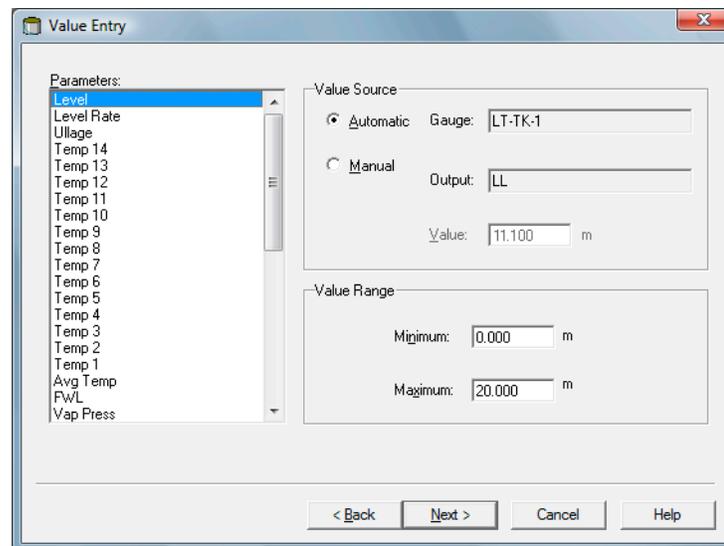
**Liquid Pressure** and **Vapor Pressure** are not automatically mapped to measurement instruments. These tank measurement variables have to be mapped to an instrument in the **Advanced Parameter Source Configuration** window in order to make them available in the **Tank Configuration** window.

The **Advanced** button opens the **Advanced Tank Setup** window which allows you to change mapping of tank measurement variables to gauge output. This option can be used, for example, to map the relay outputs of a Rosemount 2410 Tank Hub to relay status presentation in the TankMaster WinOpi program.

#### Note

Advanced configuration should only be used when there is no appropriate option available in the standard **Tank Configuration** window.

8. Click the **Next** button to open the **Value Entry** window which lets you:
  - Choose whether to use automatic measurement values from available measurement instruments, or manual values.
  - For desired parameters, for example **Level** and **Free Water Level**, specify parameter **Value Range** to be used in various windows for presentation of measurement data.



Some parameters, such as **Free Water Level**, **Liquid Pressure**, and **Vapor Pressure**, are set to **Value Source=Manual** by default. Therefore, for those instruments you need to configure automatic measurements if required.

The **Value Entry** window allows you to disable automatic measurements for selected parameters in case you need to remove an instrument for service purposes.

To use manual values do the following:

- a) Select a measurement variable in the **Parameters** list on the left-hand side of the **Value Entry** window.
- b) Set **Value Source** to **Manual**.
- c) Type the desired value in the **Value** entry field.

Manual values are marked yellow in order to distinguish them from automatic values.

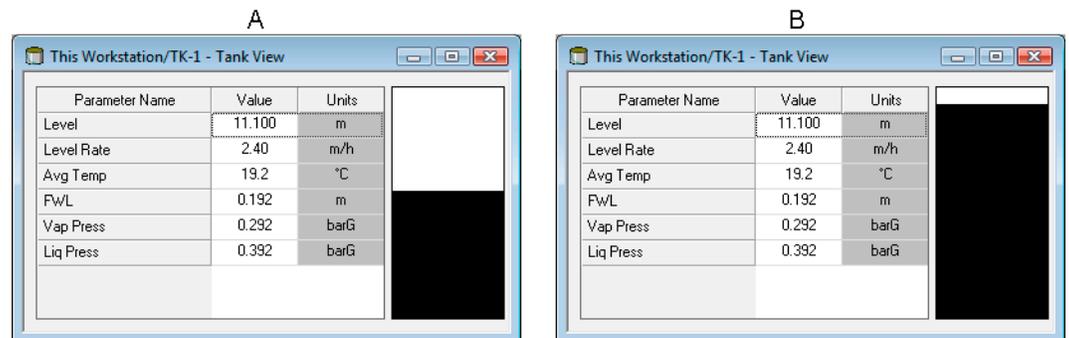
9. Specify **Value Range** if needed.

The **Value Range** parameters (**Minimum** and **Maximum**) allow you to scale bar graphs in the **Tank View** window and other windows (in WinSetup as well as WinOpi) where bar graphs are used to display product levels.

For example, the **Value Range** Maximum value for Level is normally set equal to the Tank Reference Height (R), or the maximum level in the strapping table, to obtain correct scaling of the level bar graphs.

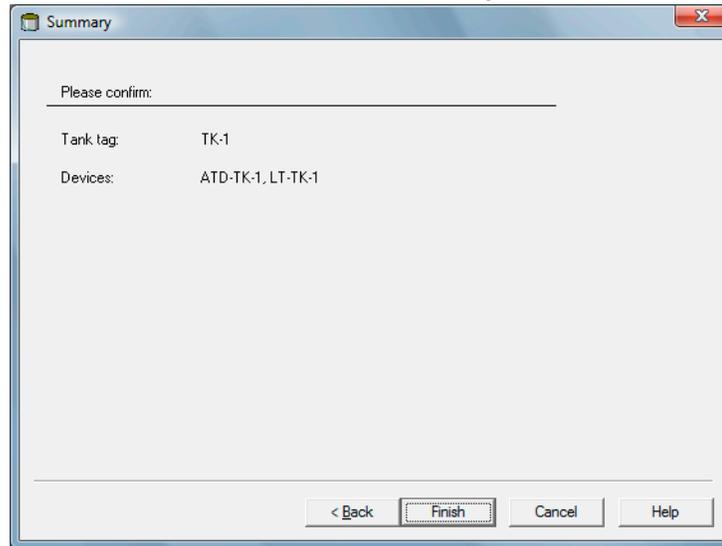
**Example**

**Figure 3-2: Tank View with Various Value Range Settings**



- A. Value range: Min=0, Max= 20 m
- B. Value range: Min=0, Max= 12 m

10. Click the **Next** button to open the **Summary** window.



The **Summary** window presents information about the current tank installation. When you click the **Finish** button, the tank installation will be completed and the tank appears in the WinSetup Workspace.

You can choose not to finish the installation by clicking the **Cancel** button. Note that if a device was installed as part of the tank installation process, the device remains installed and appears in the Workspace although the tank installation was not completed.

### Related information

- [Installation procedure](#)
- [Advanced parameter source configuration](#)
- [Setting the name tag prefixes](#)
- [Show slave positions \(advanced\)](#)
- [Installing a Rosemount 2410 Tank Hub](#)

## Advanced parameter source configuration

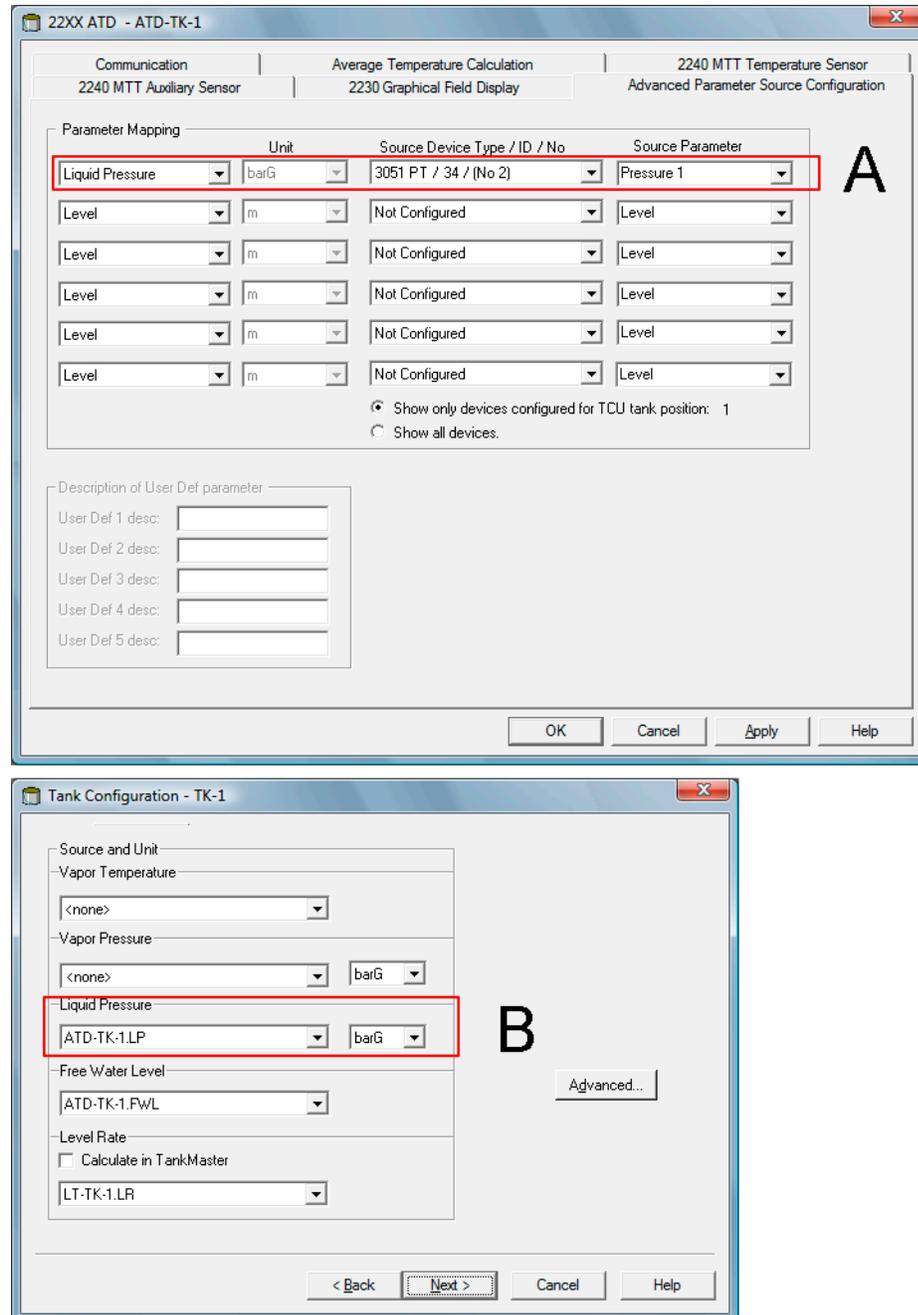
Parameters which are not automatically mapped to measurement instruments can be mapped to an instrument in the **22XX ATD/Advanced Parameter Source Configuration** window.

### Procedure

1. In the TankMaster WinSetup workspace, click the right mouse button on the ATD device icon and select the Properties option.
2. Select the **Advanced Parameter Source Configuration** tab.
3. Map the appropriate tank measurement variable to the output of a transmitter on the Tankbus. A measurement instrument which is mapped in the **22XX ATD/Advanced Parameter Source Configuration** window can be selected in the **Tank Configuration** window as illustrated in [Figure 3-3](#).

## Advanced parameter source configuration example

Figure 3-3: Example of Advanced Parameter Source Configuration



- A. *Liquid Pressure* is mapped to a source device. In the example the source device is 3051 PT/34/(No.2).
- B. In the *Tank Configuration* window, *Liquid Pressure* is mapped to the appropriate tank parameter.

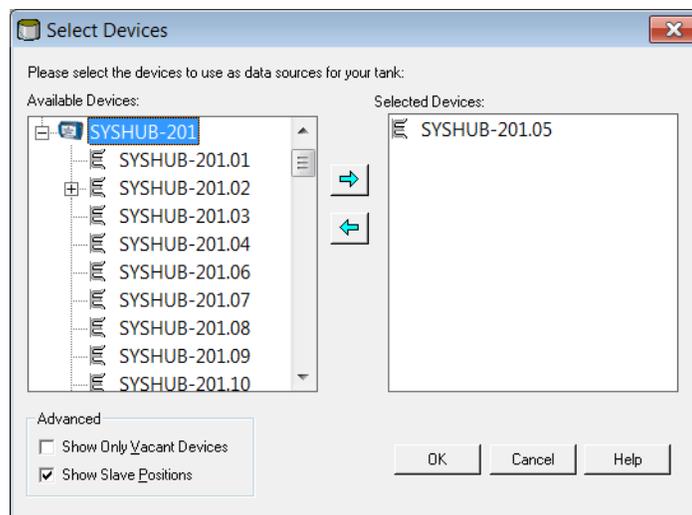
## Show slave positions (advanced)

The **Show Slave Positions** check box should only be used for advanced tank configuration of devices which are not supported by the Rosemount Tank Gauging system.

A device which is connected to the Tankbus and configured in the Rosemount 2460 System Hub's tank database, will appear in the **Available Devices** pane at the left-hand side of the **Select Devices** window. In case a device which can not be identified by the Rosemount Tank Gauging system is connected to the Tankbus, you will have to select the **Show Slave Positions** check box in order to map this device to a tank.

### Procedure

1. In the **Select Devices** window, select the **Show Slave Positions** check box to display the tank database positions.
2. In the **Select Devices** window select the slave database position that corresponds to the tank where the device is installed. In this example the devices are mapped to position 5 which is identified as SYSHUB-201.05 in the tank database.
3. Move the selected item to the **Selected Devices** pane by clicking the right arrow button.



4. Verify that the device is properly mapped to the system hub's tank database.

2460 Tank	Source	Field Port	2410 Device Address	2410 Tank Pos	Level Device Address	Temp Device Address	Number of Temp Elements	Auxiliary Inputs								Relays	
								VP	MP	LP	FWL	UIn1	UIn2	UIn3	UIn4		UIn5
1	2410	1	101	1	1	101	6	-	-	-	-	-	-	-	-	-	-
2	2410	1	102	1	2	102	8	-	-	-	-	-	-	-	-	-	-
3	(none)																
4	(none)																
5	2410	1	1	1			0	VP	-	LP	FWL	FWL	UIn 2	VP	LP	UIn 1	-
6	(none)																
7	(none)																
8	(none)																

## Advanced tank setup

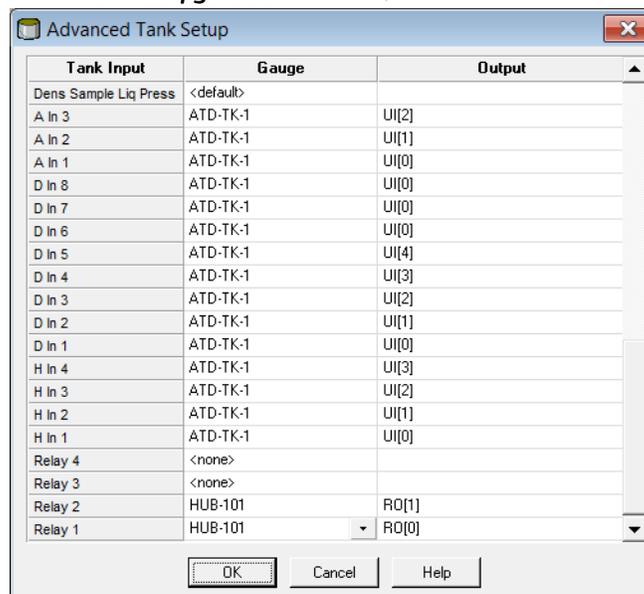
The *Advanced Tank Setup* window allows you to change mapping of tank measurement variables to gauge output. This option can be used, for example, to map the relay outputs of a Rosemount 2410 Tank Hub to relay status presentation in the TankMaster WinOpi program.

### Note

Advanced setup should only be used when there is no appropriate option available in the standard *Tank Configuration* window.

### Procedure

1. in the *Tank Configuration* window, select the **Advanced** button.



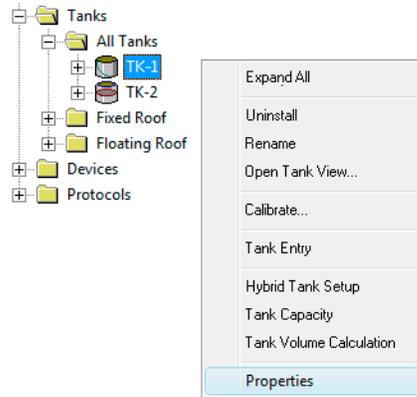
2. For each tank input variable you can change output as well as gauge. Simply put the mouse pointer in the Gauge or Output field of the desired Tank Input variable (Level, Level rate, etc.) and select the desired option from the drop-down list.
3. Click the **OK** button to save the configuration and close the *Advanced Tank Setup* window.

### 3.1.3 To change tank configuration

When a tank is installed and configured the current settings can be modified at any time by opening the corresponding **Properties** dialog.

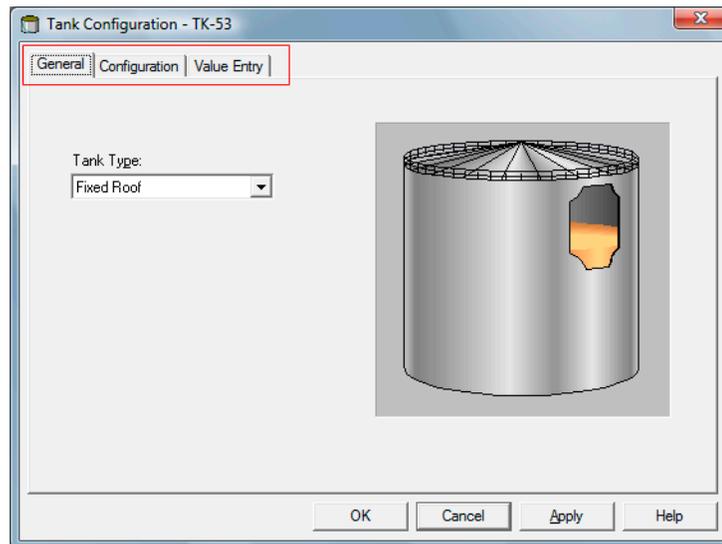
#### Procedure

1. Start the TankMaster WinSetup program.
2. In the Workspace window select the desired tank.



3. Click the right mouse button and select the **Properties** option.
4. In the **Properties** window, select the desired tab, and change the current tank settings.

Basically each tab corresponds to a step in the installation wizard.

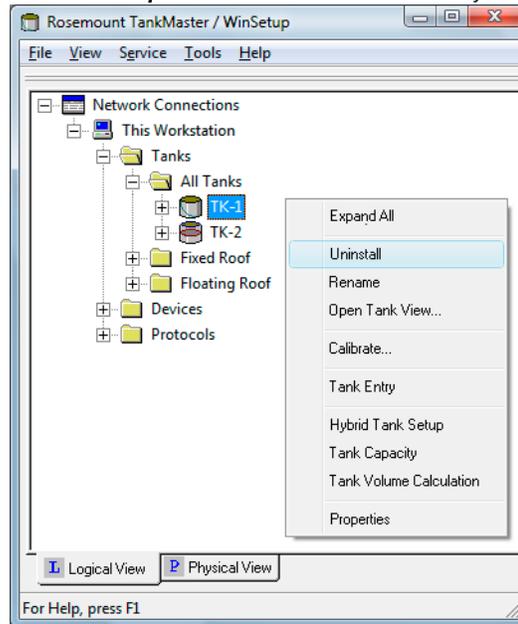


5. Click the **Apply** button to store the configuration before advancing to another tab.
6. Click **OK** to finish configuration and close the window.

## 3.1.4 To uninstall a tank

### Procedure

1. In the **Workspace** window select the tank you want to remove.



2. Click the right mouse button and select the **Uninstall** option from the pop-up menu.

### Related information

[To uninstall a tank and associated devices](#)

## 3.2 Adding a tank

New tanks can be added to an existing Rosemount Tank Gauging system. The procedure will be slightly different depending on the specific system configuration. Basically two scenarios may be identified:

- Add a new tank and a Rosemount 2410 Tank Hub with all field devices that will be installed on the tank.
- Add a new tank to an existing Rosemount 2410. This is typically a case with a tank hub that serves multiple tanks<sup>(6)</sup>.

### 3.2.1 Adding a new tank and a new Rosemount 2410 Tank Hub

This section describes how to add a new tank and new field devices to a Rosemount Tank Gauging system.

#### Summary

This is a brief summary of how to install a new tank and a new Rosemount 2410 Tank Hub in a Rosemount Tank Gauging system that includes a Rosemount 2460 System Hub and various field devices.

#### Procedure

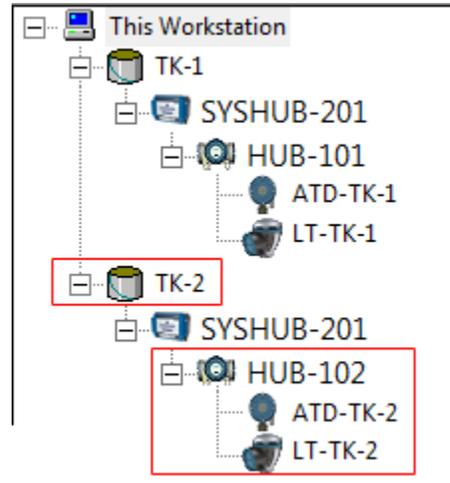
1. Configure the communication settings of the Rosemount 2460 System Hub.
2. Update the system hub's tank database by adding the field devices to be associated with the new tank.
3. Install the new Rosemount 2410 Tank Hub and configure the tank database by mapping field devices to the new tank.
4. Configure the field devices which have been added to the tank hub's database (Rosemount 5900S, Rosemount 2240S, Rosemount 3051S etc.).

---

(6) This requires Rosemount 2410 model code option M.

5. Configure the new tank.

**Figure 3-4: New Tank and new Tank Hub Added to the System**

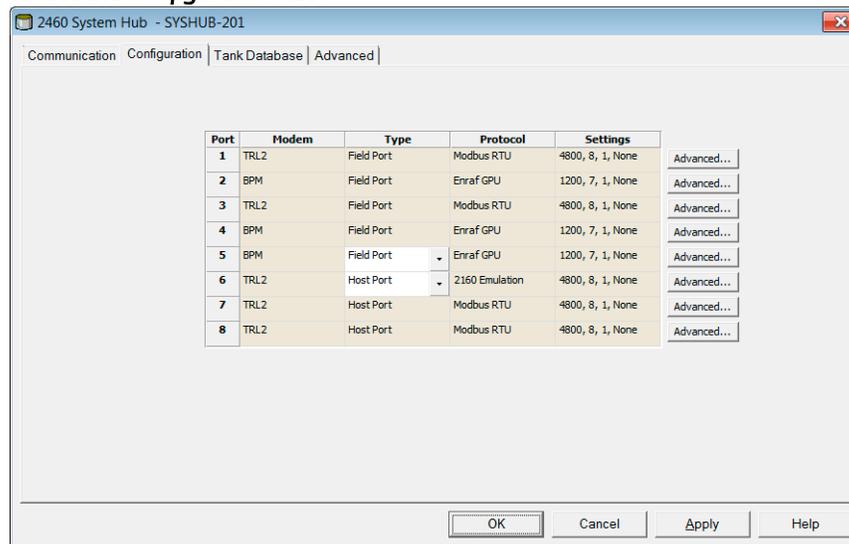


## Installation procedure

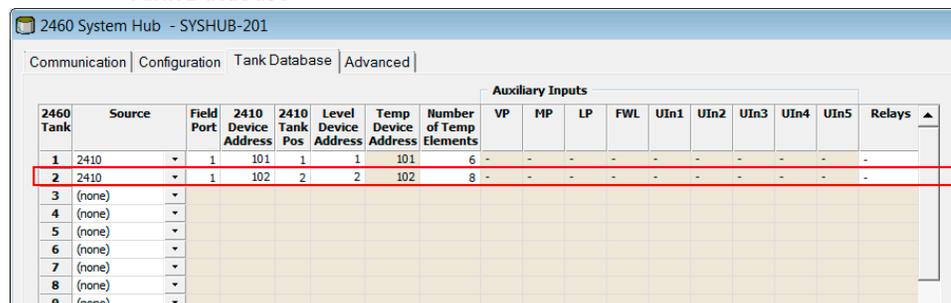
This is a detailed description of how to add a new tank and new field devices to a Rosemount Tank Gauging system.

### Procedure

1. Start the TankMaster WinSetup program.
2. In the WinSetup workspace, select the Rosemount 2460 System Hub icon.
3. Click the right mouse button and select **Properties**.
4. Select the **Configuration** tab.



5. In case the tank hub is connected to an unused field bus port, ensure that the port is properly configured for the tank hub's Primary Bus. For example, you may have to change protocol and baud rate depending on the type of communication bus that is used; RS-485 or TRL2.
6. Click the **Apply** button to save the configuration.
7. Select the **Tank Database** tab.

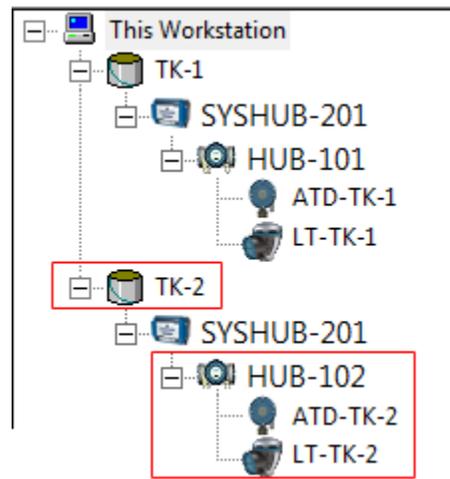


8. Configure the system hub's tank database with Modbus® addresses for the new Rosemount 2410 Tank Hub, level gauge, and temperature device (ATD<sup>(7)</sup>).

(7) Auxiliary Tank Device (ATD) is used to designate various devices such as temperature and pressure transmitters, displays and other non-level devices.

9. Install and configure a Rosemount 2410 Tank Hub and the field devices connected to the Tankbus.
10. Install a tank and associate the new tank hub to the tank.

**Figure 3-5: New Tank and Tank Hub**



**Related information**

- [Installing a Rosemount 2460 System Hub](#)
- [Installing a Rosemount 2410 Tank Hub](#)
- [Installing a tank](#)

## 3.2.2 Adding a new tank to an existing Rosemount 2410 Tank Hub

This section describes how to add a new tank to a Rosemount Tank Gauging system that includes a Rosemount 2460 System Hub, a Rosemount 2410 Tank Hub, and various field devices.

### Summary

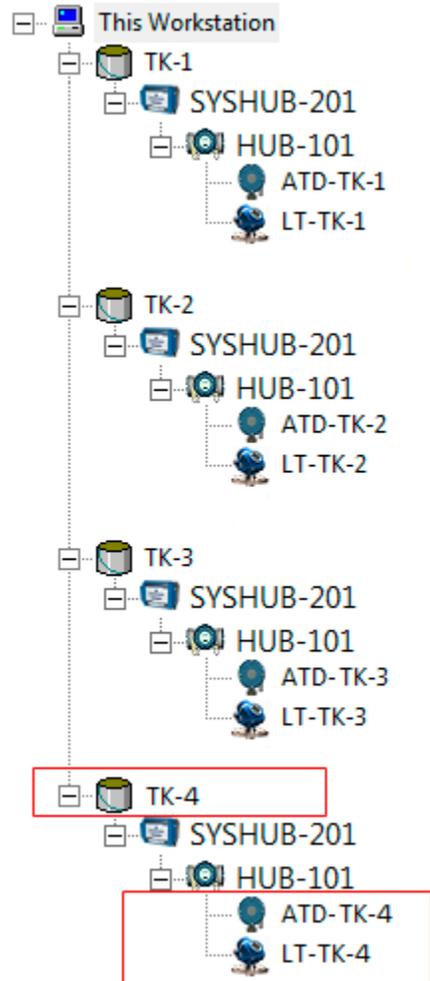
This is a brief summary of how to install a new tank in a Rosemount Tank Gauging system by adding the tank to an existing Rosemount 2410 Tank Hub.

### Procedure

1. Update the Rosemount 2460 System Hub's tank database by adding the field devices installed on the new tank.
2. Update the existing Rosemount 2410 Tank Hub's tank database by mapping the new field devices to the new tank.
3. Configure the field devices added to the tank hub's database.

4. Configure the new tank.

**Figure 3-6: A New Tank is Added to an Existing 2410 Tank Hub**



## Installation procedure

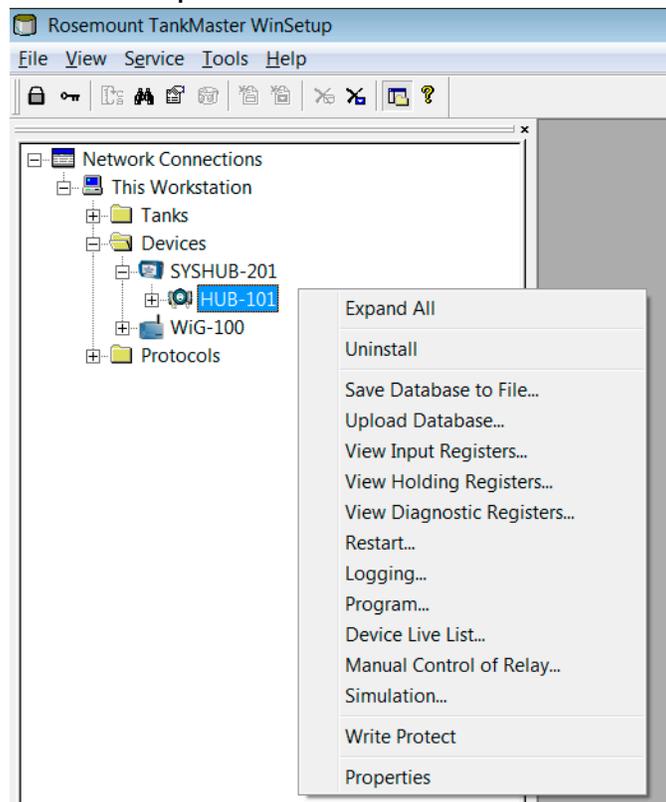
This is a detailed description of how to install a new tank in a Rosemount Tank Gauging system by adding the tank to an existing Rosemount 2410 Tank Hub.

### Procedure

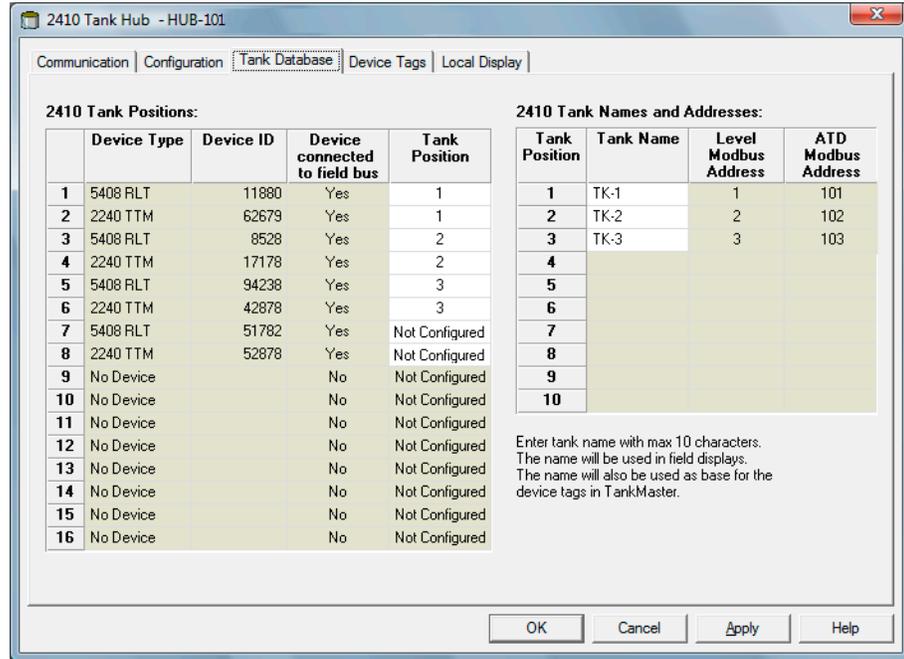
1. Start the TankMaster WinSetup program.
2. In the WinSetup workspace, select the Rosemount 2460 System Hub icon.
3. Click the right mouse button and select **Properties**, or from the **Service** menu select **Devices** → **Properties**.
4. Select the **Tank Database** tab.

2460 Tank	Source	Field Port	2410 Device Address	2410 Tank Pos	Level Device Address	Temp Device Address	Number of Temp Elements	Auxiliary Inputs							Relays		
								VP	MP	LP	FWL	UIn1	UIn2	UIn3		UIn4	UIn5
1	2410	1	101	1	1	101	8	-	-	-	-	-	-	-	-	-	-
2	2410	1	101	2	2	102	8	-	-	-	-	-	-	-	-	-	-
3	2410	1	101	3	3	103	8	-	-	-	-	-	-	-	-	-	-
4	2410	1	101	4	4	104	8	-	-	-	-	-	-	-	-	-	-

5. Configure the Tank Database with Modbus® addresses of the new level gauge and ATD devices.
6. In the WinSetup Workspace, select the Rosemount 2410 Tank Hub icon.
7. Click the right mouse button and select **Properties**, or from the **Service** menu select **Devices** → **Properties**.

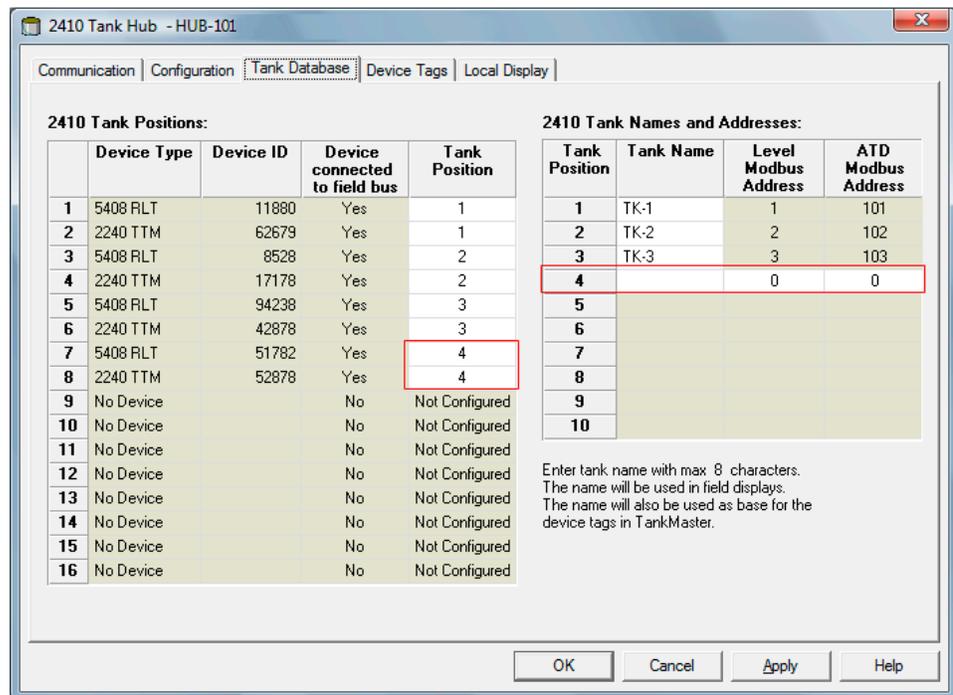
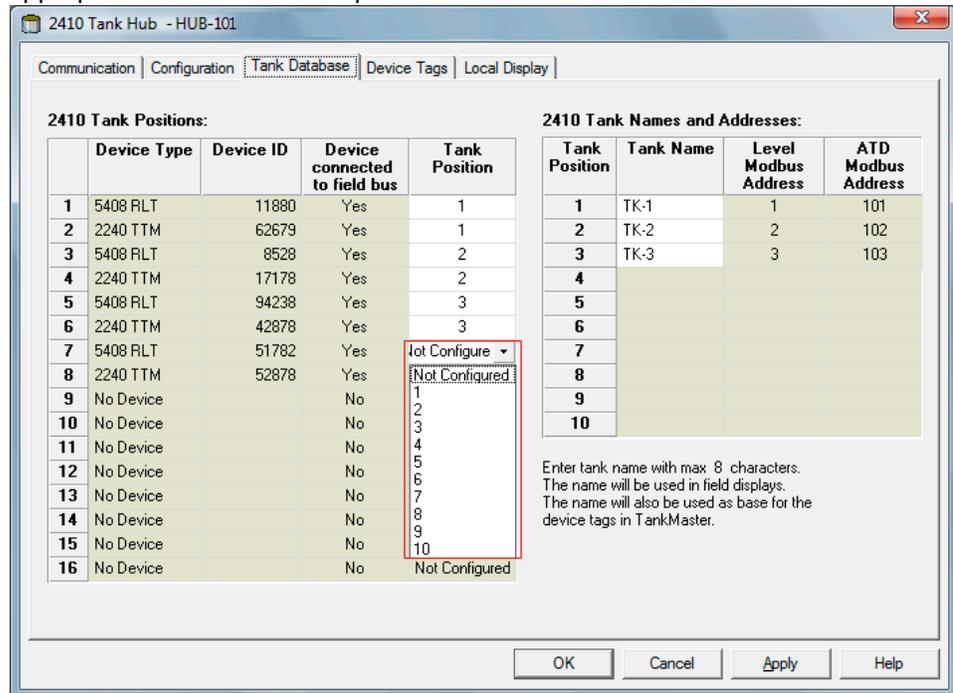


8. Select the *Tank Database* tab.

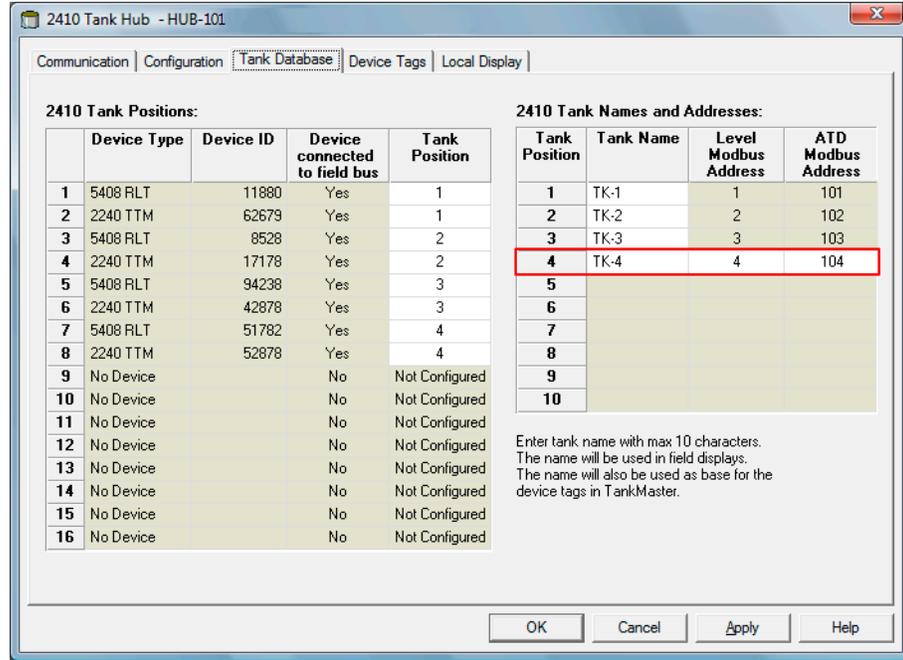


9. Verify that the new devices connected to the Tankbus appear in the **Device Type** column. Devices that appear in the list are properly communicating on the Tankbus. Devices supported by the Rosemount Tank Gauging system will automatically be identified by the Rosemount 2410.
10. Verify that the new devices are marked **Not Configured** in the **Tank Position** column.

11. In the **Tank Position** column, map the new devices to a tank by selecting the appropriate number in the drop-down list.



- Verify that a new tank position appears in the right-hand pane of the Tank Database window. In the example above, the new devices are mapped to tank position 4, and a tank position was added to the list of tanks in order to allow configuration of tank name and Modbus addresses for the new devices.



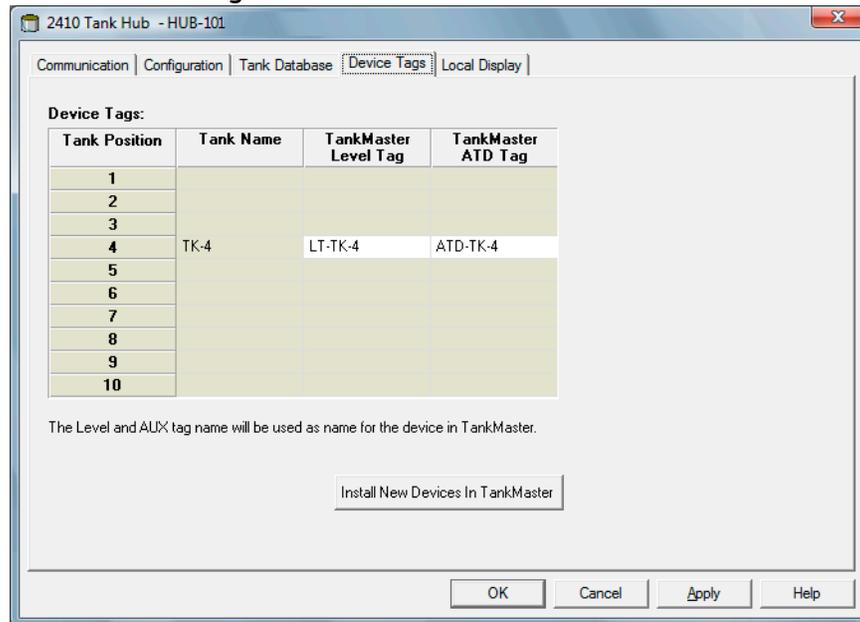
- Type a name in the Tank Name field. This tank name should also be used at a later stage when installing the tank to be associated with the current tank hub.
- The **Level Modbus Address** field is enabled for the new level gauge. Specify a Modbus address of your own choice. Note that it must be the same Modbus address as configured in the system hub's tank database for this level gauge.
- In case an Auxiliary Tank Device (ATD) such as a Rosemount 2240S Multi-input Temperature Transmitter is installed, the **ATD Modbus Address** field is enabled as well.

Specify a Modbus address of your own choice. Note that it must be the same Modbus address as configured in the system hub's tank database.

For tank position 1, the ATD Modbus address is automatically configured as the Modbus address of the Rosemount 2410 Tank Hub itself. All the non-level devices on a tank are represented by a single ATD device in the Rosemount Tank Gauging system.

- Click the **Apply** button to store the tank database configuration.

17. Select the *Device Tags* tab.



18. Verify that the TankMaster Level Tag is correct or enter a new one. 18. Verify that the TankMaster ATD Tag is correct or enter a new one. In case there are no ATD device associated with the tank, the ATD tag field will be disabled.
19. Click the **Install New Devices in TankMaster** button to automatically install the devices in the TankMaster Workspace. This is the recommended way of installing field devices in TankMaster, but you may install the devices at a later stage by using the device installation wizard.
20. Click the **OK** button to store the configuration and close the configuration window.
21. The devices will now be available in the TankMaster workspace, and each device has to be configured via its *Properties* window.
22. Proceed with installing the tank.
- Now the new tank and field devices are installed and configured and will appear in the TankMaster workspace.

**Related information**

- [Installing a tank](#)
- [Device installation](#)
- [Installing a Rosemount 2460 System Hub](#)
- [Installing a Rosemount 2410 Tank Hub](#)

## 3.3 Calibrating the level gauge

Normally a minor level gauge adjustment is needed in order to accurately match measured and actual product levels. For example, a deviation may result from minor errors in tank geometry parameters such as the tank height (R) or the position of the Gauge Reference Point.

The Rosemount 5900 level gauge can be manually calibrated by adjusting the **Calibration Distance** parameter. For Rosemount 5900 gauges in Still-pipe applications you may use the **Calibrate** function to let WinSetup automatically calculate an optimized **Correction Factor** and **Calibration Distance** based on measurement data and hand dipping at different product levels.

### Related information

[Rosemount 5900S Reference Manual](#)

### 3.3.1 Manual adjustment of Calibration Distance

This is a description of how to manually adjust the **Calibration Distance** parameter.

A Rosemount 5900 level gauge can be calibrated manually by adjusting the **Calibration Distance**<sup>(8)</sup> parameter. the **Calibration Distance** can be calculated by comparing hand dipped level values with product levels measured by the gauge according to the formula:

**New Calibration Distance**=**Old Calibration Distance**+ $\Delta L$ ,

where  $\Delta L$ =observed level (hand dip) - gauge level reading.

### Procedure

1. In the WinSetup workspace, select the desired level gauge icon.
2. Click the right mouse-button and select **Properties**.
3. Select the **Geometry** tab.
4. Type the **Calibration Distance** value in the corresponding input field and click the **OK** button.

### Related information

[Rosemount 5900S Reference Manual](#)

[Installing a Rosemount 5900 Radar Level Gauge](#)

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(8) For non-standard antennas the Tank Connection Length (TCL) may need to be adjusted as well.

### 3.3.2 Using the Calibrate function

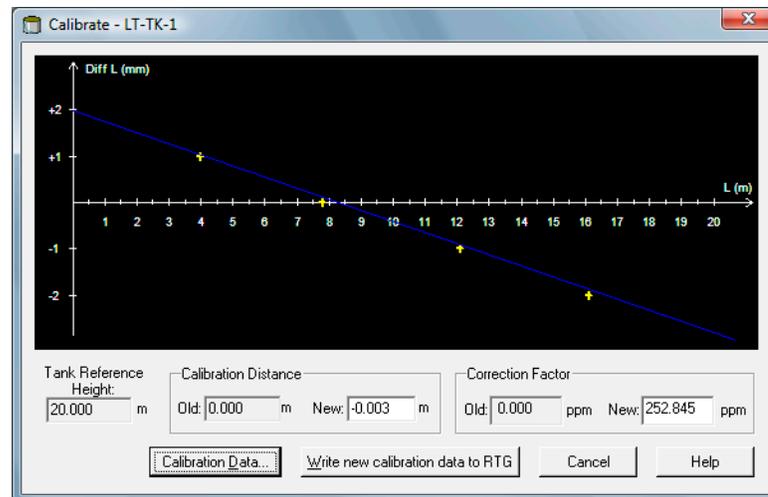
The **Calibrate** tool allows you to calculate the **Correction Factor** and **Calibration Distance** for still-pipe measurements. It optimizes measurement performance from the top to the bottom of the tank by automatically minimizing the offset between actual product levels and level values measured by the gauge.

This is a brief description of how to use the Calibrate function. See the [Rosemount 5900S Reference Manual](#) for further information.

#### Procedure

1. Select the Rosemount 5900 icon in the Workspace window.
2. Click the right mouse button and select **Calibrate**, or from the **Service** menu, select **Devices** → **Calibrate**.

The **Calibrate** window displays a straight line fitted through measurement points that represent the difference between hand dipped level values and values measured by the level gauge. For still-pipe antennas a sloping line is displayed, otherwise the line is horizontal.



3. Click the **Calibration Data** button to open the **Calibration Data** window. Enter hand dipped level values and the corresponding levels measured by the gauge.
4. Once finished, click the **Save Calibration Data in PC Database** button and return to the **Calibrate** window.
5. Click the **Write new calibration data to RTG** button to store the current calibration data in the level gauge internal memory.  
A new **Calibration Distance** will be calculated and the level values measured by the gauge are recalculated.

#### Related information

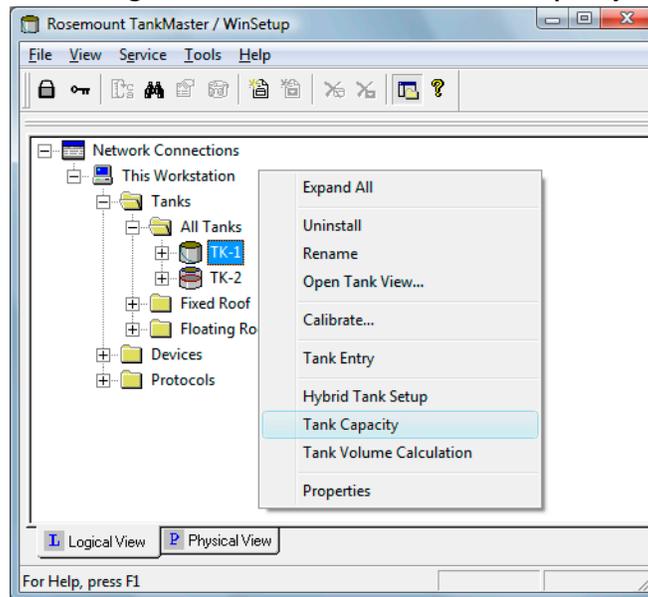
[Rosemount 5900S Reference Manual](#)  
[Installing a Rosemount 5900 Radar Level Gauge](#)

## 3.4 Setting up a Tank Capacity Table

The tank geometry can be specified in the **Tank Capacity Table (TCT)**. The TCT maps product level to the corresponding volume. Several TCT types are available: Raw; International, and Northern.

### Procedure

1. Start the TankMaster WinSetup program.
2. In the WinSetup workspace window select the desired tank icon.
3. Click the right mouse button and select **Tank Capacity**.



4. Select desired TCT type and enter level and volume data.  
See the Rosemount TankMaster WinOpi [Reference Manual](#) for further information.

Tank Capacity Setup - "TK-TRL2\_2460"

**TCT Table**  
Type: Raw Points: 3 Change...  
Table:  

Point	Level	Volume
1	0.000	0.000
2	10.000	10000.000
3	20.000	25000.000

**Units**  
Level: m  
Volume: m3  
Temp: deg C

**Volume**  
Tank: 100000.000 m3  
Max: 25000.000 m3  
Min: 0.000 m3  
Sump: 0.000 m3

**Shell**  
Insulated: No  
Steel Exp: 0.0000112 /"  
2\* Steel Exp: 0.0000224 /"  
Base Temp: 20.0 °C

**Floating Roof**  
Roof Setup...

OK Cancel Apply Help

5. Click OK to save the configuration.

### Related information

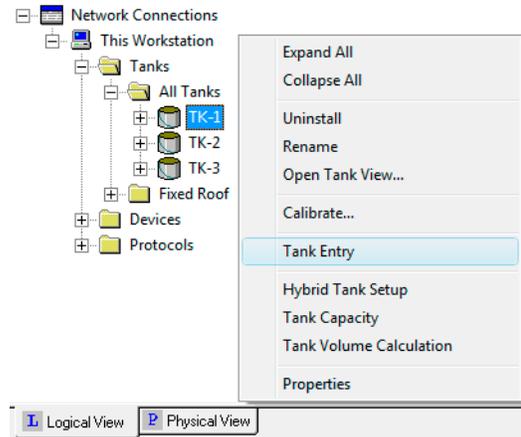
[Rosemount TankMaster WinOpi Reference Manual](#)

## 3.5 Tank Entry

The **Tank Entry** window lets you specify a number of product parameters for inventory calculations. TankMaster can use measured data, or data that is manually entered.

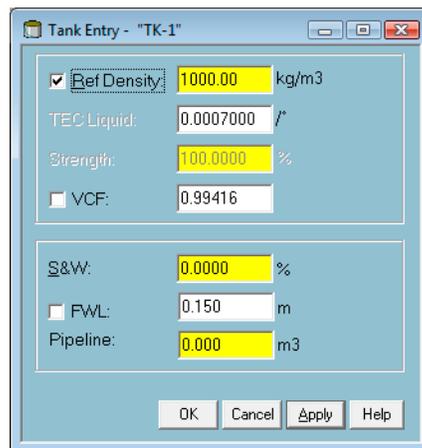
### Procedure

1. In the WinSetup workspace window select the desired tank icon.
2. Click the right mouse button and select **Tank Entry**.



3. To enter manual values, select the corresponding check box and type the desired value in the input field.

Manual values are marked yellow.



4. Click **OK** to save the configuration.

### Related information

[Rosemount TankMaster WinOpi Reference Manual](#)

## 3.6 Setting up a hybrid system

This is a description of how to install a Rosemount Tank Gauging system for on-line density measurements and mass calculations.

### Prerequisites

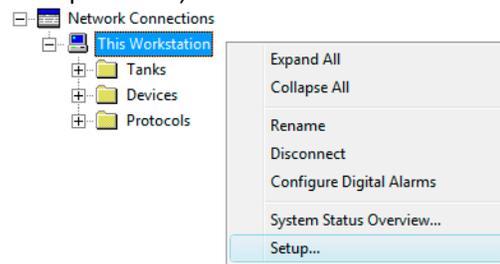
Before starting the setup make sure the 2460 System Hub's tank database is configured accordingly.

For mass calculations to work properly, a tank strapping table (also referred to as a Tank Capacity Table) must be entered.

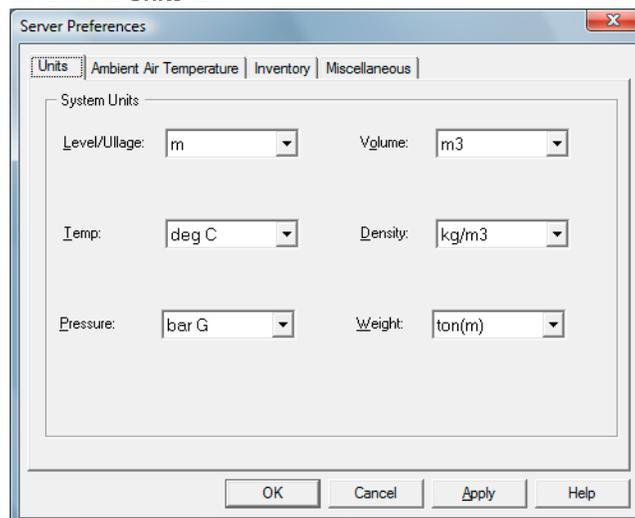
A Rosemount Tank Gauging hybrid system typically includes two pressure sensors, P1 and P3, and a Rosemount 5900S Radar Level Gauge. In case there is always atmospheric pressure in the tank, the P3 sensor may be excluded.

### Procedure

1. Start the TankMaster WinSetup program.
2. In the Workspace window select the tank server icon (This Workstation in the example below).

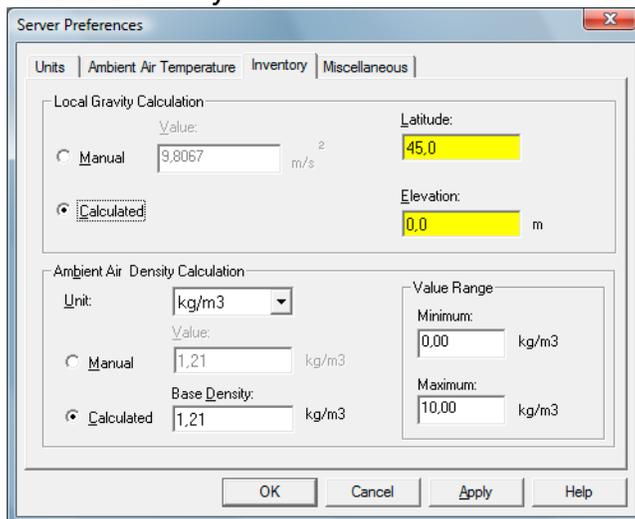


3. Click the right mouse button and select **Setup**, or select menu option **Service** → **Servers** → **Setup** to open the *Server Preferences* window.
4. Select the *Units* tab.



5. Select the desired measurement units for **Density** and **Pressure**.

6. Select the **Inventory** tab.



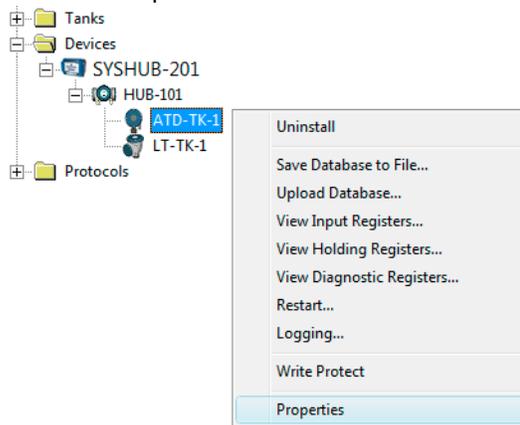
7. For Local Gravity select calculation method **Manual** or **Calculated**. The Local Gravity is used as input for calculating the Observed Density.

Manual: enter a local gravity value in the “Value” field.

Calculated: enter the latitude and elevation of the site where the tank is located.

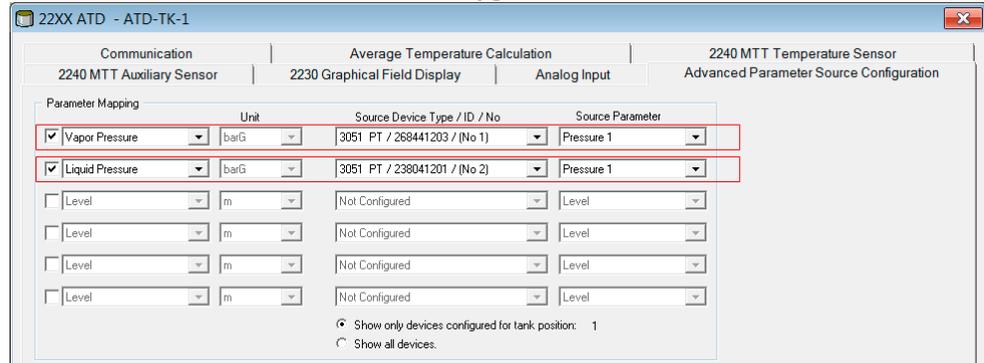
8. Click the **OK** button to store the configuration and close the window.

9. In the Workspace window select the ATD device icon:



10. Click the right mouse button and select **Properties**, or from the **Service** menu select **Devices** → **Properties** to open the **22XX ATD** window.

11. Select the **Advanced Parameter Source Configuration** tab.

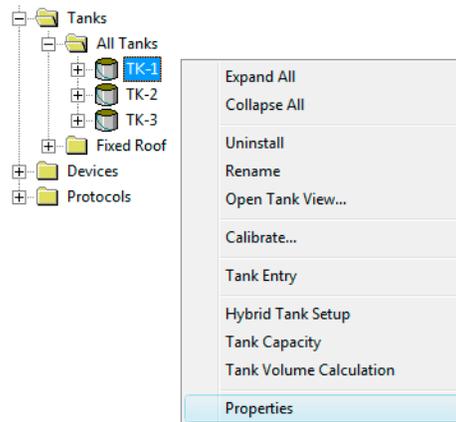


12. Verify that **Vapor Pressure** and **Liquid Pressure** are mapped to the correct pressure sensors (Source Device).

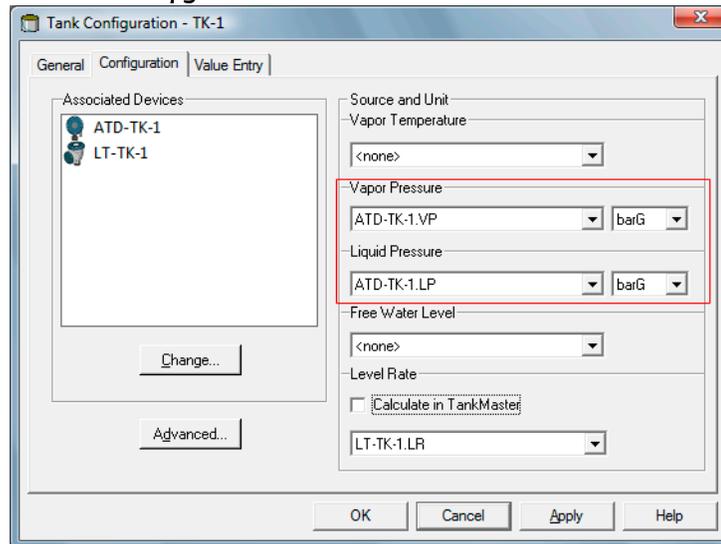
13. Click the **OK** button to store the configuration and close the window.

14. Open the **Tank Configuration** window:

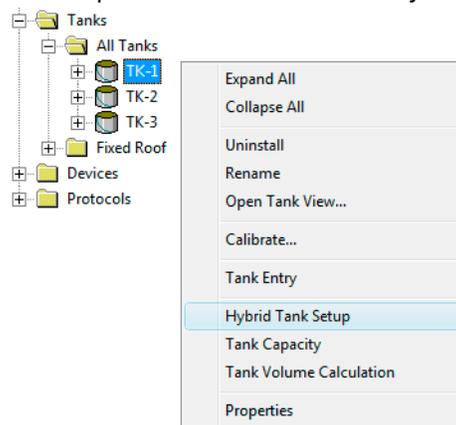
- a) In WinSetup select the desired tank icon in the workspace window
- b) Click the right mouse button and select **Properties**, or select menu option **Service → Tanks → Properties**.



15. Select the **Configuration** tab.

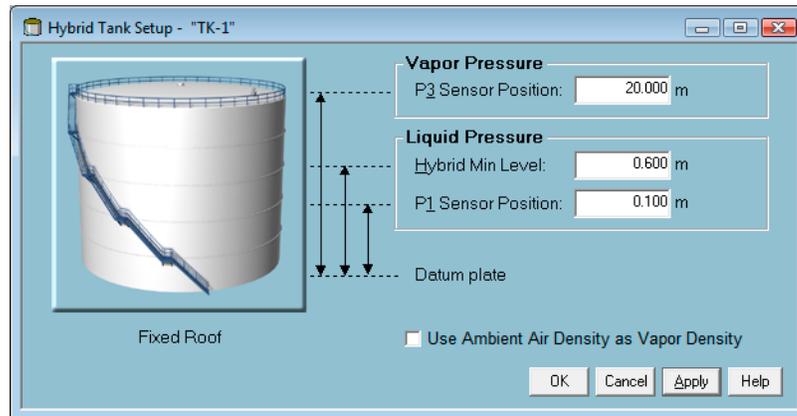


16. Select source parameter and measurement unit for **Vapor Pressure** and **Liquid Pressure**.
17. Verify measurements by opening the **Tank View** window (**Service** → **Tanks** → **Open Tank View**).
18. Configure the **Liquid Pressure** and **Vapor Pressure** sensors. In the WinSetup workspace window right-click the tank icon and select **Hybrid Tank Setup**, or select menu option **Service** → **Tanks** → **Hybrid Tank Setup**.



19. Configure P1 Sensor Position and P3 Sensor Position.

- **P1 Sensor Position** is the center position of the sensor membrane for the **Liquid Pressure** transmitter
- **P3 Sensor Position** is the center position of the sensor membrane for the **Vapor Pressure** transmitter



20. Enter the **Hybrid Min Level**.

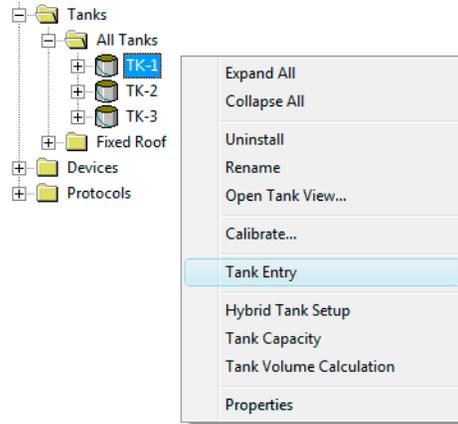
This value specifies the lowest product level at which TankMaster calculates the **Observed Density**. Normally, the accuracy of pressure sensors is poor at low pressures, i.e. at product levels close to the sensor membrane. Therefore, you can enter a limit below which the density calculation is "frozen". For example, if Hybrid Min Level is equal to 0.6 meter, TankMaster WinOpi will present the same density value for product levels below 0.6 meter.

**Note**

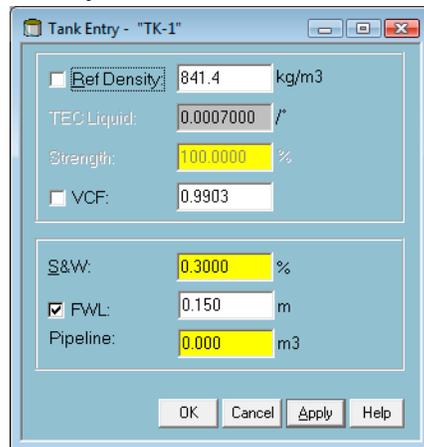
Specify the actual minimum product level and not the distance between the pressure sensor and the product surface.

21. Click the **Apply** button to save the Hybrid Tank Setup configuration, or the **OK** button to save and close the window.

22. In the WinSetup workspace window select the tank icon, click the right mouse button and select **Tank Entry**, or select menu option **Service** → **Tanks** → **Tank Entry**.

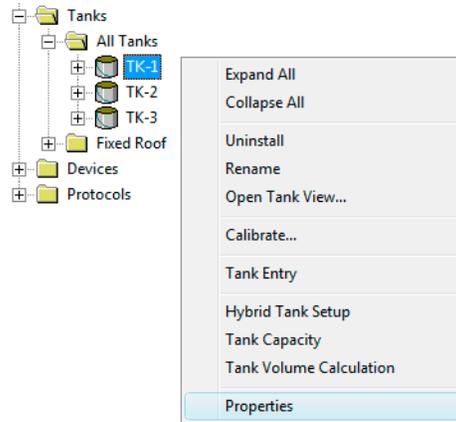


23. Ensure that **Reference Density** is measured automatically, i.e. the check box **Ref Density** is unmarked.

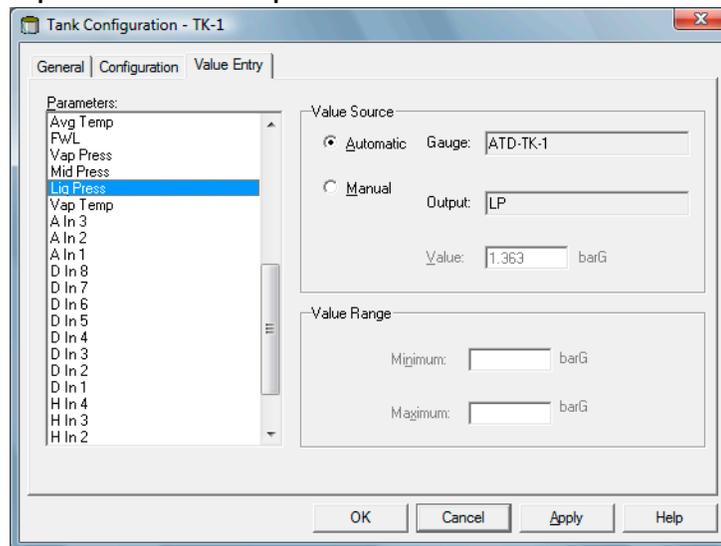


24. Click the **Apply** button to save the configuration, or click the **OK** button to save the configuration and close the window.

25. Open WinSetup. Click the right mouse button on the tank icon and select **Properties**, or select menu option **Service** → **Tanks** → **Properties**.



26. Select the **Value Entry** tab. Ensure that **Value Source** is set to **Automatic** for the **Liquid Pressure** and **Vapor Pressure** measurement variables.



27. Click the **OK** button to save the configuration and close the window.
28. Check the result in the **Tank Inventory** window:
- Start the TankMaster WinOpi program.
  - In the WinOpi workspace select the tank icon.
  - From the **View** menu, select **Tank** → **Tank Inventory**.

If the inventory calculations seem to be incorrect, see **Checklist for Inventory Parameter Setup** in the Rosemount TankMaster WinOpi [Reference Manual](#).

### Related information

[Advanced parameter source configuration](#)  
[Installing a Rosemount 2460 System Hub](#)  
[Setting up a Tank Capacity Table](#)



## 4 Device handling

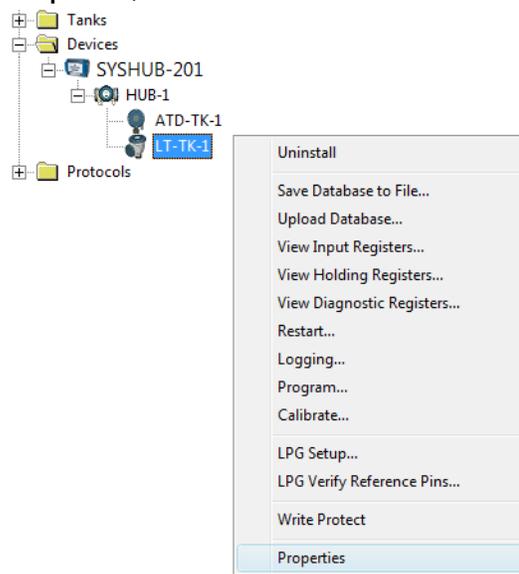
This section provides information on how to change configuration of installed devices.

### 4.1 To change device configuration

Once a device is installed and configured, you can modify the current settings at any time by in the *Properties* dialog.

#### Procedure

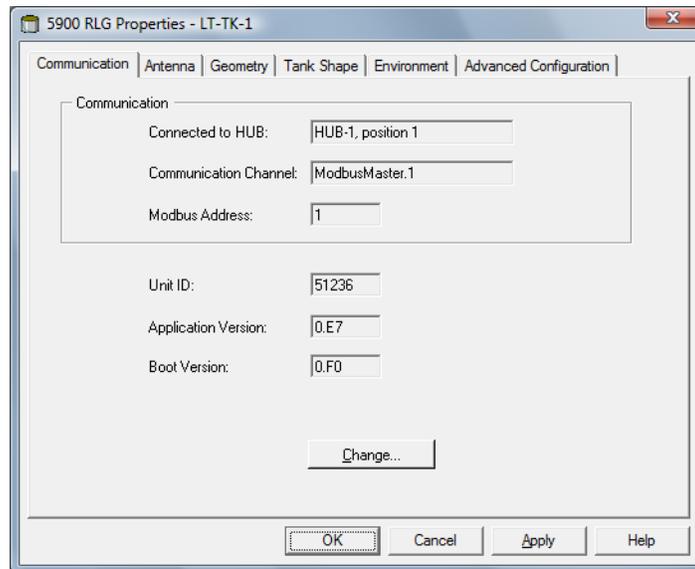
1. In the WinSetup *Workspace* window, open the **Devices** folder, navigate to the desired device, and select the device icon. Click the right mouse button and select **Properties**, or from the **Service** menu select **Devices** → **Properties**.



2. The device properties window (in this example the *5900S RLG Properties* window) appears with multiple tabs that allow you to change the current device settings.

Various tabs allow you to configure communication parameters, tank geometry, device specific parameters and advanced options.

Some tabs refer to steps in the device installation wizard. Similar dialogs are available for other device types as well, for example the Rosemount 2410 Tank Hub.



### Related information

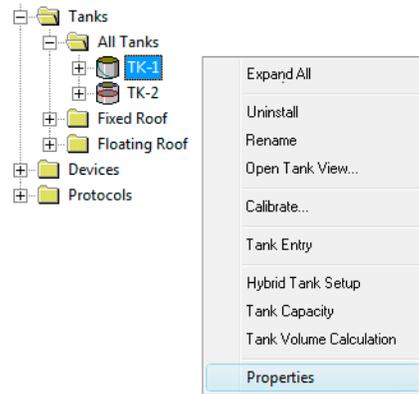
[Device installation](#)

## 4.2 To uninstall a device

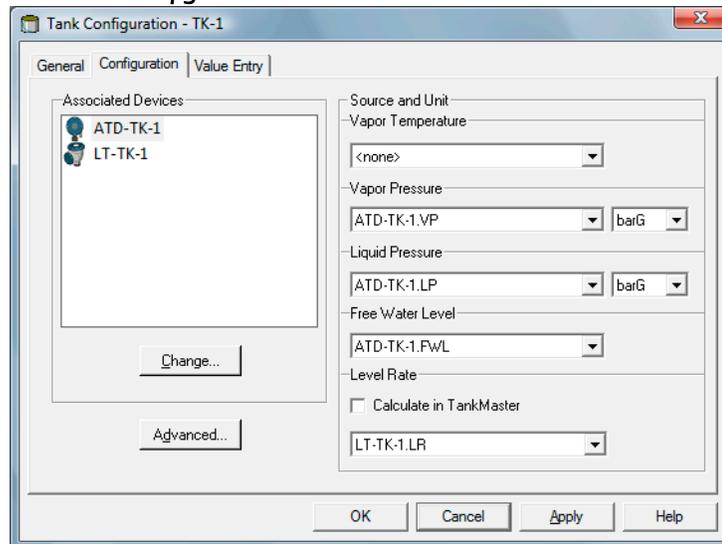
A device can be uninstalled from the WinSetup workspace at any time. However, prior to uninstalling the device it needs to be disconnected from the associated tank.

### Procedure

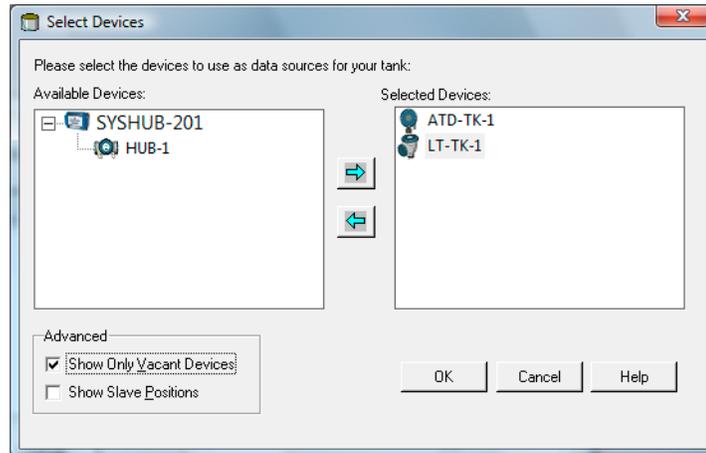
1. In the WinSetup workspace, select the desired tank.
2. Click the right mouse button and select **Properties**, or from the **Service** menu select **Devices** → **Properties**.



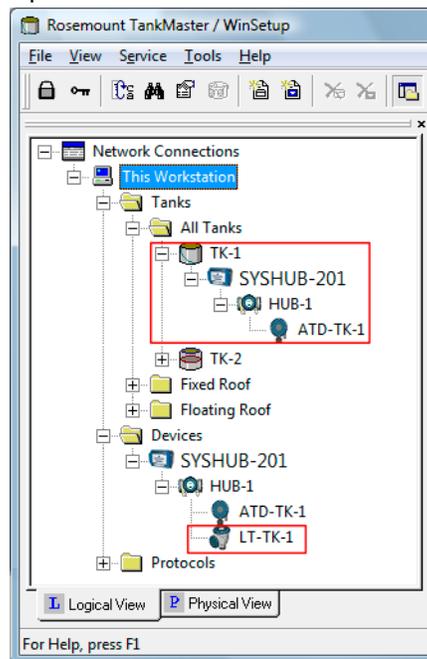
3. Select the **Configuration** tab.



4. Click the **Change** button.

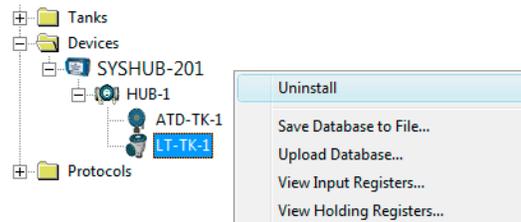


5. In the right-hand side of the **Select Devices** window, select the device (LT-TK-1 in this example) and click the left-arrow button. The device will be moved from the **Selected Devices** pane to the **Available Devices** pane.
6. Click the **OK** button.
7. Open the **Tanks and Devices** folders:



8. Verify that the device (LT-TK-1 in this case) is no longer associated with the tank but still available in the **Devices** folder.
9. Select the device and click the right mouse button.

### 10. Select Uninstall.



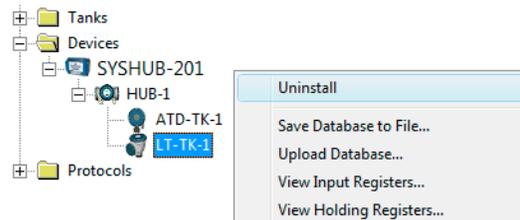
Now the device will be removed. However, the **tank** is still available in the WinSetup workspace.

## 4.3 To uninstall a tank and associated devices

In case you wish to uninstall a tank and its associated devices, you will have to start by uninstalling the tank and then proceed with uninstalling the devices.

### Procedure

1. Uninstall the tank.
2. Select the device and click the right mouse button.
3. Select **Uninstall**.



4. Repeat for each device you wish to remove.

### Related information

[To uninstall a tank](#)



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